

System-on-Chip for 2.4-GHz RF Applications

FEATURES

- RF section
 - Single-Chip 2.4-GHz RF Transceiver and MCU
 - Supports 250 kbps, 500 kbps, 1 Mbps and 2 Mbps data rates
 - Excellent Link Budget, Enabling Long Range Without External Front-Ends
 - Programmable Output Power up to 5 dBm
 - Excellent Receiver Sensitivity (–90 dBm at 2 Mbps, –98 dBm at 250 kbps)
 - Suitable for Systems Targeting Compliance With Worldwide Radio Frequency Regulations: ETSI EN 300 328 and EN 300 440 Category 2 (Europe), FCC CFR47 Part 15 (US), and ARIB STD-T66 (Japan)
 - Accurate RSSI Function
- Layout
 - Few External Components
 - Pin Out Suitable for Single Layer PCB Applications
 - Reference Designs Available
 - 32-pin 5-mm × 5-mm QFN (16 General I/O Pins) Package
- Low Power
 - Active Mode RX Best Performance: 21.2 mA
 - Active Mode TX (0 dBm): 26 mA
 - Power Mode 1 (5 μs Wake-Up): 235 μA
 - Power mode 2 (sleep timer on): 0.9 μA
 - Power mode 3 (External interrupts): 0.4µA
 - Wide Supply Voltage Range (2V to 3.6V)
 - Full RAM and Register Retention in All Power Modes

- Microcontroller
 - High-Performance and Low-Power 8051
 Microcontroller Core With Code Prefetch
 - 32-KB Flash Program Memory
 - 1 KB SRAM
 - Hardware Debug Support
 - Extensive Baseband Automation, Including Auto-Acknowledgement and Address Decoding
- Peripherals
 - Two-Channel DMA with Access to all Memory Areas and Peripherals
 - General-Purpose Timers (One 16-Bit, Two 8-Bit)
 - Radio Timer, 40-Bit
 - IR Generation Circuitry
 - Several Oscillators:
 - 32MHz XOSC
 - 16MHz RCOSC
 - 32kHz RCOSC
 - 32-kHz Sleep Timer With Capture
 - AES Security Coprocessor
 - UART/SPI/I²C Serial Interface
 - 16 General-Purpose I/O pins (3 × 20-mA Drive Strength, Remaining pins have 4 mA Drive Strength)
 - Watchdog Timer
 - True Random-Number Generator
 - ADC and Analog Comparator

APPLICATIONS

- Proprietary 2.4-GHz Systems
- Human Interface Devices (keyboard, mouse)
- Consumer Electronics

Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

PRODUCT PREVIEW



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

ABSOLUTE MAXIMUM RATINGS⁽¹⁾

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
Supply voltage VDD	All supply pins must have the same voltage	-0.3	3.9	V
Voltage on any digital pin		-0.3	VDD + 0.3 ≤ 3.9	V
Input RF level			10	dBm
Storage temperature range		-40	125	°C
ESD ⁽²⁾	All pins, excluding 20 and 21, according to human-body model, JEDEC STD 22, method A114 (HBM)		2.5	kV
	All pins, according to human-body model, JEDEC STD 22, method A114 (HBM)		1.5	kV
	According to charged-device model, JEDEC STD 22, method C101 (CDM)		750	V

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) CAUTION: ESD sensitive device. Precaution should be used when handing the device in order to prevent permanent damage.

RECOMMENDED OPERATING CONDITIONS

		MIN	MAX	UNIT
Operating ambient temperature range, T_{A}		-40	85	°C
Operating supply voltage VDD	All supply pins must have same voltage	2	3.6	V

ELECTRICAL CHARACTERISTICS

Measured on Texas Instruments CC2543EM reference design with $T_A = 25^{\circ}C$ and VDD = 3 V, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN TYP	MAX	UNIT
	2 Mbps, GFSK, 320-kHz deviation			
	RX mode, no peripherals active, low MCU activity	21.2		mA
	TX mode, 0-dBm output power, no peripherals active, low MCU activity	26		mA
	TX mode, 5-dBm output power, no peripherals active, low MCU activity	29.4		mA
	Active mode, 16-MHz RCOSC, Low MCU activity	3		mA
	Active mode, 32-MHz clock frequency, low MCU activity	6		mA
	Power mode 0, CPU clock halted, all peripherals on, no clock division, 32-MHz crystal selected	4.5		mA
I core – Core current consumption	Power mode 0, CPU clock halted, all peripherals on, clock division at max (Limits max speed in peripherals except radio), 32-MHz crystal selected	3.1		mA
	Power mode 1. Digital regulator on; 16-MHz RCOSC and 32-MHz crys tal oscillator off; 32.753-kHz RCOSC, POR, BOD, and sleep timer active; RAM and register retention	235		μA
	Power mode 2. Digital regulator off, 16 MHz RCOSC and 32 MHz crystal oscillator off; 32.753 kHz RCOSC, POR and sleep timer active; RAM and register retention	0.9		μA
	Power mode 3. Digital regulator off, no clocks, POR active; RAM and register retention	0.4		μA



ELECTRICAL CHARACTERISTICS (continued)

Measured on Texas Instruments CC2543EM reference design with $T_A = 25^{\circ}C$ and VDD = 3 V, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
I _{peri} – Peripheral	Timer 1 (16-bit). Timer running, 32-MHz XOSC used		90		μA
current consumption	Radio timer(40 bit). Timer running, 32-MHz XOSC used		90		μA
(Adds to core current I _{core} for each	Timer 3 (8-bit). Timer running, 32-MHz XOSC used		60		μA
peripheral unit	Timer 4 (8-bit). Timer running, 32-MHz XOSC used		70		μA
activated)	Sleep timer. Including 32.753-kHz RCOSC		0.6		μA

GENERAL CHARACTERISTICS

Measured on Texas Instruments CC2543EM reference design with $T_A = 25^{\circ}C$ and VDD = 3 V, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
WAKE-UP AND TIMING	WAKE-UP AND TIMING				
Power mode $1 \rightarrow Active$	Digital regulator ON, 16-MHz RCOSC and 32-MHz crystal oscillator OFF. Start-up of 16-MHz RCOSC		5		μs
Power mode 2 or 3 \rightarrow Active	Digital regulator OFF, 16 MHz RCOSC and 32 MHz crystal oscillator OFF. Start-up of regulator and 16 MHz RCOSC		130		μs
Active \rightarrow TX or RX	Crystal ESR = 16 $\Omega.$ Initially running on 16-MHz RCOSC, with 32-MHz XOSC OFF		500		μs
	With 32-MHz XOSC initially ON		180		μs
RX/TX turnaround	RCOSC, with 32MHz XOSC OFF		130		μs
RADIO PART					
RF frequency range	Programmable in 1-MHz steps	2379		2496	MHz
Data rates and modulation formats	2 Mbps, GFSK 320-kHz deviation 2-Mbps, GFSK 500 kHz deviation 1-Mbps, GFSK 250 kHz deviation 1-Mbps, GFSK 160 kHz deviation 500 kbps, MSK 250 kbps, GFSK 160 kHz deviation 250 kbps, MSK				

