74AUP1Z04Low-power X-tal driver with enable and internal resistorRev. 5 — 9 August 2012Product data sheet

1. General description

The 74AUP1Z04 combines the functions of the 74AUP1GU04 and 74AUP1G04 with enable circuitry and an internal bias resistor to provide a device optimized for use in crystal oscillator applications.

When not in use the \overline{EN} input can be driven HIGH, putting the device in a low power disable mode with X1 pulled HIGH via R_{PU}, X2 set LOW and Y set HIGH.Schmitt trigger action at the \overline{EN} input makes the circuit tolerant to slower input rise and fall times across the entire V_{CC} range from 0.8 V to 3.6 V.

This device is fully specified for partial power-down applications using I_{OFF} at output Y. The I_{OFF} circuitry disables the output Y, preventing the damaging backflow current through the device when it is powered down.

The integration of the two devices into the 74AUP1Z04 produces the benefits of a compact footprint, lower power dissipation and stable operation over a wide range of frequency and temperature.

2. Features and benefits

- Wide supply voltage range from 0.8 V to 3.6 V
- High noise immunity
- ESD protection:
 - HBM JESD22-A114F Class 3A exceeds 5000 V
 - MM JESD22-A115-A exceeds 200 V
 - CDM JESD22-C101E exceeds 1000 V
- Latch-up performance exceeds 100 mA per JESD78B Class II
- Inputs accept voltages up to 3.6 V
- Low noise overshoot and undershoot < 10 % of V_{CC}
- I_{OFF} circuitry provides partial Power-down mode operation at output Y
- Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C

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Low-power X-tal driver with enable and internal resistor

3. Ordering information

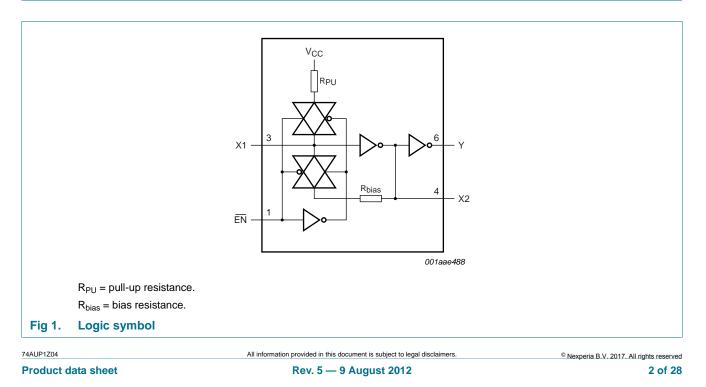
Table 1. Ordering	g information			
Type number	Package			
	Temperature range	Name	Description	Version
74AUP1Z04GW	–40 °C to +125 °C	SC-88	plastic surface-mounted package; 6 leads	SOT363
74AUP1Z04GM	–40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 \times 1.45 \times 0.5 mm	SOT886
74AUP1Z04GF	–40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 \times 1 \times 0.5 mm	SOT891
74AUP1Z04GN	–40 °C to +125 °C	XSON6	extremely thin small outline package; no leads; 6 terminals; body $0.9 \times 1.0 \times 0.35$ mm	SOT1115
74AUP1Z04GS	–40 °C to +125 °C	XSON6	extremely thin small outline package; no leads; 6 terminals; body $1.0 \times 1.0 \times 0.35$ mm	SOT1202

4. Marking

Table 2. Marking	
Type number	Marking code ^[1]
74AUP1Z04GW	a4
74AUP1Z04GM	a4
74AUP1Z04GF	a4
74AUP1Z04GN	a4
74AUP1Z04GS	a4

[1] The pin 1 indicator is located on the lower left corner of the device, below the marking code.

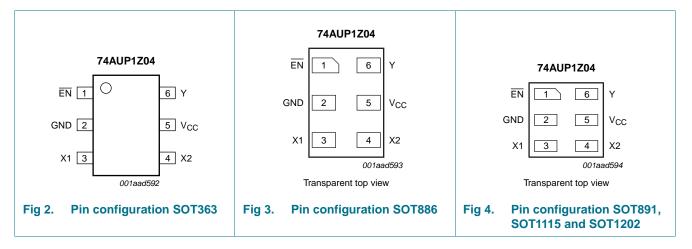
5. Functional diagram



Low-power X-tal driver with enable and internal resistor

6. Pinning information

6.1 Pinning



6.2 Pin description

Symbol	Pin	Description
EN	1	enable input (active LOW)
GND	2	ground (0 V)
X1	3	data input
X2	4	data output
V _{CC}	5	supply voltage
Y	6	data output

7. Functional description

Table 4.Function table^[1]

Input		Output		
EN	X1	X2	Y	
L	L	Н	L	
L	Н	L	Н	
Н	L	Н	L	
Н	Н	L	Н	

[1] H = HIGH voltage level; L = LOW voltage level.

Low-power X-tal driver with enable and internal resistor

8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

					,
Symbol	Parameter	Conditions	Min	Max	Unit
V _{CC}	supply voltage		-0.5	+4.6	V
I _{IK}	input clamping current	V ₁ < 0 V	-50	-	mA
VI	input voltage		<u>[1]</u> –0.5	+4.6	V
I _{OK}	output clamping current	V _O < 0 V	-50	-	mA
Vo	output voltage		<u>[1]</u> –0.5	V _{CC} + 0.5	V
lo	output current	$V_{O} = 0 V$ to V_{CC}	-	±20	mA
I _{CC}	supply current		-	50	mA
I _{GND}	ground current		-50	-	mA
T _{stg}	storage temperature		-65	+150	°C
P _{tot}	total power dissipation	$T_{amb} = -40 \ ^{\circ}C \ to +125 \ ^{\circ}C$	[2] _	250	mW

[1] The minimum input and output voltage ratings may be exceeded if the input and output current ratings are observed.

[2] For SC-88 packages: above 87.5 °C the value of P_{tot} derates linearly with 4.0 mW/K. For XSON6 packages: above 118 °C the value of P_{tot} derates linearly with 7.8 mW/K.

