

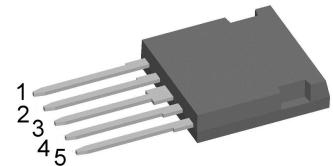
Thyristor

V_{RRM} = 2x 1600 V
 I_{TAV} = 50 A
 V_T = 1.23 V

Phase leg

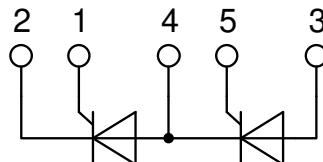
Part number

CMA50P1600FC



Backside: Isolated

 E72873



Features / Advantages:

- Thyristor for line frequency
- Planar passivated chip
- Long-term stability

Applications:

- Line rectifying 50/60 Hz
- Softstart AC motor control
- DC Motor control
- Power converter
- AC power control
- Lighting and temperature control

Package: i4-Pac

- Isolation Voltage: 3000 V~
- Industry convenient outline
- RoHS compliant
- Epoxy meets UL 94V-0
- Soldering pins for PCB mounting
- Backside: DCB ceramic
- Reduced weight
- Advanced power cycling

Disclaimer Notice

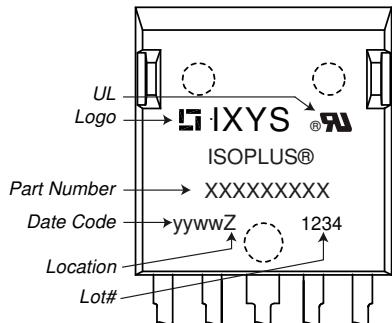
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Thyristor