RF RECEIVE SECTION

Measured on Texas Instruments CC2543EM reference design with $T_A = 25^{\circ}$ C, VDD = 3 V, and $f_C = 2440$ MHz, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN T	YP N	ЛАХ	UNIT
2 Mbps, GFSK, 320-kHz DEVIA	ATION, 0.1% BER				
Receiver sensitivity		-	-86		dBm
Saturation			-8		dBm
Co-channel rejection	Wanted signal at -67 dBm	-	13		dB
In-band blocking rejection	±2-MHz offset, wanted signal at –67 dBm		-1		
	±4-MHz offset, wanted signal at –67 dBm		34		dB
	>±6-MHz offset, wanted signal at -67 dBm		38		
	1-MHz resolution. Wanted signal at –67 dBm, f < 2 GHz Two exception frequencies with poorer performance	-	-32		
Out-of-band blocking rejection	1-MHz resolution. Wanted signal at –67 dBm, 2 GHz > f < 3 GHz Two exception frequencies with poorer performance	-	-38		dBm
	1-MHz resolution. Wanted signal at –67 dBm, f > 3GHz Two exception frequencies with poorer performance	-	·12		
Intermodulation	Wanted signal at -64 dBm, 1 st interferer is CW, 2 nd interferer is GFSK- modulated signal. Offsets of interferers are: 6 and 12 MHz 8 and 16 MHz 10 and 20 MHz	_	43		dBm



RF RECEIVE SECTION (continued)

Measured on Texas Instruments CC2543EM reference design with $T_A = 25$ °C, VDD = 3 V, and $f_C = 2440$ MHz, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Frequency error tolerance ⁽¹⁾	Including both initial tolerance and drift. Sensitivity better than –70 dBm. 250 byte payload.	-300		300	kHz
Symbol rate error tolerance ⁽²⁾	Sensitivity better than -70 dBm. 250 byte payload.	-120		120	ppm
2 Mbps, GFSK, 500 kHz DEVIA	ATION, 0.1% BER				
Receiver sensitivity			-90		dBm
Saturation			-3		dBm
Co-channel rejection	Wanted signal at –67 dBm		-10		dB
	±2 MHz offset, wanted signal at –67 dBm		-3		dB
In-band blocking rejection	±4 MHz offset, wanted signal at –67 dBm		36		dB
	>±6 MHz offset, wanted signal at –67 dBm		44		dB
Frequency error tolerance ⁽¹⁾	Including both initial tolerance and drift. Sensitivity better than –70 dBm. 250 byte payload.	-300		300	kHz
Symbol rate error tolerance ⁽²⁾	Sensitivity better than -70 dBm. 250 byte payload.	-120		120	ppm
1 Mbps, GFSK, 250 kHz DEVIA	ATION, 0.1% BER				
Receiver sensitivity			-94		dBm
Saturation			6		dBm
Co-channel rejection	Wanted signal at –67 dBm		-7		dB
	±1 MHz offset, wanted signal –67 dBm		0		
to be a distant to a set of the	±2 MHz offset, wanted signal –67 dBm		30		
In-band blocking rejection	±3 MHz offset, wanted signal –67 dBm		34		dB
	>±5 MHz offset, wanted signal –67 dBm		38		
Frequency error tolerance	Including both initial tolerance and drift. Sensitivity better than –70 dBm. 250 byte payload.	-250		250	kHz
Symbol rate error tolerance	Sensitivity better than –70 dBm. 250 byte payload.	-80		80	ppm
1 Mbps, GFSK, 160 kHz DEVIA	ATION, 0.1% BER				
Receiver sensitivity			-91		dBm
Saturation			6		dBm
Co-channel rejection	Wanted signal at –67 dBm		-8		dB
	±1 MHz offset, wanted signal at –67 dBm		2		
	±2 MHz offset, wanted signal at –67 dBm		28		
In band blocking rejection	±3 MHz offset, wanted signal at –67 dBm		33		dB
	>±5 MHz offset, wanted signal at –67 dBm		36		1
Frequency error tolerance	Including both initial tolerance and drift, Sensitivity better than -67 dBm	-250		250	kHz
Symbol rate error tolerance	Maximum packet length	-80		80	ppm

(1) Difference between center frequency of the received RF signal and local oscillator frequency

(2) Difference between incoming symbol rate and the internally generated symbol rate



RF RECEIVE SECTION (continued)

Measured on Texas Instruments CC2543EM reference design with $T_A = 25^{\circ}$ C, VDD = 3 V, and $f_C = 2440$ MHz, unless otherwise noted.