9. Recommended operating conditions

Table 6.	Recommended operating conditi	ons			
Symbol	Parameter	Conditions	Min	Мах	Unit
V _{CC}	supply voltage		0.8	3.6	V
VI	input voltage		0	3.6	V
Vo	output voltage		0	V_{CC}	V
T _{amb}	ambient temperature		-40	+125	°C
$\Delta t / \Delta V$	input transition rise and fall rate	$V_{CC} = 0.8 V \text{ to } 3.6 V$	-	200	ns/V

Table 6. Recommended operating conditions

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10. Static characteristics

Table 7. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
T _{amb} = 2	5 °C					
Ин	HIGH-level input voltage	X1 input				
		V_{CC} = 0.8 V to 3.6 V	$0.75 \times V_{CC}$	-	-	V
		EN input				
		$V_{CC} = 0.8 V$	$0.70\times V_{CC}$	-	-	V
		$V_{CC} = 0.9 V$ to 1.95 V	$0.65 \times V_{CC}$	-	-	V
		V_{CC} = 2.3 V to 2.7 V	1.6	-	-	V
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$	2.0	-	-	V
′IL	LOW-level input voltage	X1 input				
		$V_{CC} = 0.8 V$ to 3.6 V	-	-	$0.25\times V_{CC}$	V
		EN input				
		$V_{CC} = 0.8 V$	-	-	$0.30\times V_{CC}$	V
		$V_{CC} = 0.9 V$ to 1.95 V	-	-	$0.35\times V_{CC}$	V
		V_{CC} = 2.3 V to 2.7 V	-	-	0.7	V
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$	-	-	0.9	V
∕ _{он}	HIGH-level output voltage	Y output; V _I at X1 input = V_{IH} or V_{IL}				
		I_{O} = -20 μ A; V _{CC} = 0.8 V to 3.6 V	$V_{CC}-0.1$	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.75\times V_{CC}$	-	-	V
		$I_0 = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.11	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.32	-	-	V
		$I_{O} = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	2.05	-	-	V
		$I_{O} = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.9	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.72	-	-	V
		$I_{O} = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.6	-	-	V
		X2 output; $V_I = GND$ or V_{CC}				
		I_{O} = -20 μ A; V _{CC} = 0.8 V to 3.6 V	$V_{CC}-0.1$	-	-	V
		$I_0 = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.75 \times V_{CC}$	-	-	V
		$I_0 = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.11	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.32	-	-	V
		$I_0 = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	2.05	-	-	V
		$I_0 = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.9	-	-	V
		$I_0 = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.72	-	-	V
		$I_0 = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.6	-	-	V

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Low-power X-tal driver with enable and internal resistor

At recommended operating conditions; voltages are referenced to GND (ground = 0 V). Symbol Parameter Conditions Unit Min Тур Max LOW-level output voltage Y output; V_I at X1 input = V_{IH} or V_{IL} VOL $I_{O} = 20 \ \mu A$; $V_{CC} = 0.8 \ V$ to 3.6 V V 0.1 -- $I_0 = 1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$ - $0.3 \times V_{CC}$ V - $I_0 = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$ 0.31 V --I_O = 1.9 mA; V_{CC} = 1.65 V V _ _ 0.31 $I_0 = 2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$ _ 0.31 V _ $I_0 = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$ 0.44 V -- $I_{O} = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$ V -_ 0.31 $I_0 = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$ 0.44 V --X2 output; $V_I = GND$ or V_{CC} $I_{O} = 20 \ \mu A; V_{CC} = 0.8 \ V \text{ to } 3.6 \ V$ V 0.1 -- $I_0 = 1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$ $0.3 \times V_{CC}$ V -- $I_0 = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$ 0.31 V --V $I_0 = 1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$ _ 0.31 - $I_0 = 2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$ 0.31 V -- $I_0 = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$ 0.44 V --I_O = 2.7 mA; V_{CC} = 3.0 V V 0.31 -_ $I_0 = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$ 0.44 V -input leakage current X1 input I_I $V_I = \overline{EN} = V_{CC}$; $V_{CC} = 0$ V to 3.6 V --±0.1 μΑ EN input $V_I = GND$ to 3.6 V; ±0.1 μΑ -- $V_{CC} = 0 V \text{ to } 3.6 V$ X1 input; $\overline{EN} = V_{CC}$ Ipu pull-up current $V_{I} = GND; V_{CC} = 0.8 V \text{ to } 3.6 V$ 15 μΑ --[1] _ V_{I} or $V_{O} = 0$ V to 3.6 V; $V_{CC} = 0$ V ±0.2 power-off leakage current μA **I**OFF -[1] additional power-off V_{I} or $V_{O} = 0$ V to 3.6 V; ±0.2 ΔI_{OFF} _ μΑ $V_{CC} = 0 V \text{ to } 0.2 V$ leakage current supply current $V_I = GND \text{ or } V_{CC}; I_O = 0 \text{ A};$ 75 μA Icc -_ $\overline{EN} = GND; V_{CC} = 0.8 V \text{ to } 3.6 V$ ΔI_{CC} additional supply current **EN** input $V_{I} = V_{CC} - 0.6 V; I_{O} = 0 A;$ 40 μΑ -- $V_{CC} = 3.3 V$ Cı input capacitance X1 input $V_{CC} = 0 V \text{ to } 3.6 V;$ 1.3 pF $V_I = GND \text{ or } V_{CC}$ EN input $V_{CC} = 0 V \text{ to } 3.6 V;$ 0.8 pF _ $V_I = GND \text{ or } V_{CC}$

Table 7. Static characteristics ... continued

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Low-power X-tal driver with enable and internal resistor

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Co	output capacitance	X2 output				
		$V_O = GND; V_{CC} = 0 V$	-	1.5	-	pF
		Y output				
		$V_O = GND; V_{CC} = 0 V$	-	1.7	-	pF
Jfs	forward transconductance	see Figure 10 and Figure 11				
		$V_{CC} = 0.8 V$	-	-	-	mA/V
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	0.2	-	9.9	mA/V
		$V_{CC} = 1.4 \text{ V} \text{ to } 1.6 \text{ V}$	3.9	-	17.7	mA/V
		V_{CC} = 1.65 V to 1.95 V	7.9	-	24.3	mA/V
		V_{CC} = 2.3 V to 2.7 V	18	-	30.7	mA/V
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$	20.5	-	32.4	mA/V
R _{bias}	bias resistance	$\overline{EN} = GND; f_i = 0 Hz; V_1 = 0 V or V_{CC}; see Figure 5; for frequency behavior see Figure 6$	1.08	1.62	3.08	MΩ
T _{amb} = –	40 °C to +85 °C					
V _{IH}	HIGH-level input voltage	X1 input				
		$V_{CC} = 0.8 V \text{ to } 3.6 V$	$0.75\times V_{CC}$	-	-	V
		EN input				
		$V_{CC} = 0.8 V$	$0.70\times V_{CC}$	-	-	V
		$V_{CC} = 0.9 V$ to 1.95 V	$0.65 \times V_{CC}$	-	-	V
		V_{CC} = 2.3 V to 2.7 V	1.6	-	-	V
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$	2.0	-	-	V
V _{IL}	LOW-level input voltage	X1 input				
		V_{CC} = 0.8 V to 3.6 V	-	-	$0.25\times V_{CC}$	V
		EN input				
		$V_{CC} = 0.8 V$	-	-	$0.30\times V_{CC}$	V
		V_{CC} = 0.9 V to 1.95 V	-	-	$0.35\times V_{CC}$	V
		V_{CC} = 2.3 V to 2.7 V	-	-	0.7	V
		V_{CC} = 3.0 V to 3.6 V	-	-	0.9	V

