

3.3-V PHASE-LOCK LOOP CLOCK DRIVER WITH 3-STATE OUTPUTS

FEATURES

- Low Output Skew for Clock-Distribution and Clock-Generation Applications
- Operates at 3.3-V V_{CC}
- **Distributes One Clock Input to 12** Outputs
- **Two Select Inputs Configure Up to Nine Outputs to Operate at One-Half or Double** the Input Frequency
- No External RC Network Required
- **External Feedback (FBIN) Synchronizes the** . **Outputs to the Clock Input**

- Application for Synchronous DRAM, • **High-Speed Microprocessor**
- **TTL-Compatible Inputs and Outputs**
- **Outputs Have Internal 26-** Ω Series • **Resistors to Dampen Transmission-Line** Effects
- State-of-the-Art *EPIC-IIB*[™] BiCMOS Design Significantly Reduces Power Dissipation
- Distributed V_{CC} and Ground Pins Reduce Switching Noise
- Packaged in 52-Pin Thin Quad Flat Package



NC - No internal connection

DESCRIPTION

The CDC2586 is a high-performance, low-skew, low-jitter clock driver. It uses a phase-lock loop (PLL) to precisely align, in both frequency and phase, the clock output signals to the clock input (CLKIN) signal. It is specifically designed for use with popular microprocessors operating at speeds from 50 MHz to 100 MHz or down to 25 MHz on outputs configured for half-frequency operation. Each output has an internal 26- Ω series resistor that improves the signal integrity at the load. The CDC2586 operates at nominal 3.3-V V_{CC} .

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The feedback input (FBIN) synchronizes the output clocks in frequency and phase to CLKIN. One of the twelve output clocks must be fed back to FBIN for the PLL to maintain synchronization between CLKIN and the outputs. The output used as feedback is synchronized to the same frequency as CLKIN.

The Y outputs can be configured to switch in phase and at the same frequency as CLKIN. Select inputs (SEL1, SEL0) configure up to nine Y outputs, in banks of three, to operate at one-half or double the CLKIN frequency depending on which output is fed back to FBIN (see Table 1 and Table 2). All output signal duty cycles are adjusted to 50% independent of the duty cycle at CLKIN.

Output-enable (\overline{OE}) provides output control. When \overline{OE} is high, the outputs are in the high-impedance state. When \overline{OE} is low, the outputs are active. TEST is used for factory testing of the device and can be used to bypass the PLL. TEST should be strapped to GND for normal operation.

Unlike many products containing PLLs, the CDC2586 does not require external RC networks. The loop filter for the PLL is included on-chip, minimizing component count, board space, and cost.

Because it is based on PLL circuitry, the CDC2586 requires a stabilization time to achieve phase lock of the feedback signal to the reference signal. This stabilization time is required following power up and application of a fixed-frequency, fixed-phase signal at CLKIN, as well as following any changes to the PLL reference or feedback signals. Such changes occur upon change of the select inputs, enabling of the PLL via TEST, and upon enable of all outputs via OE.

The CDC2586 is characterized for operation from 0°C to 70°C.

DETAILED DESCRITPION OF OUTPUT CONFIGURATIONS

The voltage-controlled oscillator (VCO) used in the CDC2586 PLL has a frequency range of 100 MHz to 200 MHz, twice the operating frequency range of the CDC2586 outputs. The output of the VCO is divided by two and four to provide reference frequencies with a 50% duty cycle of one-half and one-fourth the VCO frequency. The SEL0 and SEL1 inputs select which of the two signals are buffered to each bank of device outputs.

One device output must be externally wired to FBIN to complete the PLL. The VCO operates such that the frequency and phase of this output matches that of the CLKIN signal. In the case that a VCO/2 output is wired to FBIN, the VCO must operate at twice the CLKIN frequency resulting in device outputs that operate at either the same or one-half the CLKIN frequency. If a VCO/4 output is wired to FBIN, the device outputs operate at twice or the same as the CLKIN frequency.

Output Configuration A

Output configuration A is valid when any output configured as a 1x frequency output in Table 1 is fed back to FBIN. The input frequency range for CLKIN is 50 MHz to 100 MHz when using output configuration A. Outputs configured as 1/2 outputs operate at half the CLKIN frequency, while outputs configured as 1x outputs operate at the same frequency as CLKIN.

INPUTS		OUTPUTS		
SEL1	SEL0	1/2× FREQUENCY	1× FREQUENCY	
L	L	None	All	
L	Н	1Yn	2Yn, 3Yn, 4Yn	
н	L	1Yn, 2Yn	3Yn, 4Yn	
н	Н	1Yn, 2Yn, 3Yn	4Yn	

Table 1. Output Configuration A⁽¹⁾

(1) n = 1, 2, 3

Output Configuration B

Output configuration B is valid when any output configured as a 1x frequency output in Table 2 is fed back to FBIN. The input frequency range for CLKIN is 25 MHz to 50 MHz when using output configuration B. Outputs configured as 1x outputs operate at the CLKIN frequency, while outputs configured as 2x outputs operate at double the frequency of CLKIN.