500 kbps, MSK, 0.1% BERReceiver sensitivitySaturationCo-channel rejectionWanted signal at –67 dBmIn band blocking rejection±1 MHz offset, wanted signal at –67 dBm±2 MHz offset, wanted signal at –67 dBm>±2 MHz offset, wanted signal at –67 dBmFrequency error toleranceIncluding both initial tolerance and drift, Sensitivity better than –67dBmSymbol rate error toleranceMaximum packet length250 kbps, GFSK, 160 kHz DEV×TION , 0.1% BERReceiver sensitivitySaturationWanted signal at –67 dBmCo-channel rejectionWanted signal at –67 dBm	-150 -60	-98 6 -5 21 32 33		dBm dBm dB dB
Saturation Vanted signal at -67 dBm Co-channel rejection Wanted signal at -67 dBm In band blocking rejection ±1 MHz offset, wanted signal at -67 dBm ±2 MHz offset, wanted signal at -67 dBm >±2 MHz offset, wanted signal at -67 dBm >±2 MHz offset, wanted signal at -67 dBm Symbol rate error tolerance Including both initial tolerance and drift, Sensitivity better than -67dBm Symbol rate error tolerance Maximum packet length 250 kbps, GFSK, 160 kHz DEVIATION , 0.1% BER Receiver sensitivity Saturation		6 5 21 32		dBm dB
Co-channel rejection Wanted signal at -67 dBm In band blocking rejection ±1 MHz offset, wanted signal at -67 dBm ±2 MHz offset, wanted signal at -67 dBm >±2 MHz offset, wanted signal at -67 dBm >±2 MHz offset, wanted signal at -67 dBm Symbol rate error tolerance Including both initial tolerance and drift, Sensitivity better than -67dBm Symbol rate error tolerance Maximum packet length 250 kbps, GFSK, 160 kHz DEV+TION , 0.1% BER Receiver sensitivity Saturation		-5 21 32		dB
In band blocking rejection ±1 MHz offset, wanted signal at -67 dBm ±2 MHz offset, wanted signal at -67 dBm >±2 MHz offset, wanted signal at -67 dBm >±2 MHz offset, wanted signal at -67 dBm Symbol rate error tolerance Including both initial tolerance and drift, Sensitivity better than -67dBm 250 kbps, GFSK, 160 kHz DEVIATION , 0.1% BER Receiver sensitivity Saturation		21 32		
In band blocking rejection ±2 MHz offset, wanted signal at -67 dBm >±2 MHz offset, wanted signal at -67 dBm Frequency error tolerance Including both initial tolerance and drift, Sensitivity better than -67dBm Symbol rate error tolerance Maximum packet length 250 kbps, GFSK, 160 kHz DEVIATION , 0.1% BER Receiver sensitivity Saturation		32		dB
>±2 MHz offset, wanted signal at -67 dBm Frequency error tolerance Including both initial tolerance and drift, Sensitivity better than -67dBm Symbol rate error tolerance Maximum packet length 250 kbps, GFSK, 160 kHz DEVIATION , 0.1% BER Receiver sensitivity Saturation		-		dB
Frequency error tolerance Including both initial tolerance and drift, Sensitivity better than -67dBm Symbol rate error tolerance Maximum packet length 250 kbps, GFSK, 160 kHz DEVIATION , 0.1% BER Receiver sensitivity Saturation		33		
Symbol rate error tolerance Maximum packet length 250 kbps, GFSK, 160 kHz DEVIATION , 0.1% BER Receiver sensitivity Saturation				1
250 kbps, GFSK, 160 kHz DEVIATION , 0.1% BER Receiver sensitivity Saturation	-60		150	kHz
Receiver sensitivity Saturation			60	ppm
Saturation				
		-98		dBm
Co-channel rejection Wanted signal at -67 dBm		6		dBm
Trained olynamic of upin		-2		dB
±1 MHz offset, wanted signal at –67 dBm		22		
In-band blocking rejection ±2 MHz offset, wanted signal at -67 dBm		32		dB
>±2 MHz offset, wanted signal at –67 dBm		32		1
Frequency error tolerance Including both initial tolerance and drift, Sensitivity better than –67 dBm	-150		150	kHz
Symbol rate error tolerance Maximum packet length	-60		60	ppm
250 kbps, MSK, 0.1% BER				
Receiver sensitivity		-98		dBm
Saturation		6		dBm
Co-channel rejection Wanted signal at -67 dBm		-5		dB
±1 MHz offset, wanted signal at –67 dBm		21		
In-band blocking rejection ±2 MHz offset, wanted signal at -67 dBm		32		dB
>2 MHz offset, wanted signal at –67 dBm		33		1
Frequency error tolerance Including both initial tolerance and drift, Sensitivity better than –67 dBm	-150		150	kHz
Symbol rate error tolerance Maximum packet length	-60		60	ppm
ALL RATES/FORMATS				
Spurious emission in RX. Conducted measurement f < 1 GHz		-67		dBm
Spurious emission in RX. Conducted measurement f > 1 GHz		-60		dBm



RF TRANSMIT SECTION

Measured on Texas Instruments CC2543EM reference design with $T_A = 25^{\circ}$ C, VDD = 3 V, and $f_C = 2440$ MHz, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Output power, maximum setting	Delivered to a single-ended 50- Ω load through a balun using maximum recommended output power setting.		5		dBm
Output power, minimum setting	Delivered to a single-ended 50- Ω load through a balun using minimum recommended output power setting.		-20		dBm
Programmable output power range	Delivered to a single-ended 50- Ω load through a balun.		25		dB
	f < 1 GHz		-46		dBm
Spurious emission in TX. Conducted measurement	f > 1 GHz		-46		dBm
	Suitable for Systems Targeting Compliance With Worldwide Radio Frequency Regulations: ETSI EN 300 328 and EN 300 440 Class 2 (Europe), FCC CFR47 Part 15 (US), and ARIB STD-T66 (Japan)				

Use a simple LC filter (1.6nH and 1.8pF in parallel to ground) to pass ETSI conducted requirements below 1GHz in restricted bands. For radiated measurements low antenna gain for these frequencies (depending on antenna design) can achieve the same attenuation of these low frequency components (see EM reference design).

32-MHz CRYSTAL OSCILLATOR

Measured on Texas Instruments CC2543EM reference design with $T_A = 25^{\circ}C$, VDD = 3 V, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Crystal frequency			32		MHz
	250 kbps and 500 kbps data rates	-30		30	
Crystal frequency accuracy	1 Mbps data rate	-40		40	ppm
requirement	2 Mbps data rate	-60		60	
Equivalent series resistance		6		60	Ω
Crystal shunt capacitance		1		7	pF
Crystal load capacitance		10		16	pF
Start-up time			0.25		ms
Power-down guard time	The crystal oscillator must be in power down for a guard time before it is used again. This requirement is valid for all modes of operation. The need for power-down guard time can vary with crystal type and load.	3			ms

32-kHz RC OSCILLATOR

Measured on Texas Instruments CC2543EM reference design with T_A = 25°C, VDD = 3 V, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN TYP	MAX	UNIT
Calibrated frequency		32.753		kHz
Frequency accuracy after calibration		±0.2%		
Temperature coefficient		0.4		%/ºC
Supply-voltage coefficient		3		%/V
Calibration time		2		ms

16-MHz RC OSCILLATOR

Measured on Texas Instruments CC2543EM reference design with $T_A = 25^{\circ}C$, VDD = 3 V, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Calibrated frequency			16		MHz
Uncalibrated frequency accuracy		:	±18%		
Frequency accuracy after calibration		÷	±0.6%		
Start-up time			10		μs
Initial calibration time			50		μs

RSSI CHARACTERISTICS

Measured on Texas Instruments CC2543EM reference design with $T_A = 25^{\circ}C$, VDD = 3 V, unless otherwise noted.