Table 7. Static characteristics ...continued

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Low-power X-tal driver with enable and internal resistor

Table 7. Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V _{он}	HIGH-level output voltage	Y output; V _I at X1 input = V_{IH} or V_{IL}				
		I_{O} = –20 $\mu A; V_{CC}$ = 0.8 V to 3.6 V	$V_{CC}-0.1$	-	-	V
		$I_0 = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.7\times V_{CC}$	-	-	V
		$I_0 = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.03	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.30	-	-	V
		$I_{O} = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.97	-	-	V
		$I_{O} = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.85	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.67	-	-	V
		$I_{O} = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.55	-	-	V
		V_I at X1 input = V_{IH} or V_{IL}				
		I_{O} = –20 $\mu\text{A};V_{CC}$ = 0.8 V to 3.6 V	$V_{CC} - 0.1$	-	-	V
		$I_0 = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.7\times V_{CC}$	-	-	V
		$I_0 = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.03	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.30	-	-	V
		$I_{O} = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.97	-	-	V
		$I_{O} = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.85	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.67	-	-	V
		$I_{O} = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.55	-	-	V
/ _{OL}	LOW-level output voltage	Y output; V _I at X1 input = V_{IH} or V_{IL}				
		I_O = 20 $\mu\text{A};V_{CC}$ = 0.8 V to 3.6 V	-	-	0.1	V
		$I_{O} = 1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	-	-	$0.3\times V_{CC}$	V
		I_{O} = 1.7 mA; V_{CC} = 1.4 V	-	-	0.37	V
		I_{O} = 1.9 mA; V_{CC} = 1.65 V	-	-	0.35	V
		I_{O} = 2.3 mA; V_{CC} = 2.3 V	-	-	0.33	V
		$I_{O} = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.45	V
		I_{O} = 2.7 mA; V_{CC} = 3.0 V	-	-	0.33	V
		I_{O} = 4.0 mA; V_{CC} = 3.0 V	-	-	0.45	V
		X2 output; $V_I = GND$ or V_{CC}				
		I_{O} = 20 $\mu\text{A};V_{CC}$ = 0.8 V to 3.6 V	-	-	0.1	V
		$I_{O} = 1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	-	-	$0.3\times V_{CC}$	V
		$I_0 = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	-	-	0.37	V
		I_{O} = 1.9 mA; V_{CC} = 1.65 V	-	-	0.35	V
		I_{O} = 2.3 mA; V_{CC} = 2.3 V	-	-	0.33	V
		$I_{O} = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.45	V
		$I_0 = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.33	V
		I_{O} = 4.0 mA; V_{CC} = 3.0 V	-	-	0.45	V

Low-power X-tal driver with enable and internal resistor

Table 7. Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
I	input leakage current	X1 input				
		$V_I = \overline{EN} = V_{CC}; V_{CC} = 0 V \text{ to } 3.6 V$	-	-	±0.5	μΑ
		EN input				
		V _I = GND to 3.6 V; V _{CC} = 0 V to 3.6 V	-	-	±0.5	μΑ
pu	pull-up current	X1 input; $\overline{EN} = V_{CC}$				
		$V_I = GND; V_{CC} = 0.8 V \text{ to } 3.6 V$	-	-	15	μΑ
OFF	power-off leakage current	V_{I} or V_{O} = 0 V to 3.6 V; V_{CC} = 0 V	<u>[1]</u> _	-	±0.5	μΑ
∆I _{OFF}	additional power-off leakage current	V_1 or $V_0 = 0$ V to 3.6 V; $V_{CC} = 0$ V to 0.2 V	<u>[1]</u>	-	±0.6	μΑ
СС	supply current	$\label{eq:VI} \begin{array}{l} V_{I} = GND \text{ or } V_{CC}; \ I_{O} = 0 \text{ A}; \\ \overline{EN} = GND; \ V_{CC} = 0.8 \text{ V to } 3.6 \text{ V} \end{array}$	-	-	75	μΑ
VI _{CC}	additional supply current	EN input				
		$V_{I} = V_{CC} - 0.6 \text{ V}; I_{O} = 0 \text{ A};$ $V_{CC} = 3.3 \text{ V}$	-	-	50	μΑ
9 _{fs}	forward transconductance	see Figure 10 and Figure 11				
		$V_{CC} = 0.8 V$	-	-	-	mA/\
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	-	-	10.8	mA/
		$V_{CC} = 1.4 \text{ V}$ to 1.6 V	1.8	-	21.2	mA/
		$V_{CC} = 1.65 \text{ V} \text{ to } 1.95 \text{ V}$	7.5	-	29.9	mA/\
		V_{CC} = 2.3 V to 2.7 V	15.0	-	38.0	mA/\
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$	17.8	-	39.2	mA/\
R _{bias}	bias resistance	$\overline{EN} = GND; f_i = 0 Hz; V_I = 0 V or V_{CC}; see Figure 5; for frequency behavior see Figure 6$	1.07	-	3.11	MΩ
Г _{атb} = –	40 °C to +125 °C					
/ _{IH}	HIGH-level input voltage	X1 input				
		$V_{CC} = 0.8 \text{ V} \text{ to } 3.6 \text{ V}$	0.75 × \	V _{CC} -	-	V
		EN input				
		$V_{CC} = 0.8 V$	0.75 × \	V _{CC} -	-	V
		$V_{CC} = 0.9 V$ to 1.95 V	0.70 × \	V _{CC} -	-	V
		$V_{CC} = 2.3 \text{ V} \text{ to } 2.7 \text{ V}$	1.6	-	-	V
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$	2.0	-	-	V
/ _{IL}	LOW-level input voltage	X1 input				
		$V_{CC} = 0.8 V \text{ to } 3.6 V$	-	-	$0.25\times V_{CC}$	V
		EN input				
		$V_{CC} = 0.8 V$	-	-	$0.25 \times V_{CC}$	V
		V_{CC} = 0.9 V to 1.95 V	-	-	$0.30 \times V_{CC}$	V
		V_{CC} = 2.3 V to 2.7 V	-	-	0.7	V
		V_{CC} = 3.0 V to 3.6 V	-	-	0.9	V

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Low-power X-tal driver with enable and internal resistor