Symbol	Definition	Conditions	Ratings			
			min.	typ.	max.	
$V_{RSM/DSM}$	max. non-repetitive reverse/forward blocking voltage	$T_{VJ} = 25^\circ\text{C}$			1700	V
$V_{RRM/DRM}$	max. repetitive reverse/forward blocking voltage	$T_{VJ} = 25^\circ\text{C}$			1600	V
$I_{R/D}$	reverse current, drain current	$V_{R/D} = 1600 \text{ V}$ $V_{R/D} = 1600 \text{ V}$	$T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		50 3	μA mA
V_T	forward voltage drop	$I_T = 50 \text{ A}$	$T_{VJ} = 25^\circ\text{C}$		1.30	V
		$I_T = 100 \text{ A}$			1.58	V
		$I_T = 50 \text{ A}$ $I_T = 100 \text{ A}$	$T_{VJ} = 125^\circ\text{C}$		1.23 1.56	V
I_{TAV}	average forward current	$T_C = 90^\circ\text{C}$	$T_{VJ} = 150^\circ\text{C}$		50	A
$I_{T(RMS)}$	RMS forward current	180° sine			79	A
V_{T0}	threshold voltage	$\left. \begin{array}{l} \text{slope resistance} \\ \end{array} \right\} \text{for power loss calculation only}$	$T_{VJ} = 150^\circ\text{C}$		0.88	V
r_T	slope resistance				6.7	$\text{m}\Omega$
R_{thJC}	thermal resistance junction to case				0.7	K/W
R_{thCH}	thermal resistance case to heatsink			0.2		K/W
P_{tot}	total power dissipation		$T_C = 25^\circ\text{C}$		170	W
I_{TSM}	max. forward surge current	$t = 10 \text{ ms}; (50 \text{ Hz}), \text{sine}$	$T_{VJ} = 45^\circ\text{C}$		720	A
		$t = 8,3 \text{ ms}; (60 \text{ Hz}), \text{sine}$	$V_R = 0 \text{ V}$		780	A
		$t = 10 \text{ ms}; (50 \text{ Hz}), \text{sine}$	$T_{VJ} = 150^\circ\text{C}$		610	A
		$t = 8,3 \text{ ms}; (60 \text{ Hz}), \text{sine}$	$V_R = 0 \text{ V}$		660	A
I^2t	value for fusing	$t = 10 \text{ ms}; (50 \text{ Hz}), \text{sine}$	$T_{VJ} = 45^\circ\text{C}$		2.59	kA^2s
		$t = 8,3 \text{ ms}; (60 \text{ Hz}), \text{sine}$	$V_R = 0 \text{ V}$		2.53	kA^2s
		$t = 10 \text{ ms}; (50 \text{ Hz}), \text{sine}$	$T_{VJ} = 150^\circ\text{C}$		1.86	kA^2s
		$t = 8,3 \text{ ms}; (60 \text{ Hz}), \text{sine}$	$V_R = 0 \text{ V}$		1.81	kA^2s
C_J	junction capacitance	$V_R = 400 \text{ V}$ $f = 1 \text{ MHz}$	$T_{VJ} = 25^\circ\text{C}$	32		pF
P_{GM}	max. gate power dissipation	$t_p = 30 \mu\text{s}$	$T_C = 150^\circ\text{C}$		10	W
		$t_p = 300 \mu\text{s}$			5	W
P_{GAV}	average gate power dissipation				0.5	W
$(di/dt)_{cr}$	critical rate of rise of current	$T_{VJ} = 125^\circ\text{C}; f = 50 \text{ Hz}$ repetitive, $I_T = 150 \text{ A}$			150	$\text{A}/\mu\text{s}$
		$t_p = 200 \mu\text{s}; di_G/dt = 0.3 \text{ A}/\mu\text{s};$				
		$I_G = 0.45 \text{ A}; V = \frac{2}{3} V_{DRM}$ non-repet., $I_T = 50 \text{ A}$			500	$\text{A}/\mu\text{s}$
$(dv/dt)_{cr}$	critical rate of rise of voltage	$V = \frac{2}{3} V_{DRM}$	$T_{VJ} = 125^\circ\text{C}$		1000	$\text{V}/\mu\text{s}$
		$R_{GK} = \infty$; method 1 (linear voltage rise)				
V_{GT}	gate trigger voltage	$V_D = 6 \text{ V}$	$T_{VJ} = 25^\circ\text{C}$		1.4	V
			$T_{VJ} = -40^\circ\text{C}$		1.6	V
I_{GT}	gate trigger current	$V_D = 6 \text{ V}$	$T_{VJ} = 25^\circ\text{C}$		80	mA
			$T_{VJ} = -40^\circ\text{C}$		200	mA
V_{GD}	gate non-trigger voltage	$V_D = \frac{2}{3} V_{DRM}$	$T_{VJ} = 150^\circ\text{C}$		0.2	V
I_{GD}	gate non-trigger current				5	mA
I_L	latching current	$t_p = 10 \mu\text{s}$	$T_{VJ} = 25^\circ\text{C}$		450	mA
		$I_G = 0.3 \text{ A}; di_G/dt = 0.3 \text{ A}/\mu\text{s}$				
I_H	holding current	$V_D = 6 \text{ V}$ $R_{GK} = \infty$	$T_{VJ} = 25^\circ\text{C}$		100	mA
t_{gd}	gate controlled delay time	$V_D = \frac{1}{2} V_{DRM}$	$T_{VJ} = 25^\circ\text{C}$		2	μs
		$I_G = 0.5 \text{ A}; di_G/dt = 0.5 \text{ A}/\mu\text{s}$				
t_q	turn-off time	$V_R = 100 \text{ V}; I_T = 50 \text{ A}; V = \frac{2}{3} V_{DRM}$ $T_{VJ} = 125^\circ\text{C}$	$di/dt = 10 \text{ A}/\mu\text{s}$ $dv/dt = 20 \text{ V}/\mu\text{s}$ $t_p = 200 \mu\text{s}$	150		μs