2Mbps, GFSK, 320-kHz Deviation, 0.1% BE	R and 2 Mbps, GFSK, 500-kHz Deviation, 0.1% BE	R	
RSSI range ⁽¹⁾	Reduced gain by AC algorithm		dB
RSSFrange	High gain by AGC algorithm	64	uв
RSSI offset ⁽¹⁾	Reduced gain by AGC algorithm	79	dBm
RSSI Oliset /	High gain by AGC algorithm	99	ubm
Absolute uncalibrated accuracy ⁽¹⁾		±3	dB
Step size (LSB value)		1	dB
All Other Rates/Formats			
RSSI range ⁽¹⁾		64	dB
RSSI offset ⁽¹⁾		99	dBm
Absolute uncalibrated accuracy		±3	dB
Step size (LSB value)		1	dB

(1) Assuming CC2543 EM reference design. Other RF designs give an offset from the reported value.

FREQUENCY SYNTHESIZER CHARACTERISTICS

Measured on Texas Instruments CC2543EM reference design with T_A = 25°C, VDD = 3 V, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
	At ±1 MHz from carrier		-112		
Phase noise, unmodulated carrier	At ±3 MHz from carrier		-119		dBc/Hz
	At ±5 MHz from carrier		-122		

ANALOG TEMPERATURE SENSOR

Measured on Texas Instruments CC2543EM reference design with T_A = 25°C, VDD = 3 V unless otherwise noted

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Output			1480		12-bit
Temperature coefficient			4.5		mV/⁰C
Voltage coeficcient	Measured using integrated ADC, internal band-gap voltage		1		/ 0.1V
Initial accuracy without calibration	reference, and maximum resolution		±10		°C
Accuracy using 1-point calibration			±5		°C
Current consumption when enabled			0.5		mA

DC CHARACTERISTICS

<u>Measured on Texas Instruments CC2543EM</u> reference design with $T_A = 25^{\circ}C$, VDD = 3 V, unless otherwise noted.⁽¹⁾

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Logic-0 input voltage				0.5	V
Logic-1 input voltage		2.5			V
Logic-0 input current		-50		50	nA
Logic-1 input current		-50		50	nA
I/O pin pullup and pulldown resistors			20		kΩ
Logic-0 output voltage 4-mA pins	Output load 4 mA			0.5	V
Logic-1 output voltage 4-mA pins	Output load 4 mA	2.4			V
Logic-0 output voltage 20-mA pins	Output load 20 mA			0.5	V
Logic-1 output voltage 20-mA pins	Output load 20 mA	2.4			V

(1) Note that only two of the three 20mA pins can drive in the same direction at the same time, and toggle at the same time.

NSTRUMENTS

FEXAS

CONTROL INPUT AC CHARACTERISTICS

$T_A = -40^{\circ}C$ to	85°C. VDD =	2 V to 3.6 V.
$I_{A} = 1000.00$	00 0, 100 -	

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
System clock, f_{SYSCLK} $t_{SYSCLK} = 1/f_{SYSCLK}$	The undivided system clock is 32 MHz when crystal oscillator is used. The undivided system clock is 16 MHz when calibrated 16-MHz RC oscillator is used.	16		32	MHz
RESET_N low duration	See item 1, Figure 1. This is the shortest pulse that is recognized as a complete reset pin request. Note that shorter pulses may be recognized but do not lead to complete reset of all modules within the chip.	1			μs
Interrupt pulse duration	See item 2, Figure 1.This is the shortest pulse that is recognized as an interrupt request.	20			ns

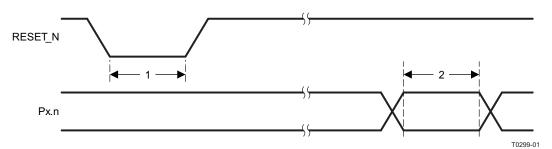


Figure 1. Control Input AC Characteristics

SPI AC CHARACTERISTICS

 $T_A = -40^{\circ}C$ to 85°C, VDD = 2 V to 3.6 V

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
		Master, RX and TX	250				
t ₁	SCK period	Slave, RX and TX	250			ns	
	SCK duty cycle	Master		50%			
	CON Jour to COK Figure 2 and Figure 2	Master	63				
t ₂	SSN low to SCK, Figure 2 and Figure 3	Slave	63			ns	
	CCK to CCN high	Master	63			~~~	
t ₃	SCK to SSN high	Slave	63			ns	
t ₄	MOSI early out	Master, load = 10 pF			7	ns	
t ₅	MOSI late out	Master, load = 10 pF			10	ns	
t ₆	MISO setup	Master	90			ns	
t7	MISO hold	Master	10			ns	
	SCK duty cycle	Slave		50%		ns	
t ₁₀	MOSI setup	Slave	35			ns	
t ₁₁	MOSI hold	Slave	10			ns	
t ₈	MISO early out	Slave, load = 10 pF			0	ns	
t ₉	MISO late out	Slave, load = 10 pF			95	ns	
		Master, TX only			8		
	Operating fragmana	Master, RX and TX			4		
	Operating frequency	Slave, RX only			8	MHz	
		Slave, RX and TX			4		



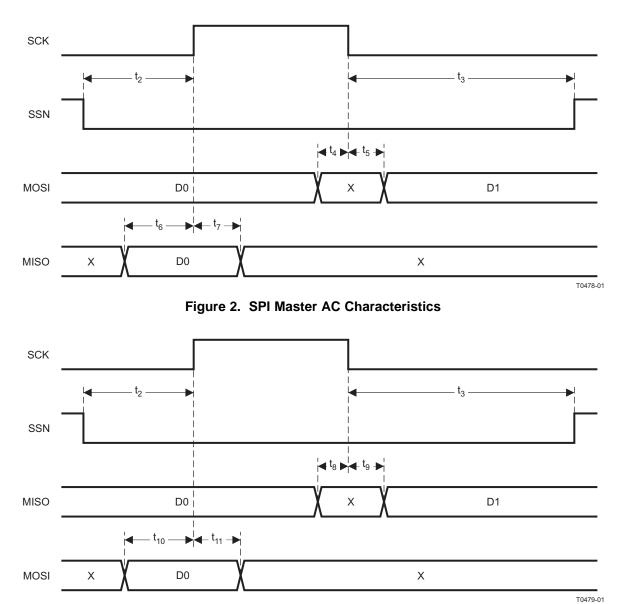
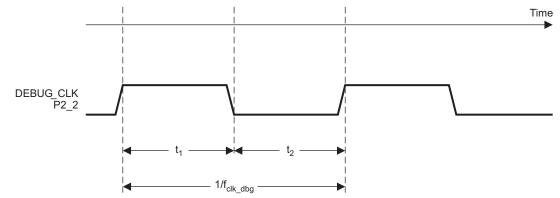