Table 7. Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
/ _{ОН}	HIGH-level output voltage	Y output; V _I at X1 input = V _{IH} or V _{IL}				V
		I_O = –20 $\mu\text{A};V_{CC}$ = 0.8 V to 3.6 V	$V_{CC}-0.11$	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.6\times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	0.93	-	-	V
		I_{O} = -1.9 mA; V_{CC} = 1.65 V	1.17	-	-	V
		I_{O} = -2.3 mA; V_{CC} = 2.3 V	1.77	-	-	V
		I_{O} = -3.1 mA; V_{CC} = 2.3 V	1.67	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.40	-	-	V
		$I_{O} = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.30	-	-	V
		X2 output; $V_I = GND$ or V_{CC}				V
		I_{O} = –20 $\mu\text{A};V_{CC}$ = 0.8 V to 3.6 V	$V_{CC} - 0.11$	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.6 \times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	0.93	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.17	-	-	V
		I_{O} = -2.3 mA; V_{CC} = 2.3 V	1.77	-	-	V
		$I_{O} = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.67	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.40	-	-	V
		I_{O} = -4.0 mA; V_{CC} = 3.0 V	2.30	-	-	V
OL	LOW-level output voltage	Y output; V _I at X1 input = V_{IH} or V_{IL}				
		I_O = 20 $\mu A; V_{CC}$ = 0.8 V to 3.6 V	-	-	0.11	V
		I_{O} = 1.1 mA; V_{CC} = 1.1 V	-	-	$0.33 \times V_{CC}$	V
		I_{O} = 1.7 mA; V_{CC} = 1.4 V	-	-	0.41	V
		I_{O} = 1.9 mA; V_{CC} = 1.65 V	-	-	0.39	V
		I_{O} = 2.3 mA; V_{CC} = 2.3 V	-	-	0.36	V
		I_{O} = 3.1 mA; V_{CC} = 2.3 V	-	-	0.50	V
		I_{O} = 2.7 mA; V_{CC} = 3.0 V	-	-	0.36	V
		I_{O} = 4.0 mA; V_{CC} = 3.0 V	-	-	0.50	V
		X2 output; $V_I = GND$ or V_{CC}				
		I_O = 20 μ A; V_{CC} = 0.8 V to 3.6 V	-	-	0.11	V
		I _O = 1.1 mA; V _{CC} = 1.1 V	-	-	$0.33 \times V_{CC}$	V
		$I_0 = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	-	-	0.41	V
		I_{O} = 1.9 mA; V_{CC} = 1.65 V	-	-	0.39	V
		I_{O} = 2.3 mA; V_{CC} = 2.3 V	-	-	0.36	V
		$I_0 = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.50	V
		$I_0 = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.36	V
		$I_0 = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.50	V

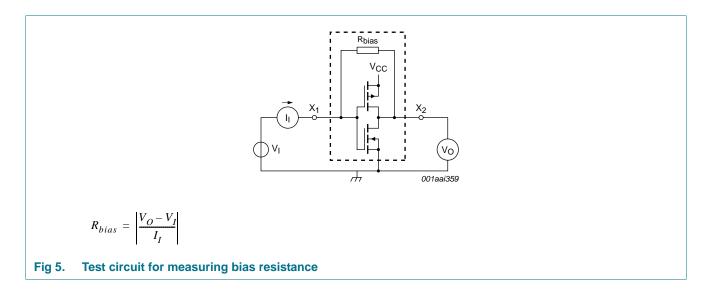
Low-power X-tal driver with enable and internal resistor

Table 7. Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
l _l	input leakage current	X1 input				
		$V_I = \overline{EN} = V_{CC}; V_{CC} = 0 V \text{ to } 3.6 V$	-	-	±0.75	μΑ
		EN input				
		V _I = GND to 3.6 V; V _{CC} = 0 V to 3.6 V	-	-	±0.75	μΑ
I _{pu}	pull-up current	X1 input; $\overline{EN} = V_{CC}$				
		$V_1 = GND; V_{CC} = 0.8 V \text{ to } 3.6 V$	-	-	15	μA
I _{OFF}	power-off leakage current	V_{I} or V_{O} = 0 V to 3.6 V; V_{CC} = 0 V	<u>[1]</u> _	-	±0.75	μA
ΔI_{OFF}	additional power-off leakage current	V_1 or $V_0 = 0$ V to 3.6 V; $V_{CC} = 0$ V to 0.2 V	<u>[1]</u> _	-	±0.75	μΑ
I _{CC}	supply current	$\frac{V_{I}}{EN} = GND \text{ or } V_{CC}; I_{O} = 0 \text{ A};$ $\overline{EN} = GND; V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	75	μA
ΔI_{CC}	additional supply current	EN input				
		$V_{I} = V_{CC} - 0.6 \text{ V}; I_{O} = 0 \text{ A};$ $V_{CC} = 3.3 \text{ V}$	-	-	75	μΑ
g fs	forward transconductance	see Figure 10 and Figure 11				
		$V_{CC} = 0.8 V$	-	-	-	mA/V
		$V_{CC} = 1.1 \text{ V} \text{ to } 1.3 \text{ V}$	-	-	10.8	mA/V
		$V_{CC} = 1.4 \text{ V}$ to 1.6 V	1.8	-	21.2	mA/V
		V_{CC} = 1.65 V to 1.95 V	6.9	-	29.9	mA/V
		V_{CC} = 2.3 V to 2.7 V	13.4	-	38.0	mA/V
		V_{CC} = 3.0 V to 3.6 V	15.8	-	39.2	mA/V
R _{bias}	bias resistance	$\overline{EN} = GND$; f _i = 0 Hz; V ₁ = 0 V or V _{CC} ; see <u>Figure 5</u> ; for frequency behavior see Figure 6	1.07	-	3.11	MΩ

[1] Only for output Y and input \overline{EN} .

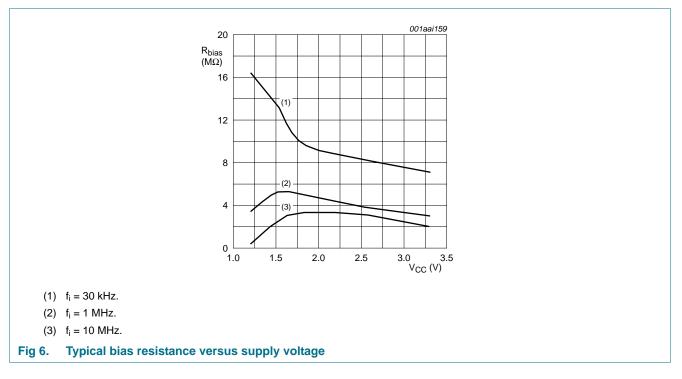


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Low-power X-tal driver with enable and internal resistor



11. Dynamic characteristics

Table 8.Dynamic characteristics

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 9.