Package i4-Pac			Ratings			
Symbol	Definition	Conditions	min.	typ.	max.	Unit
I_{RMS}	RMS current	per terminal			70	A
T_{VJ}	virtual junction temperature		-40		150	°C
T_{op}	operation temperature		-40		125	°C
T_{stg}	storage temperature		-40		150	°C
Weight				9		g
F_c	mounting force with clip		20		120	N
$d_{Spp/App}$	creepage distance on surface / striking distance through air	terminal to terminal	1.7			mm
$d_{Spb/Apb}$		terminal to backside	5.1			mm
V_{ISOL}	isolation voltage	t = 1 second t = 1 minute	3000 50/60 Hz, RMS; $I_{ISOL} \leq 1$ mA	2500		V

Product Marking



Part description

C = Thyristor (SCR)
 M = Thyristor
 A = (up to 1800V)
 50 = Current Rating [A]
 P = Phase leg
 1600 = Reverse Voltage [V]
 FC = i4-Pac (5)

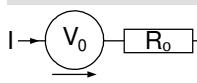
Ordering	Ordering Number	Marking on Product	Delivery Mode	Quantity	Code No.
Standard	CMA50P1600FC	CMA50P1600FC	Tube	25	507603

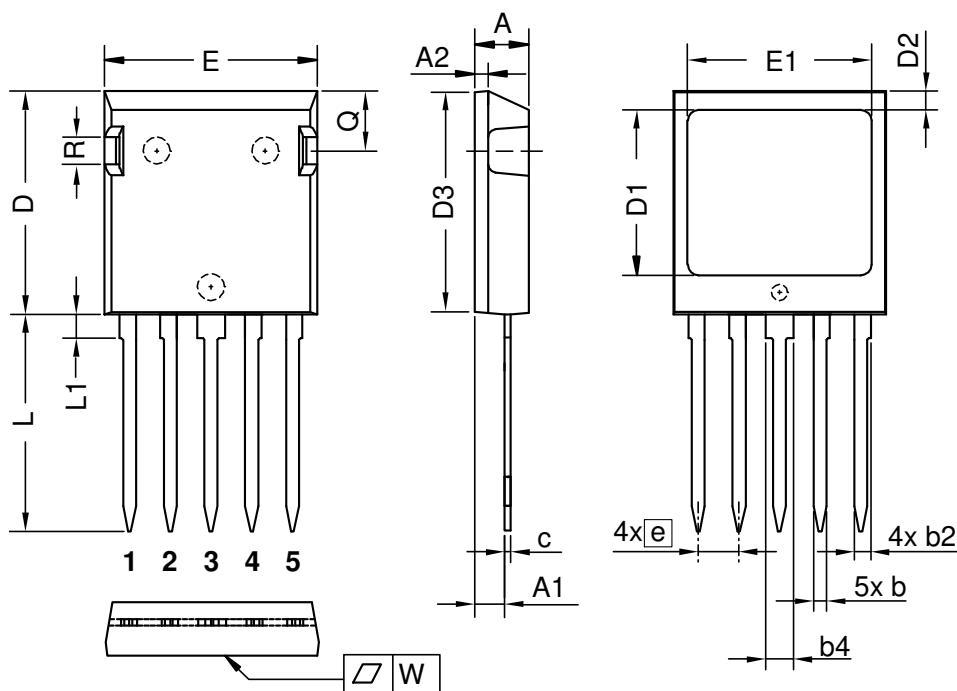
Similar Part	Package	Voltage class
CMA30P1600FC	i4-Pac (5)	1600

Equivalent Circuits for Simulation

* on die level

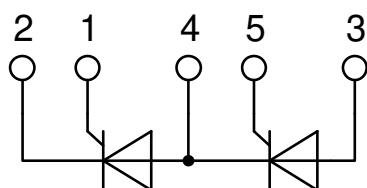
$T_{VJ} = 150^\circ\text{C}$

	Thyristor
V_0	
$V_{0\ max}$	threshold voltage 0.88 V
$R_{0\ max}$	slope resistance * 4.2 mΩ