Figure 3. SPI Slave AC Characteristics

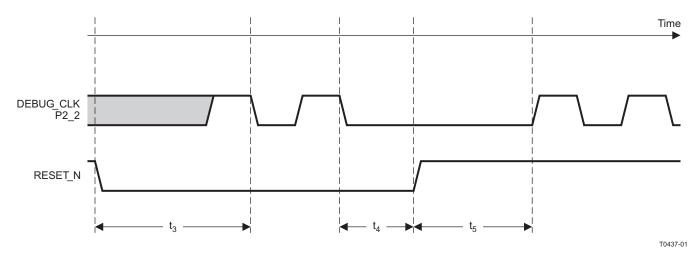
DEBUG INTERFACE AC CHARACTERISTICS

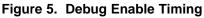
$T_A = -40$	$T_A = -40^{\circ}C$ to 85°C, VDD = 2 V to 3.6 V						
	PARAMETER	TEST CONDITIONS	MIN	ΤΥΡ ΜΑΧ	UNIT		
f _{clk_dbg}	Debug clock frequency (see Figure 4)			12	2 MHz		
t ₁	Allowed high pulse on clock (see Figure 4)		35		ns		
t ₂	Allowed low pulse on clock (see Figure 4)		35		ns		
t ₃	EXT_RESET_N low to first falling edge on debug clock (see Figure 5)		167		ns		
t ₄	Falling edge on clock to EXT_RESET_N high (see Figure 5)		83		ns		
t ₅	EXT_RESET_N high to first debug command (see Figure 5)		83		ns		
t ₆	Debug data setup (see Figure 6)		2		ns		
t ₇	Debug data hold (see Figure 6)		4		ns		
t ₈	Clock-to-data delay (see Figure 6)	Load = 10 pF		30) ns		



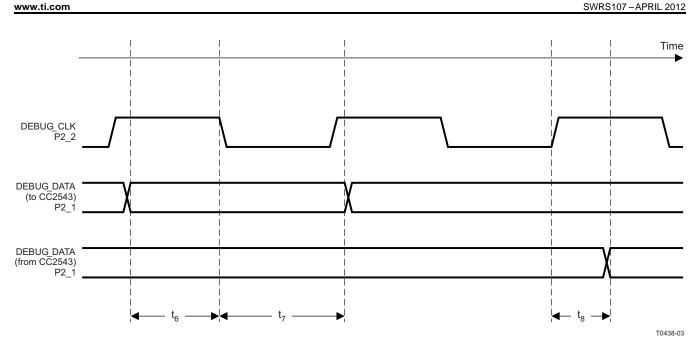
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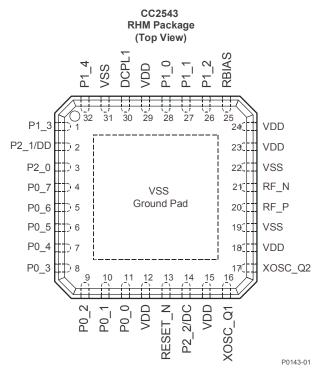
TIMER INPUTS AC CHARACTERISTICS

 $T_A = -40^{\circ}C$ to 85°C, VDD = 2 V to 3.6 V

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input capture pulse duration	Synchronizers determine the shortest input pulse that can be recognized. The synchronizers operate at the current system clock rate (16 MHz or 32 MHz).	1.5			t _{SYSCLK}

DEVICE INFORMATION

PIN DESCRIPTIONS



NOTE: The exposed ground pad must be connected to a solid ground plane; this is the main ground connection for the chip.

Table 1. Pin Description Table

NAME	PIN	PIN TYPE	DESCRIPTION
P1_3	1	Digital I/O	Port 1.3
P2_1/DD	2	Digital I/O / Debug	Port 2.1 / Debug Data
P2_0	3	Digital I/O	Port 2.0
P0_7	4	Digital I/O	Port 0.7
P0_6	5	Digital I/O	Port 0.6
P0_5	6	Digital I/O	Port 0.5
P0_4	7	Digital I/O	Port 0.4
P0_3	8	Digital I/O	Port 0.3
P0_2	9	Digital I/O	Port 0.2
P0_1	10	Digital I/O	Port 0.1
P0_0	11	Digital I/O	Port 0.0
VDD	12	Power (analog)	2-V-3.6V analog power-supply connection
RESET_N	13	Digital input	Reset, active-low
P2_2/DC	14	Digital I/O / Debug	Port 2.2 / Debug Clock
VDD	15	Power (analog)	2-V-3.6V analog power-supply connection
XOSC_Q1	16	Analog O	32-MHz crystal oscillator pin 1
XOSC_Q2	17	Analog O	32-MHz crystal oscillator pin 2
VDD	18	Power (analog)	2-V-3.6V analog power-supply connection
VSS	19	Unused pin	Connect to ground
RF_P	20	RF I/O	Positive RF input signal to LNA during RX Positive RF output signal from PA during TX

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NAME	PIN	PIN TYPE	DESCRIPTION
RF_N	21	RF I/O	Negative RF input signal to LNA during RX Negative RF output signal from PA during TX
VSS	22	Unused pin	Connect to ground
VDD	23	Power (analog)	2-V–3.6-V analog power-supply connection
VDD	24	Power (analog)	2-V–3.6-V analog power-supply connection
RBIAS	25	Analog I/O	External precision bias resistor for reference current
P1_2	26	Digital I/O	Port 1.2, 20 mA
P1_1	27	Digital I/O	Port 1.1, 20 mA
P1_0	28	Digital I/O	Port 1.0, 20 mA
VDD	29	Power (analog)	2-V–3.6-V analog power-supply connection
DCPL1	30	Power (digital)	1.8-V digital power-supply decoupling. Do not use for supplying external circuits.
VSS	31	Unused pin	Connect to ground
P1_4	32	Digital I/O	Port 1.4
VSS	Ground pad	Ground	Must be connected to solid ground as this is the main ground connection for the chip. See Pinout Diagram.