Symbol	Parameter	Conditions		Ta	amb =25 °	°C	T _{amb} =	–40 °C to	+125 °C	Unit
				Min	Typ <mark>[1]</mark>	Мах	Min	Max (85 °C)	Max (125 °C)	_
C _L = 5 pl	F									
t _{pd}	propagation delay	X1 to X2; see Figure 7	[2]							
		$V_{CC} = 0.8 V$		-	12.8	-	-	-	-	ns
		V_{CC} = 1.1 V to 1.3 V		1.2	3.0	3.9	1.2	3.9	3.9	ns
		V_{CC} = 1.4 V to 1.6 V		1.0	2.2	2.6	1.0	2.7	2.7	ns
		V_{CC} = 1.65 V to 1.95 V		0.8	1.9	2.3	0.8	2.4	2.5	ns
		V_{CC} = 2.3 V to 2.7 V		0.7	1.6	1.9	0.7	2.0	2.0	ns
		V_{CC} = 3.0 V to 3.6 V		0.7	1.4	1.6	0.7	1.7	1.7	ns
		X1 to Y; see Figure 8	[2]							
		$V_{CC} = 0.8 V$		-	39.2	-	-	-	-	ns
		V_{CC} = 1.1 V to 1.3 V		2.5	8.0	10.7	2.3	10.8	10.9	ns
		V_{CC} = 1.4 V to 1.6 V		2.2	5.5	6.6	2.0	7.0	7.0	ns
		V_{CC} = 1.65 V to 1.95 V		1.8	4.4	5.5	1.7	5.9	6.0	ns
		V_{CC} = 2.3 V to 2.7 V		1.5	3.5	4.1	1.4	4.4	4.5	ns
		V_{CC} = 3.0 V to 3.6 V		1.5	3.1	3.5	1.4	3.8	3.8	ns

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Low-power X-tal driver with enable and internal resistor

Symbol	Parameter	Conditions	Т	_{amb} =25	°C	$T_{amb} = -40 \text{ °C to } +125 \text{ °C}$			Unit
				Typ <mark>[1]</mark>	Max	Min	Max (85 °C)	Max (125 °C)	
C _L = 10 p	ρF								
t _{pd} propagation delay		X1 to X2; see Figure 7 [2]							
		$V_{CC} = 0.8 V$	-	20.9	-	-	-	-	ns
		V_{CC} = 1.1 V to 1.3 V	1.4	4.1	5.4	1.3	5.6	5.6	ns
		V_{CC} = 1.4 V to 1.6 V	1.3	2.9	3.6	1.2	3.8	3.8	ns
	V_{CC} = 1.65 V to 1.95 V	1.2	2.5	3.0	1.1	3.2	3.2	ns	
		V_{CC} = 2.3 V to 2.7 V	0.9	2.0	2.4	0.8	2.5	2.5	ns
		V_{CC} = 3.0 V to 3.6 V	0.9	1.8	2.1	0.8	2.3	2.3	ns
		X1 to Y; see Figure 8 [2]							
	$V_{CC} = 0.8 V$	-	46.6	-	-	-	-	ns	
	V_{CC} = 1.1 V to 1.3 V	2.7	9.2	12.4	2.5	12.7	12.7	ns	
	V_{CC} = 1.4 V to 1.6 V	2.5	6.3	7.8	2.2	8.2	8.2	ns	
	V_{CC} = 1.65 V to 1.95 V	2.3	5.0	6.2	2.2	6.7	6.7	ns	
		V_{CC} = 2.3 V to 2.7 V	1.8	4.0	4.7	1.7	5.0	5.1	ns
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$	1.9	3.6	4.2	1.8	4.5	4.5	ns
C _L = 15 p	ρF								
t _{pd}	propagation delay	X1 to X2; see Figure 7 [2]							
		$V_{CC} = 0.8 V$	-	28.9	-	-	-	-	ns
		V_{CC} = 1.1 V to 1.3 V	1.7	5.2	7.1	1.6	7.2	7.3	ns
		V_{CC} = 1.4 V to 1.6 V	1.6	3.6	4.4	1.6	4.7	4.8	ns
		V_{CC} = 1.65 V to 1.95 V	1.3	3.0	3.7	1.3	3.9	4.0	ns
		V_{CC} = 2.3 V to 2.7 V	1.0	2.4	2.9	1.0	3.1	3.1	ns
		V_{CC} = 3.0 V to 3.6 V	1.1	2.2	2.5	1.0	2.7	2.7	ns
		X1 to Y; see Figure 8 [2]							
		$V_{CC} = 0.8 V$	-	53.9	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	3.1	10.4	14.2	2.8	14.6	14.7	ns
		$V_{CC} = 1.4 \text{ V}$ to 1.6 V	2.9	7.0	8.5	2.7	9.2	9.3	ns
		V_{CC} = 1.65 V to 1.95 V	2.5	5.6	6.9	2.3	7.4	7.5	ns
		V_{CC} = 2.3 V to 2.7 V	2.1	4.5	5.4	2.0	5.7	5.7	ns
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$	2.3	4.1	4.7	2.1	5.1	5.1	ns

Dynamic characteristics ... continued Table 8.

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Low-power X-tal driver with enable and internal resistor

Symbol	Parameter	Conditions	-	Г _{атb} =25 '	°C	T _{amb} =	-40 °C to	• +125 °C	Unit
				Typ <mark>[1]</mark>	Max	Min	Max (85 °C)	Max (125 °C)	_
C _L = 30	ρF						1		
t _{pd} propagation delay		X1 to X2; see Figure 7	[2]						
		$V_{CC} = 0.8 V$	-	52.8	-	-	-	-	ns
		V_{CC} = 1.1 V to 1.3 V	2.4	8.5	11.8	2.3	12.2	12.4	ns
		V_{CC} = 1.4 V to 1.6 V	2.2	5.6	6.8	2.0	7.5	7.6	ns
		V_{CC} = 1.65 V to 1.95 V	2.0	4.5	5.6	1.9	6.2	6.2	ns
	V_{CC} = 2.3 V to 2.7 V		3.7	4.2	1.4	4.6	4.6	ns	
		V_{CC} = 3.0 V to 3.6 V	1.7	3.3	3.7	1.6	4.0	4.2	ns
		X1 to Y; see Figure 8	[2]						
		$V_{CC} = 0.8 V$	-	77.6	-	-	-	-	ns
		V_{CC} = 1.1 V to 1.3 V	3.7	13.8	19.2	3.3	19.8	20.1	ns
	V_{CC} = 1.4 V to 1.6 V	3.4	9.2	11.2	3.1	12.2	12.3	ns	
		V_{CC} = 1.65 V to 1.95 V	3.4	7.4	8.8	3.1	9.7	9.7	ns
		V_{CC} = 2.3 V to 2.7 V	2.6	5.9	6.7	2.4	7.4	7.4	ns
		V_{CC} = 3.0 V to 3.6 V	3.2	5.4	6.2	2.9	6.7	6.9	ns
C _L = 5 pl	F, 10 pF, 15 pF and	30 pF							
C _{PD}	power dissipation capacitance	$f_i = 1 \text{ MHz}; \overline{EN} = GND;$ $V_I = GND \text{ to } V_{CC}$	<u>][4][5]</u>						
		$V_{CC} = 0.8 V$	-	6.8	-	-	-	-	pF
		V_{CC} = 1.1 V to 1.3 V	-	12.0	-	-	-	-	pF
		V_{CC} = 1.4 V to 1.6 V	-	18.2	-	-	-	-	pF
		V_{CC} = 1.65 V to 1.95 V	-	19.2	-	-	-	-	pF
		V_{CC} = 2.3 V to 2.7 V	-	21.9	-	-	-	-	pF
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$	-	24.9	-	-	-	-	pF

Dynamic characteristics ... continued Table 8.