INPUTS		OUTPUTS		
SEL1	SEL0	1× FREQUENCY	2× FREQUENCY	
L	L	All	None	
L	Н	1Yn	2Yn, 3Yn, 4Yn	
н	L	1Yn, 2Yn	3Yn, 4Yn	
н	Н	1Yn, 2Yn, 3Yn	4Yn	

Table 2. Output Configuration B⁽¹⁾

(1) n = 1, 2, 3



FUNCTIONAL BLOCK DIAGRAM





Terminal Functions

TERMINAL		1/0	DECORIDE	
NAME	NO.	1/0	DESCRIPTION	
CLKIN	45	I	Clock input. CLKIN is the clock signal to be distributed by the CDC2586 clock-driver circuit. CLKIN provides the reference signal to the integrated PLL that generates the clock output signals. CLKIN must have a fixed frequency and fixed phase for the PLL to obtain phase lock. Once the circuit is powered up and a valid CLKIN signal is applied, a stabilization time is required for the PLL to phase lock the feedback signal to its reference signal.	
CLR	40	I	CLR is used for testing purposes only.	
FBIN	48	I	Feedback input. FBIN provides the feedback signal to the internal PLL. FBIN must be hardwired to one of the 12 clock outputs to provide frequency and phase lock. The internal PLL adjusts the output clocks to obtain zero phase delay between FBIN and CLKIN.	
OE	42	I	Output enable. \overline{OE} is the output enable for all outputs. When \overline{OE} is low, all outputs are enabled. When \overline{OE} is high, all outputs are in the high-impedance state. Since the feedback signal for the PLL is taken directly from an output, placing the outputs in the high-impedance state interrupts the feedback loop; therefore, when a high-to-low transition occurs at \overline{OE} , enabling the output buffers, a stabilization time is required before the PLL obtains phase lock.	
SEL1, SEL0	51, 50	I	Output configuration select. SEL0 and SEL1 select the output configuration for each output bank (e.g., $1/2\times$, $1\times$, or $2\times$) (see Table 1 and Table 2).	
TEST	41	I	TEST is used to bypass the PLL circuitry for factory testing of the device. When TEST is low, all outputs operate using the PLL circuitry. When TEST is high, the outputs are placed in a test mode that bypasses the PLL circuitry. TEST should be strapped to GND for normal operation.	
1Y1-1Y3 2Y1-2Y3 3Y1-3Y3	2, 5, 8 12, 15, 18 22, 25, 28	0	Output ports. These outputs are configured by the select inputs (SEL1, SEL0) to transmit one-half or one-fourth the frequency of the VCO. The relationship between the CLKIN frequency and the output frequency is dependent on the select inputs and the frequency of the output being fed back to FBIN (see Table 1 and Table 2). The duty cycle of the Y output signals is nominally 50%, independent of the duty cycle of CLKIN. Each output has an internal series resistor to dampen transmission-line effects and improve the signal integrity at the load.	
4Y1-4Y3	32, 35, 38	0	Output ports. 4Y1-4Y3 transmit one-half the frequency of the VCO regardless of the state of the select inputs. The relationship between the CLKIN frequency and the output frequency is dependent on the frequency of the output being fed back to FBIN (see Table 1 and Table 2). The duty cycle of the Y output signals is nominally 50%, independent of the duty cycle of CLKIN. Each output has an internal series resistor to dampen transmission-line effects and improve the signal integrity at the load.	

ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range (unless otherwise noted) ⁽¹⁾

	UNIT
Supply voltage range, V _{CC}	-0.5 V to 4.6 V
Input voltage range, VI ⁽²⁾	-0.5 V to 7 V
Voltage range applied to any output in the high state or power-off state, $V_0^{(2)}$	-0.5 V to 5.5 V
Current into any output in the low state, I _O	24 mA
Input clamp current, I _{IK} (V _I < 0)	-20 mA
Output clamp current, I _{OK} (V _O < 0)	-50 mA
Maximum power dissipation at $T_A = 55^{\circ}C$ (in still air) ⁽³⁾	1.2 W
Storage temperature range, T _{stg}	-65°C to 150°C

Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
The input and output negative-voltage ratings may be exceeded if the input and output clamp-current ratings are observed.

(2) The input and output negative-voltage ratings may be exceeded if the input and output clamp-current ratings are observed.
(3) The maximum package power dissipation is calculated using a junction temperature of 150°C and a board trace length of 75 mils. For more information, see the *Package Thermal Considerations* application note in the *ABT Advanced BiCMOS Technology Data Book*, literature number SCBD002.



RECOMMENDED OPERATING CONDITIONS ⁽¹⁾

		MIN	MAX	UNIT
V _{CC}	Supply voltage	3	3.6	V
V _{IH}	High-level input voltage	2		V
V _{IL}	Low-level input voltage		0.8	V
VI	Input voltage	0	5.5	V
I _{OH}	High-level output current		-12	mA
I _{OL}	Low-level output current		12	mA
T _A	Operating free-air temperature	0	70	°C

(1) Unused inputs must be held high or low to prevent them from floating.