Table 1. Pin Description Table (continued)

BLOCK DIAGRAM

A block diagram of the CC2543 is shown in Figure 7. The modules can be roughly divided into one of three categories: CPU-related modules; modules related to power, test, and clock distribution; and radio-related modules. In the following subsections, a short description of each module is given. See CC2543/44/45 User's Guide (SWRU283) for more details.

CC2543 SWRS107 - APRIL 2012 TEXAS INSTRUMENTS

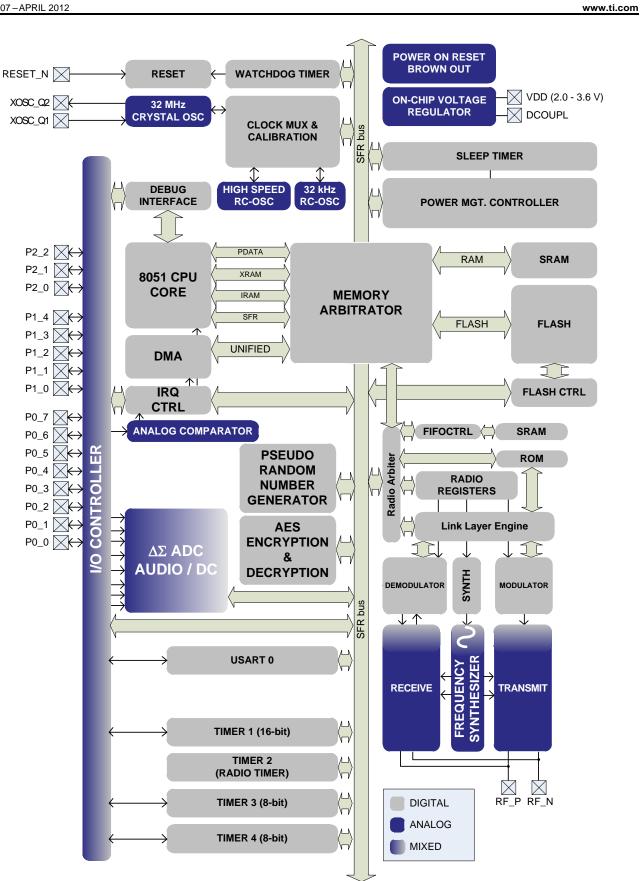


Figure 7. CC2543 Block Diagram



BLOCK DESCRIPTIONS

CPU and Memory

The **8051 CPU core** is a single-cycle 8051-compatible core. It has three different memory access busses (SFR, DATA, and CODE/XDATA), a debug interface, and an 15-input extended interrupt unit.

The **memory arbiter** is at the heart of the system, as it connects the CPU and DMA controller with the physical memories and all peripherals through the SFR bus. The memory arbiter has four memory-access points, access of which can map to one of three physical memories: an SRAM, flash memory, and XREG/SFR registers. It is responsible for performing arbitration and sequencing between simultaneous memory accesses to the same physical memory.

The **SFR bus** is drawn conceptually in Figure 7 as a common bus that connects all hardware peripherals to the memory arbiter. The SFR bus in the block diagram also provides access to the radio registers in the radio register bank, even though these are indeed mapped into XDATA memory space.

The 1-KB SRAM maps to the DATA memory space and to parts of the XDATA memory spaces.

The **18-KB/32-KB flash block** provides in-circuit programmable non-volatile program memory for the device, and maps into the CODE and XDATA memory spaces.

Peripherals

Writing to the flash block is performed through a **flash controller** that allows page-wise erasure and 4-bytewise programming. See User Guide for details on the flash controller.

A versatile two-channel **DMA controller** is available in the system, accesses memory using the XDATA memory space, and thus has access to all physical memories. Each channel (trigger, priority, transfer mode, addressing mode, source and destination pointers, and transfer count) is configured with DMA descriptors that can be located anywhere in memory. Many of the hardware peripherals (AES core, flash controller, USART, timers, etc.) can be used with the DMA controller for efficient operation by performing data transfers between a single SFR or XREG address and flash/SRAM.

The **interrupt controller** services a total of 17 interrupt sources, divided into six interrupt groups, each of which is associated with one of four interrupt priorities. Any interrupt service request is serviced also when the device is in idle mode by going back to active mode. Some interrupts can also wake up the device from sleep mode (when in sleep mode, the device is in low-power mode PM1, PM2 or PM3).

The **debug interface** implements a proprietary two-wire serial interface that is used for in-circuit debugging. Through this debug interface, it is possible to perform an erasure of the entire flash memory, control which oscillators are enabled, stop and start execution of the user program, execute supplied instructions on the 8051 core, set code breakpoints, and single-step through instructions in the code. Using these techniques, it is possible to perform in-circuit debugging and external flash programming elegantly.

The **I/O controller** is responsible for all general-purpose I/O pins. The CPU can configure whether peripheral modules control certain pins or whether they are under software control, and if so, whether each pin is configured as an input or output and if a pullup or pulldown resistor in the pad is connected. Each peripheral that connects to the I/O pins can choose between several different I/O pin locations to ensure flexibility in various applications.

The **sleep timer** is an ultralow-power timer that uses an internal 32.753-kHz RC oscillator. The sleep timer runs continuously in all operating modes. Typical applications of this timer are as a real-time counter or as a wake-up timer to get out of power modes 1 or 2.

A built-in **watchdog timer** allows the CC2543 to reset itself if the firmware hangs. When enabled by software, the watchdog timer must be cleared periodically; otherwise, it resets the device when it times out.

Timer 1 is a 16-bit timer with timer/counter/PWM functionality. It has a programmable prescaler, a 16-bit period value, and five individually programmable counter/capture channels, each with a 16-bit compare value. Each of the counter/capture channels can be used as a PWM output or to capture the timing of edges on input signals. It can also be configured in IR generation mode, where it counts timer 3 periods and the output is ANDed with the output of timer 3 to generate modulated consumer IR signals with minimal CPU interaction.

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Timer 2 is a 40-bit timer used by the Radio. It has a 16-bit counter with a configurable timer period and a 24-bit overflow counter that can be used to keep track of the number of periods that have transpired. A 40-bit capture register is also used to record the exact time at which a start-of-frame delimiter is received/transmitted or the exact time at which a packet ends. There are two 16-bit timer-compare registers and two 24-bit overflow-compare registers that can be used to give exact timing for start of RX or TX to the radio or general interrupts.

Timer 3 and timer 4 are 8-bit timers with timer/counter/PWM functionality. They have a programmable prescaler, an 8-bit period value, and one programmable counter channel with an 8-bit compare value. Each of the counter channels can be used as PWM output.