(0, V): for tost circuit soo Figure 0 CND (around

[1] All typical values are measured at nominal V_{CC} .

[2] t_{pd} is the same as t_{PLH} and t_{PHL} .

[3] All specified values are the average typical values over all stated loads.

[4] C_{PD} is used to determine the dynamic power dissipation (P_D in μ W).

 $\label{eq:PD} \mathsf{P}_\mathsf{D} = \mathsf{C}_\mathsf{PD} \times \mathsf{V}_\mathsf{CC}^2 \times \mathsf{f}_i \times \mathsf{N} + \Sigma(\mathsf{C}_\mathsf{L} \times \mathsf{V}_\mathsf{CC}^2 \times \mathsf{f}_o) \text{ where:}$

 f_i = input frequency in MHz;

 $f_o = output frequency in MHz;$

 C_L = output load capacitance in pF;

V_{CC} = supply voltage in V;

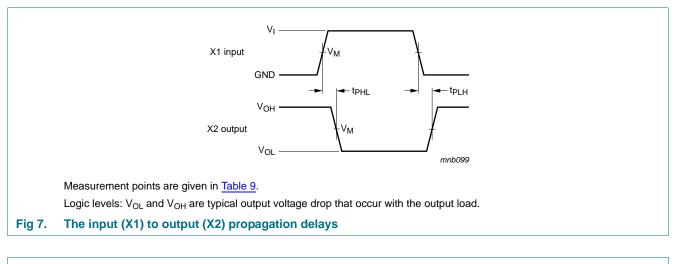
N = number of inputs switching;

 $\Sigma(C_L \times V_{CC}^2 \times f_o)$ = sum of the outputs.

[5] Feedback current is included in the C_{PD}.

Low-power X-tal driver with enable and internal resistor

12. Waveforms



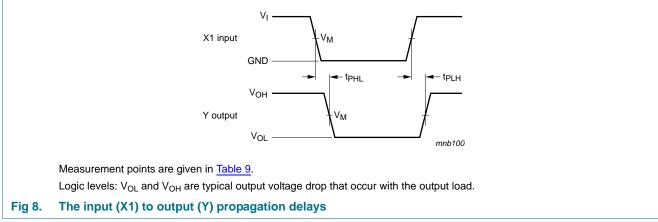


Table 9. Measurement points

Supply voltage	Output	Input		
V _{CC}	V _M	V _M	VI	t _r = t _f
0.8 V to 3.6 V	$0.5\times V_{CC}$	$0.5\times V_{CC}$	V _{CC}	≤ 3.0 ns

Low-power X-tal driver with enable and internal resistor

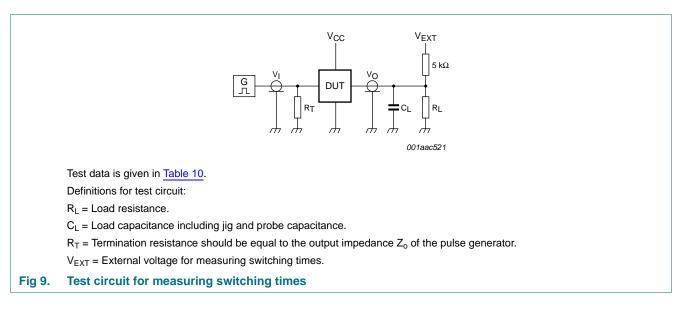
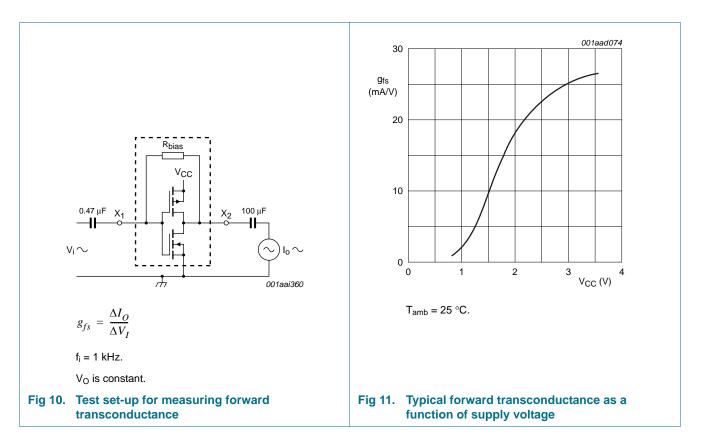


Table 10. Test data

Supply voltage	Load		V _{EXT}		
V _{cc}	CL	R _L [1]	t _{PLH} , t _{PHL}	t _{PZH} , t _{PHZ}	t _{PZL} , t _{PLZ}
0.8 V to 3.6 V	5 pF, 10 pF, 15 pF and 30 pF	5 k Ω or 1 M Ω	open	GND	$2 \times V_{CC}$

[1] For measuring enable and disable times $R_L = 5 k\Omega$, for measuring propagation delays, setup and hold times and pulse width $R_L = 1 M\Omega$.

Low-power X-tal driver with enable and internal resistor



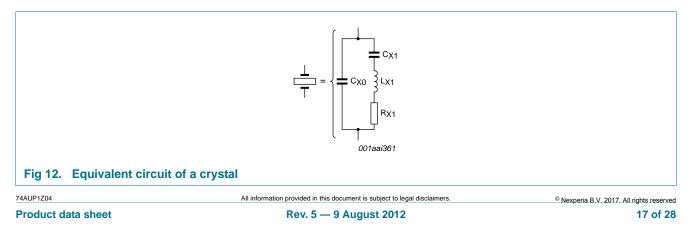
13. Application information

Crystal controlled oscillator circuits are widely used in clock pulse generators because of their excellent frequency stability and wide operating frequency range. The use of the 74AUP1Z04 provides the additional advantages of low power dissipation, stable operation over a wide range of frequency and temperature and a very small footprint. This application information describes crystal characteristics, design and testing of crystal oscillator circuits based on the 74AUP1Z04.

13.1 Crystal characteristics

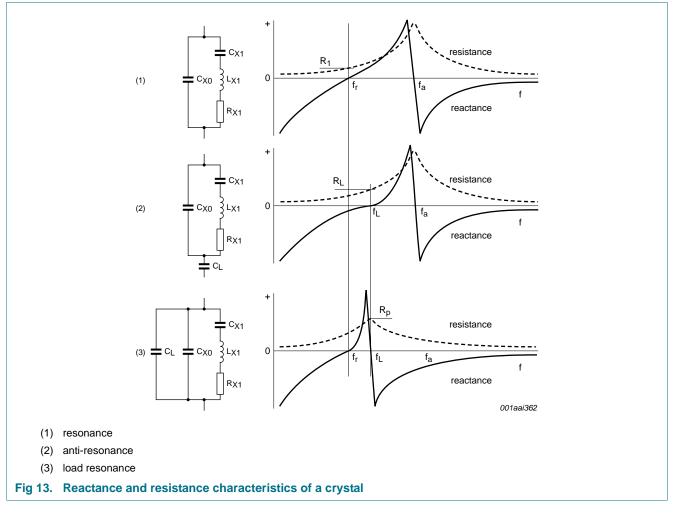
Figure 12 is the equivalent circuit of a quartz crystal.