ELECTRICAL CHARACTERISTICS

over recommended operating free-air temperature range (unless otherwise noted)

DADAMETED	TEST CONDITIONS		T _A = 25°C			
PARAMETER			MIN	MAX		
V _{IK}	V _{CC} = 3 V,	I _I = -18 mA		-1.2	V	
N/	$V_{CC} = MIN$ to MAX ⁽¹⁾ ,	I _{OH} = -100 μA	V _{CC} -0.2		V	
V OH	V _{CC} = 3 V,	I _{OH} = -12 mA	2		v	
V		I _{OL} = 100 μA		0.2	V	
VOL	$v_{\rm CC} = 3 v$	I _{OL} = 12 mA		0.8	v	
	$V_{CC} = 0,$	V ₁ = 3.6 V		±10		
'1	V _{CC} = 3.6 V,	$V_{I} = V_{CC}$ or GND		±1	μΑ	
I _{OZH}	V _{CC} = 3.6 V,	$V_0 = 3 V$		10	μA	
I _{OZL}	V _{CC} = 3.6 V,	$V_{O} = 0$		-10	μA	
		Outputs high		1		
I _{cc}		Outputs low		1	mA	
		Outputs disabled		1		
C _i	$V_{I} = V_{CC}$ or GND			4	pF	
C _o	$V_0 = V_{CC}$ or GND			8	pF	

(1) For conditions shown as MIN or MAX, use the appropriate value specified under recommended operating conditions.

TIMING REQUIREMENTS

over recommended ranges of supply voltage and operating free-air temperature

			MIN	MAX	UNIT
f _{clock}	Clock frequency	VCO operating at four times the CLKIN frequency	25	50	NAL I-
	Clock frequency	VCO operating at double the CLKIN frequency	50	100	
	Input clock duty cycle		40%	60%	
Stabilization time ⁽¹⁾		After SEL1, SEL0		50	
	Stabilization time ⁽¹⁾	After OE↓		50	μs
		After power up		50	
		After CLKIN		50	

(1) Time required for the integrated PLL circuit to obtain phase lock of its feedback signal to its reference signal. In order for phase lock to be obtained, a fixed-frequency, fixed-phase reference signal must be present at CLKIN. Until phase lock is obtained, the specifications for propagation delay and skew parameters given in the *switching characteristics*table are not applicable.



SWITICHING CHARACTERISTICS

over recommended ranges of supply voltage and operating free-air temperature, $C_L = 15 \text{ pF}$ (see ⁽¹⁾ and Figure 1 through Figure 3)

PARAMETER	FROM (INPUT)	TO (OUTPUT)	MIN	MAX	UNIT
f _{max}				100	MHz
Duty cycle		Y	45%	55%	
t _{phase error} ⁽²⁾	CLKIN↑	Y↑	-500	+500	ps
jitter	CLKIN↑	Y↑		200	ps
t _{sk(o)} ⁽²⁾				0.5	ns
t _{sk(pr)} ⁽²⁾				1	ns
tr				1.4	ns
t _f				1.4	ns

(1) The specifications for parameters in this table are applicable only after any appropriate stabilization time has elapsed.

(2) The propagation delay, t_{phase error}, is dependent on the feedback path from any output to FBIN. The t_{phase error}, t_{sk(o)}, and t_{sk(pr)} specifications are valid only for equal loading of all outputs.

PARAMETER MEASUREMENT INFORMATION



- A. C_L includes probe and jig capacitance.
- B. All input pulses are supplied by generators having the following characteristics: PRR \leq 100 MHz, Z_O = 50 Ω , t_r \leq 2.5 ns, t_f \leq 2.5 ns.
- C. The outputs are measured one at a time with one transition per measurement.

Figure 1. Load Circuit and Voltage Waveforms



PARAMETER MEASUREMENT INFORMATION (continued)



- The difference between the fastest and slowest of t_{phase error n} (n = 1, 2, ... 6)
- The difference between the fastest and slowest of $t_{phase error n}$ (n = 7, 8, 9)
- B. Process skew, $t_{sk(pr)}$, is calculated as the greater of:
 - The difference between the maximum and minimum t_{phase error n} (n = 1, 2, ... 6) across multiple devices under identical operating conditions
 - The difference between the maximum and minimum t_{phase error n} (n = 7, 8, 9) across multiple devices under identical operating conditions
- C. For configuration A, see Table 1

Figure 2. Waveforms for Calculation of t_{sk(o)}for Configuration A

PARAMETER MEASUREMENT INFORMATION (continued)



- The difference between the fastest and slowest of $t_{phase error n}$ (n = 10, 11, . . . 15)
- B. Process skew, t_{sk}(pr), is calculated as the greater of:
 - The difference between the maximum and minimum $t_{phase error n}$ (n = 10, 11, ... 15) across multiple devices under identical operating conditions
- C. For configuration B, see Table 2

Figure 3. Waveforms for Calculation of t_{sk(o)}for Configuration B

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