Outlines i4-Pac


Dim.	Millimeter		Inches	
	min	max	min	max
A	4.83	5.21	0.190	0.205
A1	2.59	3.00	0.102	0.118
A2	1.17	2.16	0.046	0.085
b	1.14	1.40	0.045	0.055
b2	1.47	1.73	0.058	0.068
b4	2.54	2.79	0.100	0.110
c	0.51	0.74	0.020	0.029
D	20.80	21.34	0.819	0.840
D1	14.99	15.75	0.590	0.620
D2	1.65	2.03	0.065	0.080
D3	20.30	20.70	0.799	0.815
E	19.56	20.29	0.770	0.799
E1	16.76	17.53	0.660	0.690
e	3.81	BSC	0.150	BSC
L	19.81	21.34	0.780	0.840
L1	2.11	2.59	0.083	0.102
Q	5.33	6.20	0.210	0.244
R	2.54	4.57	0.100	0.180
W	-	0.10	-	0.004

Die konvexe Form des Substrates ist typ. < 0.05 mm über der Kunststoffoberfläche der Bauteilunterseite
The convexbow of substrate is typ. < 0.05 mm over plastic surface level of device bottom side



Thyristor

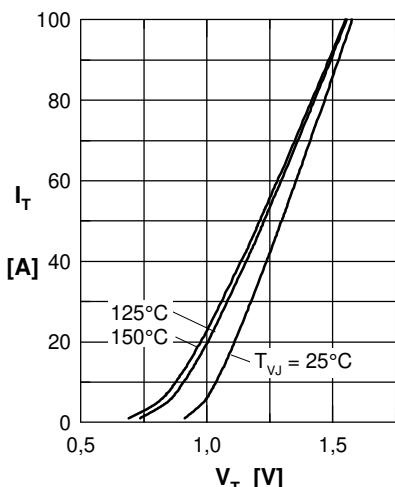


Fig. 1 Forward characteristics

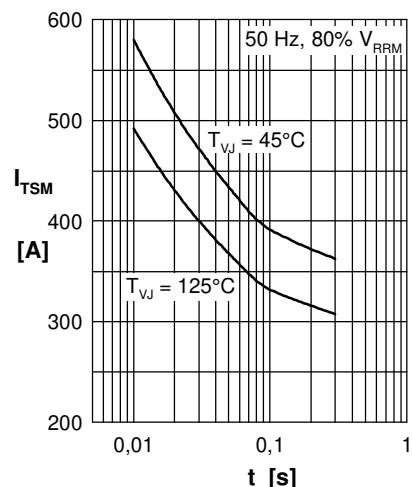


Fig. 2 Surge overload current

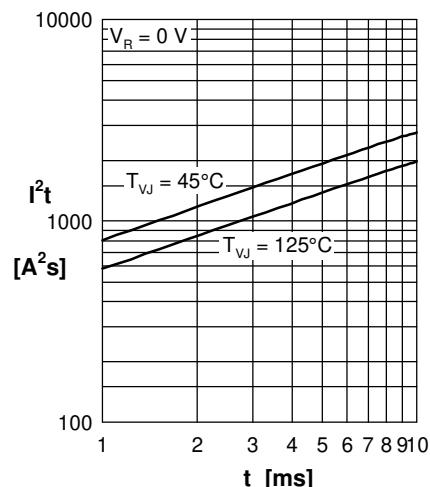


Fig. 3 I^2t versus time (1-10 ms)