The reactive and resistive component of the impedance of the crystal alone and the crystal with a series and a parallel capacitance is shown in Figure 13.



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Low-power X-tal driver with enable and internal resistor



13.1.1 Design

Figure 14 shows the recommended way to connect a crystal to the 74AUP1Z04. This circuit is basically a Pierce oscillator circuit in which the crystal is operating at its fundamental frequency and is tuned by the parallel load capacitance of C_1 and C_2 . C_1 and C_2 are in series with the crystal. They should be approximately equal. R_1 is the drive-limiting resistor and is set to approximately the same value as the reactance of C_1 at the crystal frequency ($R_1 = X_{C1}$). This will result in an input to the crystal of 50 % of the rail-to-rail output of X2. This keeps the drive level into the crystal within drive specifications (the designer should verify this). Overdriving the crystal can cause damage.

The internal bias resistor provides negative feedback and sets a bias point of the inverter near mid-supply, operating the 74AUP1GU04 portion in the high gain linear region.

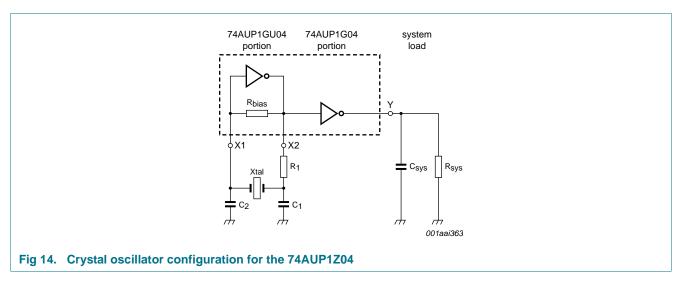
To calculate the values of C_1 and C_2 , the designer can use the formula:

$$C_L = \frac{C_1 \times C_2}{C_1 + C_2} + C_s$$

 C_L is the load capacitance as specified by the crystal manufacturer, C_s is the stray capacitance of the circuit (for the 74AUP1Z04 this is equal to an input capacitance of 1.5 pF).

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13.1.2 Testing

After the calculations are performed for a particular crystal, the oscillator circuit should be tested. The following simple checks will verify the prototype design of a crystal controlled oscillator circuit. Perform them after laying out the board:

- Test the oscillator over worst-case conditions (lowest supply voltage, worst-case crystal and highest operating temperature). Adding series and parallel resistors can simulate a worst-case crystal.
- Insure that the circuit does not oscillate without the crystal.
- Check the frequency stability over a supply range greater than that which is likely to occur during normal operation.
- Check that the start-up time is within system requirements.

As the 74AUP1Z04 isolates the system loading, once the design is optimized, the single layout may work in multiple applications for any given crystal.

Low-power X-tal driver with enable and internal resistor

14. Package outline

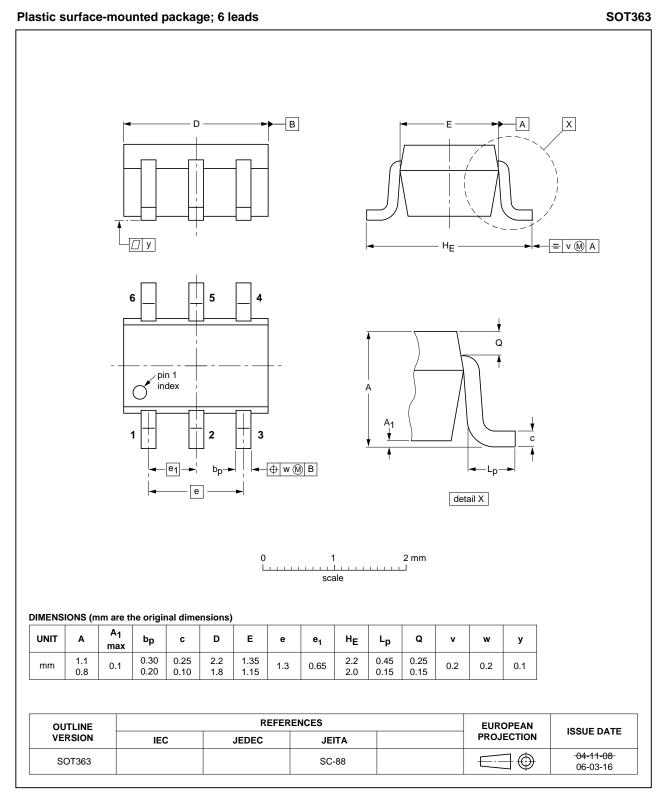


Fig 15. Package outline SOT363 (SC-88)

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Low-power X-tal driver with enable and internal resistor

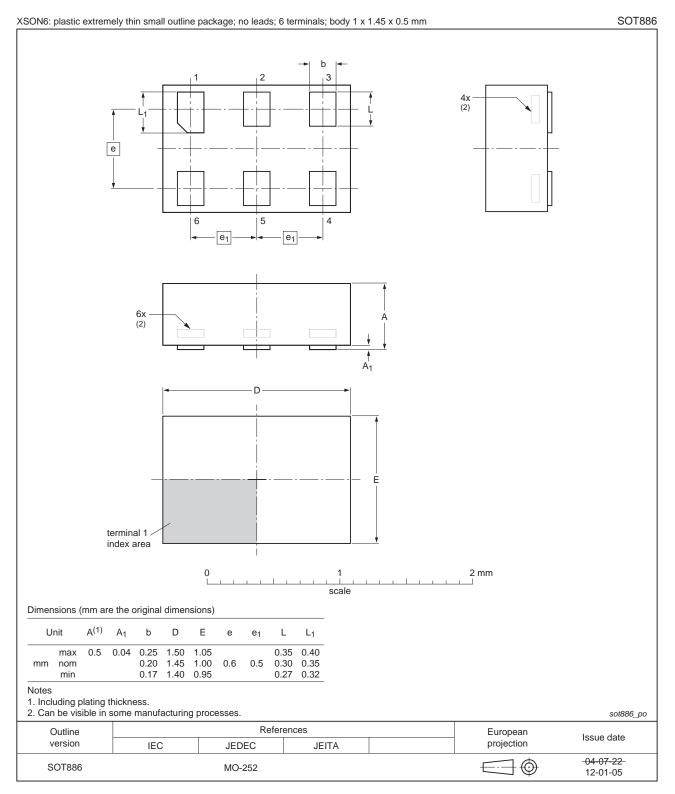


Fig 16. Package outline SOT886 (XSON6)