USART 0 is configurable as either an SPI master/slave or a UART. It provides double buffering on both RX and TX and hardware flow control and is thus well suited to high-throughput full-duplex applications. The USART has its own high-precision baud-rate generator, thus leaving the ordinary timers free for other uses. When configured as SPI slaves, the USART samples the input signal using SCK directly instead of using some oversampling scheme, and are thus well-suited for high data rates.

The **I**²**C** module provides a digital peripheral connection with two pins and supports both master and slave operation.

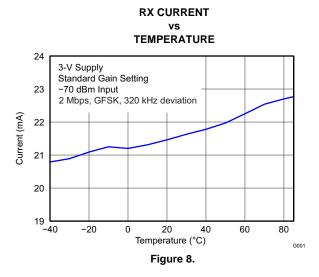
The **ADC** supports 7 bits (30 kHz bandwidth) to 12 bits (4 kHz bandwidth) of resolution. DC and audio conversions with up to eight input channels (Port 0) are possible. The inputs can be selected as single-ended or differential. The reference voltage can be internal, AVDD, or a single-ended or differential external signal. The ADC also has a temperature-sensor input channel. The ADC can automate the process of periodic sampling or conversion over a sequence of channels.

The **AES encryption/decryption core** allows the user to encrypt and decrypt data using the AES algorithm with 128-bit keys. The AES core also supports ECB, CBC, CFB, OFB, CTR, and CBC-MAC, as well as hardware support for CCM.

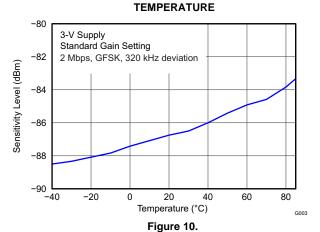
The ultralow-power **analog comparator** enables applications to wake up from PM2 or PM3 based on an analog signal. Both inputs are brought out to pins; the reference voltage must be provided externally. The comparator output is mapped into the digital I/O port and can be treated by the MCU as a regular digital input.



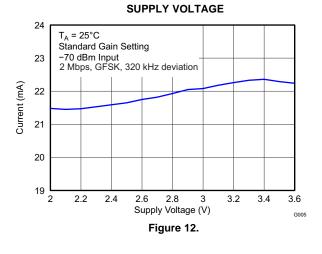


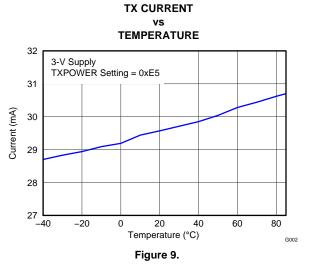


RX SENSITIVITY vs

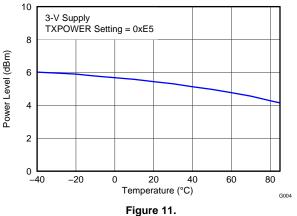


RX CURRENT vs

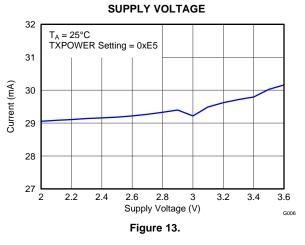




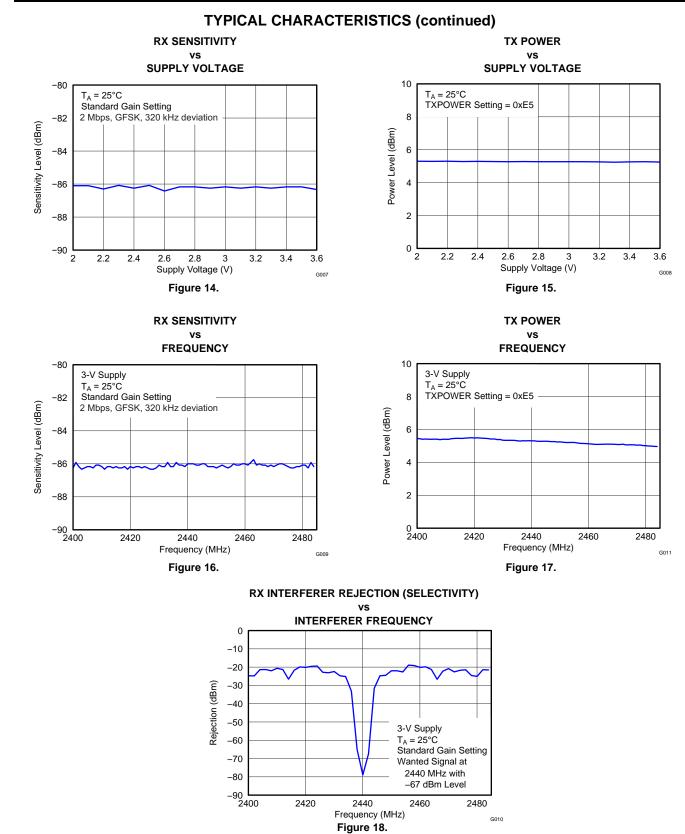
TX POWER vs TEMPERATURE



TX CURRENT vs



PRODUCT PREVIEW





TYPICAL CHARACTERISTICS (continued) Table 2. Recommended Output Power Settings⁽¹⁾

TXPOWER Register Setting	Typical Output Power (dBm)
0xE5	5
0xD5	4
0xC5	3
0xB5	2
0xA5	0
0x95	-2
0x85	-3
0x75	-4
0x65	-6
0x55	-8
0x45	-11
0x35	-13
0x25	-15
0x15	-17
0x05	-20

 Measured on Texas Instruments CC2543 EM reference design with TA = 25°C, VDD = 3 V and fc = 2440 MHz. See SWRU283 for recommended register settings.

APPLICATION INFORMATION

Few external components are required for the operation of the CC2543. A typical application circuit is shown in Figure 19. For suggestions of component values other than those listed in Table 3, see reference design CC2543EM. The performance stated in this data sheet is only valid for the CC2543EM reference design. To obtain similar performance, the reference design should be copied as closely as possible.