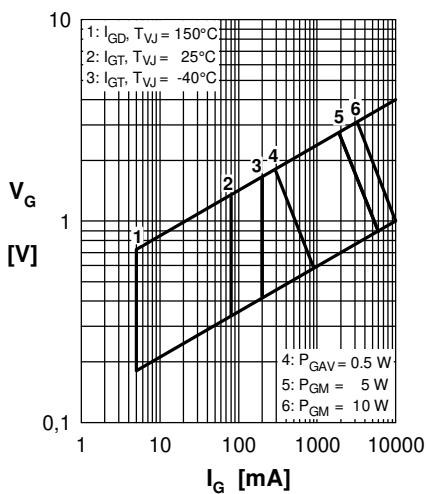


Fig. 4 Gate trigger characteristics

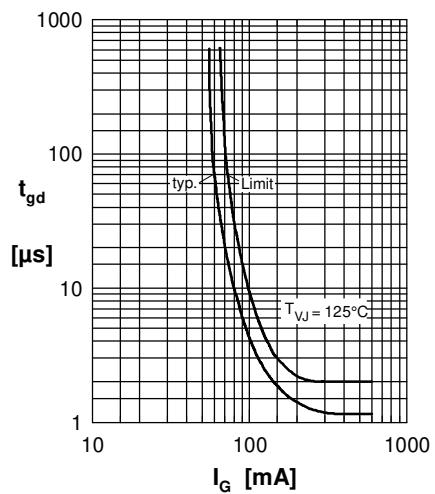


Fig. 5 Gate controlled delay time

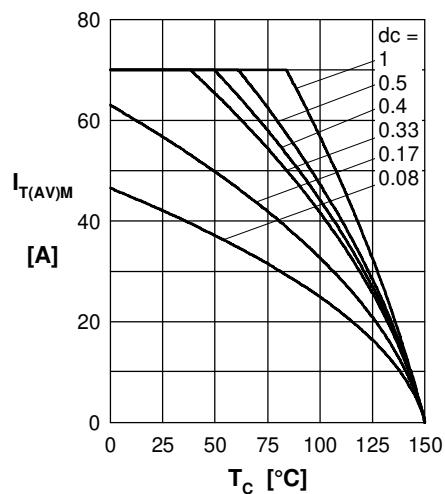


Fig. 6 Max. forward current at case temperature

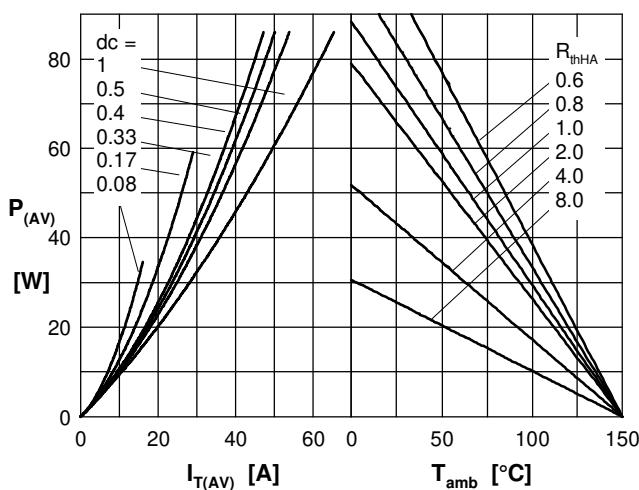


Fig. 7a Power dissipation versus direct output current
Fig. 7b and ambient temperature

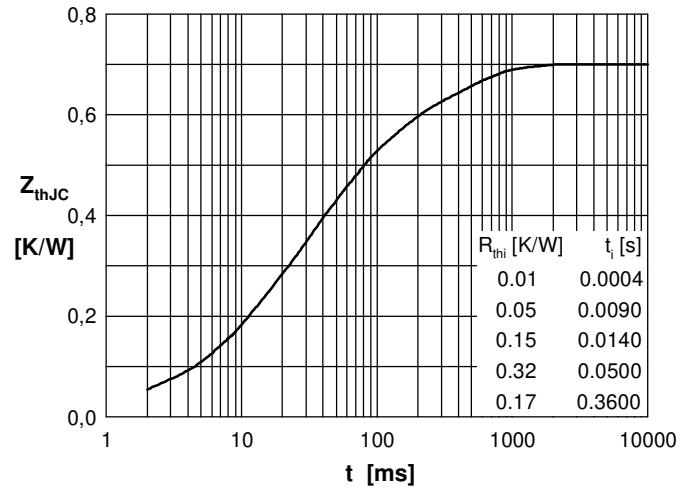


Fig. 8 Transient thermal impedance