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Low-power X-tal driver with enable and internal resistor

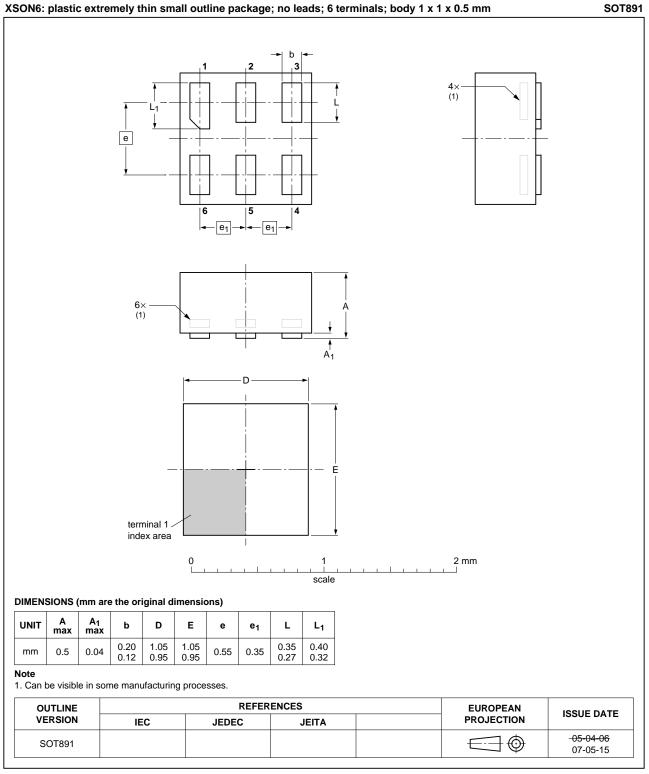
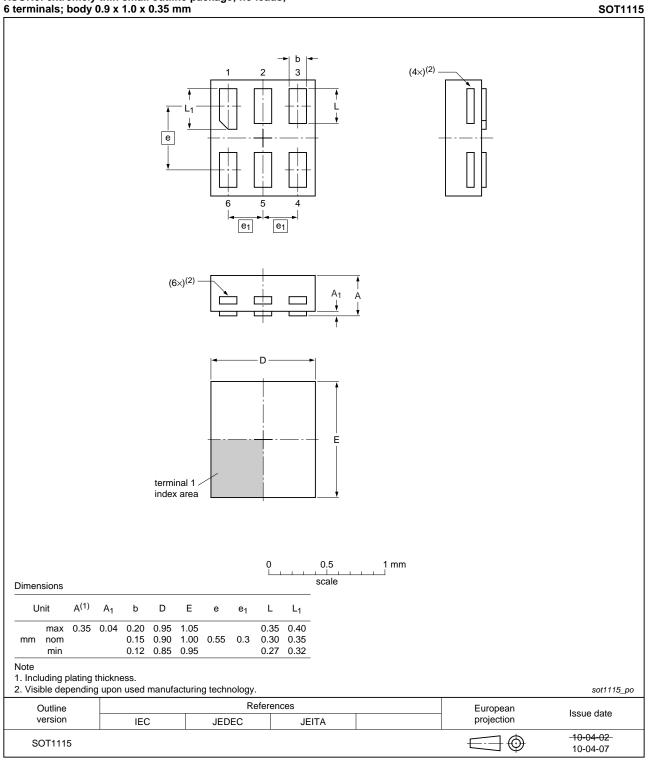


Fig 17. Package outline SOT891 (XSON6)

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Low-power X-tal driver with enable and internal resistor

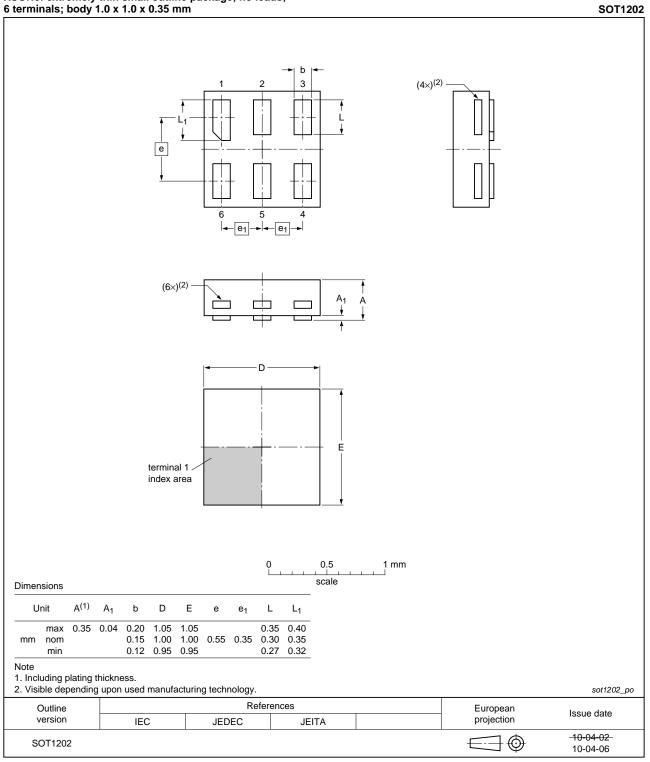


XSON6: extremely thin small outline package; no leads; 6 terminals; body 0.9 x 1.0 x 0.35 mm

Fig 18. Package outline SOT1115 (XSON6)

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XSON6: extremely thin small outline package; no leads; 6 terminals; body 1.0 x 1.0 x 0.35 mm

Fig 19. Package outline SOT1202 (XSON6)

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15. Abbreviations

Table 11. At	breviations
Acronym	Description
CDM	Charged Device Model
DUT	Device Under Test
ESD	ElectroStatic Discharge
HBM	Human Body Model
MM	Machine Model

16. Revision history

Table 12.Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
74AUP1Z04 v.5	20120809	Product data sheet	-	74AUP1Z04 v.4
Modifications:	 Package ou 	tline drawing of SOT886 (Figure 16) modified.	
74AUP1Z04 v.4	20111201	Product data sheet	-	74AUP1Z04 v.3
Modifications:	 Legal pages 	s updated.		
74AUP1Z04 v.3	20100722	Product data sheet	-	74AUP1Z04 v.2
74AUP1Z04 v.2	20080703	Product data sheet	-	74AUP1Z04 v.1
74AUP1Z04 v.1	20061212	Product data sheet	-	-

17. Legal information

17.1 Data sheet status

Document status[1][2]	Product status ^[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL http://www.nexperia.com.

17.2 Definitions

Draft — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. Nexperia does not give any

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74AUP1Z04

Product data sheet

74AUP1Z04

Low-power X-tal driver with enable and internal resistor

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Low-power X-tal driver with enable and internal resistor

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