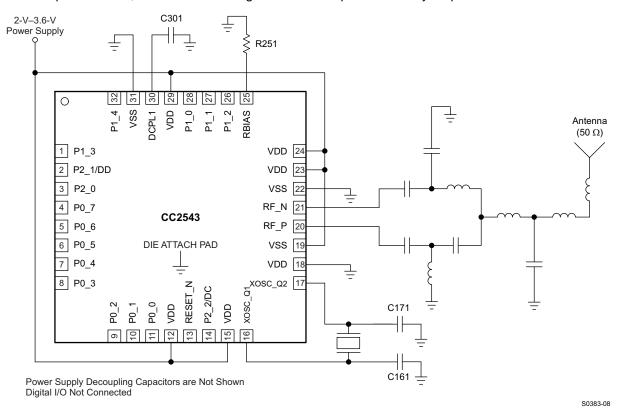


Figure 19. CC2543 Application Circuit

Table 3. Overview of External Components (Excluding Balun, Crystal and Supply Decoupling Capacitors)

COMPONENT	DESCRIPTION	VALUE
C301	Decoupling capacitor for the internal 1.8V digital voltage regulator	1 µF
R251	Precision resistor ±1%, used for internal biasing	56 kΩ

Input/Output Matching

When using an unbalanced antenna such as a monopole, a balun should be used to optimize performance. The balun can be implemented using low-cost discrete inductors and capacitors. See reference design, CC2543EM, for recommended balun.



Crystal

An external 32-MHz crystal with two loading capacitors is used for the 32-MHz crystal oscillator. The load capacitance seen by the 32-MHz crystal is given by:

$$C_{L} = \frac{1}{\frac{1}{C_{161}} + \frac{1}{C_{171}}} + C_{\text{parasitic}}$$
(1)

A series resistor may be used to comply with ESR requirement.

On-Chip 1.8-V Voltage Regulator Decoupling

The 1.8-V on-chip voltage regulator supplies the 1.8-V digital logic. This regulator requires a decoupling capacitor (C301) for stable operation.

Power-Supply Decoupling and Filtering

Proper power-supply decoupling must be used for optimum performance. The placement and size of the decoupling capacitors and the power supply filtering are very important to achieve the best performance in an application. TI provides a compact reference design that should be followed very closely.



PACKAGING INFORMATION

Orderable Device	Status ⁽¹⁾	Package Type	Package Drawing	Pins	Package Qty	Eco Plan ⁽²⁾	Lead/ Ball Finish	MSL Peak Temp ⁽³⁾	Samples (Requires Login)
CC2543RHMR	ACTIVE	QFN	RHM	32	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	
CC2543RHMT	ACTIVE	QFN	RHM	32	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

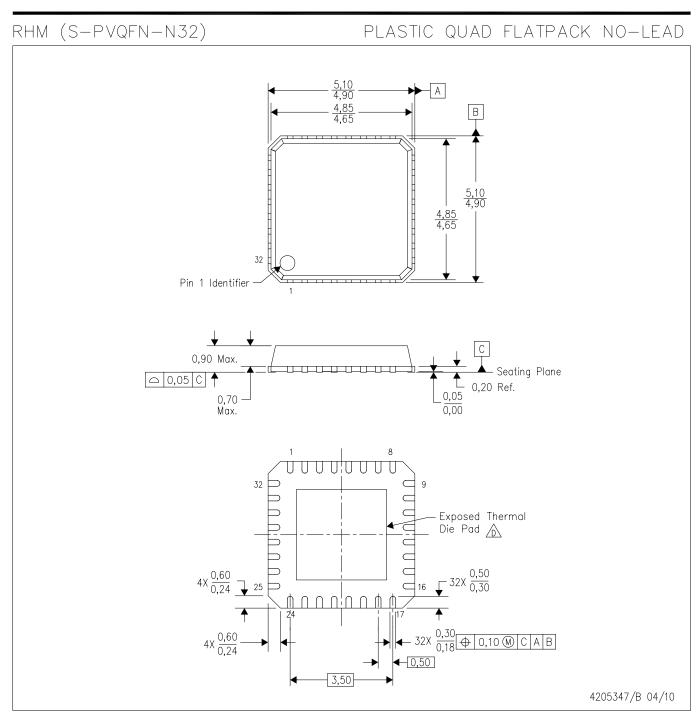
Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

⁽³⁾ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. QFN (Quad Flatpack No-Lead) Package configuration.

The package thermal pad must be soldered to the board for thermal and mechanical performance. See the Product Data Sheet for details regarding the exposed thermal pad dimensions.



THERMAL PAD MECHANICAL DATA

RHM (S-PVQFN-N32)

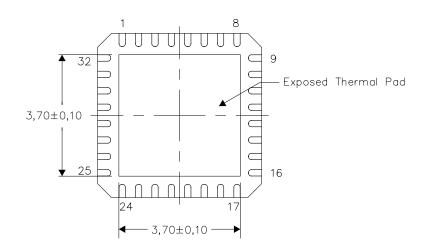
PLASTIC QUAD FLATPACK NO-LEAD

THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.





NOTE: All linear dimensions are in millimeters

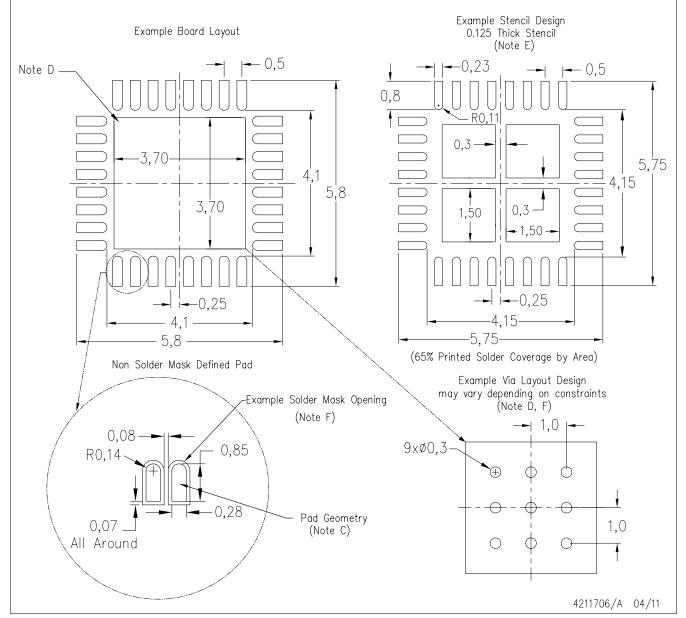
Exposed Thermal Pad Dimensions



4210977-3/A 06/10

RHM (S-PVQFN-N32)

PLASTIC QUAD FLATPACK NO-LEAD



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat-Pack Packages, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com http://www.ti.com.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
- F. Customers should contact their board fabrication site for recommended solder mask tolerances and via tenting recommendations for vias placed in the thermal pad.



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