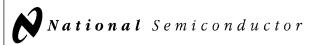
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TP3064, TP3067 "Enhanced" Serial Interface **CMOS CODEC/Filter COMBO®**

General Description

The TP3064 (µ-law) and TP3067 (A-law) are monolithic PCM CODEC/Filters utilizing the A/D and D/A conversion architecture shown in Figure 1, and a serial PCM interface. The devices are fabricated using National's advanced double-poly CMOS process (microCMOS).

Similar to the TP305X family, these devices feature an additional Receive Power Amplifier to provide push-pull balanced output drive capability. The receive gain can be adjusted by means of two external resistors for an output level of up to $\pm 6.6V$ across a balanced 600 Ω load.

Also included is an Analog Loopback switch and a $\overline{\text{TS}_{X}}$ output.

See also AN-370, "Techniques for Designing with CODEC/ Filter COMBO Circuits."

Features

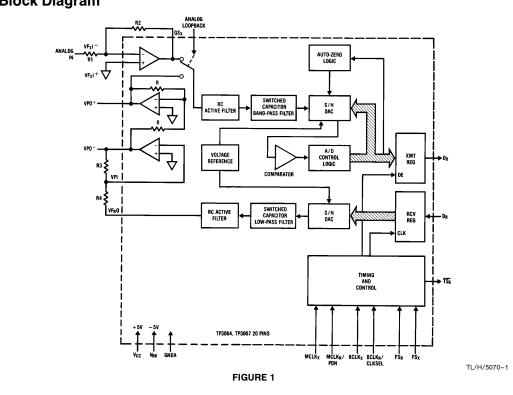
- Complete CODEC and filtering system including: - Transmit high-pass and low-pass filtering - Receive low-pass filter with sin x/x correction
 - Active RC noise filters
 - μ -law or A-law compatible COder and DECoder
 - Internal precision voltage reference
 - Serial I/O interface
 - Internal auto-zero circuitry
- Receive push-pull power amplifiers μ-law—TP3064
- A-law—TP3067
- Designed for D3/D4 and CCITT applications
- ±5V operation
 - Low operating power-typically 70 mW
 - Power-down standby mode-typically 3 mW
 - Automatic power-down
- TTL or CMOS compatible digital interfaces
- Maximizes line interface card circuit density

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Block Diagram

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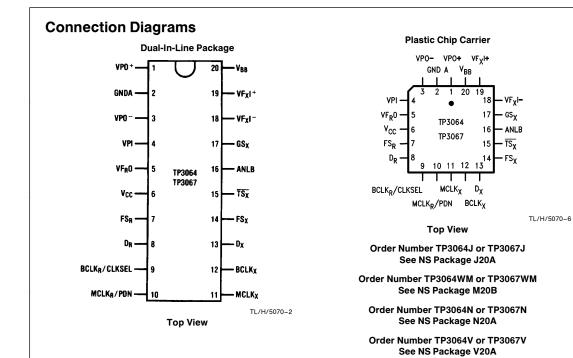
TL/H/5070



RRD-B30M115/Printed in U. S. A.

TP3064, TP3067 "Enhanced" Serial Interface CMOS CODEC/Filter COMBC

October 1991



Pin Description

Symbol	Function	Symbol MCLK _X	Function Transmit master clock. Must be 1.536 MHz.
VPO+	The non-inverted output of the receive power amplifier.	MCLKX	1.544 MHz or 2.048 MHz. May be asynchronous with MCLK _B . Best
GNDA	Analog ground. All signals are referenced to this pin.		performance is realized from synchronous operation.
VPO-	The inverted output of the receive power amplifier.	BCLKX	The bit clock which shifts out the PCM data on D_X . May vary from 64 kHz to 2.048 MHz,
VPI	Inverting input to the receive power amplifier.		but must be synchronous with MCLKX.
VF _R O V _{CC}	Analog output of the receive filter. Positive power supply pin. $V_{CC} = +5V \pm 5\%$.	D_X	The TRI-STATE [®] PCM data output which is enabled by FS _X .
FS _R	Receive frame sync pulse which enables $BCLK_R$ to shift PCM data into D_R . FS _R is an 8 kHz pulse train. See <i>Figures 2</i> and 3 for timing details.	FS _X	Transmit frame sync pulse input which enables $BCLK_X$ to shift out the PCM data on D_X . FS _X is an 8 kHz pulse train, see <i>Figures 2</i> and <i>3</i> for timing details.
D _R	Receive data input. PCM data is shifted into D_{R} following the FS_{R} leading edge.	TSX	Open drain output which pulses low during the encoder time slot.
BCLK _R / CLKSEL	The bit clock which shifts data into D_R after the FS _R leading edge. May vary from 64 kHz to 2.048 MHz. Alternatively, may be a logic input which selects either 1.536 MHz/1.544 MHz or 2.048 MHz for master clock in synchronous mode and	ANLB	Analog Loopback control input. Must be set to logic '0' for normal operation. When pulled to logic '1', the transmit filter input is disconnected from the output of the transmit preamplifier and connected to the VPO ⁺ output of the receive power amplifier.
	$BCLK_X$ is used for both transmit and receive directions (see Table I).	GS _X	Analog output of the transmit input amplifier. Used to externally set gain.
MCLK _R /	Receive master clock. Must be 1.536 MHz,	VF_XI^-	Inverting input of the transmit input amplifier.
PDN	1.544 MHz or 2.048 MHz. May be asynchronous with MCLK _X , but should be	VF_XI^+	Non-inverting input of the transmit input amplifier.
	synchronous with MCLK _X for best performance. When MCLK _R is connected continuously low, MCLK _X is selected for all internal timing. When MCLK _R is connected continuously high, the device is powered down.	V _{BB}	Negative power supply pin. V_{BB} = $-5V\pm5\%$.

Functional Description

POWER-UP

When power is first applied, power-on reset circuitry initializes the COMBOTM and places it into a power-down state. All non-essential circuits are deactivated and the D_X, VF_RO, VPO⁻ and VPO⁺ outputs are put in high impedance states. To power-up the device, a logical low level or clock must be applied to the MCLK_R/PDN pin *and* FS_X and/or FS_R pulses must be present. Thus, 2 power-down control modes are available. The first is to pull the MCLK_R/PDN pin high; the alternative is to hold both FS_X and FS_R inputs continuously low—the device will power-down approximately 2 ms after the last FS_X or FS_R pulse. Power-up will occur on the first FS_X or FS_R pulse. The TRI-STATE PCM data output, D_X, pulse.

SYNCHRONOUS OPERATION

For synchronous operation, the same master clock and bit clock should be used for both the transmit and receive directions. In this mode, a clock must be applied to MCLK_X and the MCLK_R/PDN pin can be used as a power-down control. A low level on MCLK_R/PDN powers up the device and a high level powers down the device. In either case, MCLK_X will be selected as the master clock for both the transmit and receive circuits. A bit clock must also be applied to BCLK_X and the BCLK_R/CLKSEL can be used to select the proper internal divider for a master clock of 1.536 MHz, 1.544 MHz or 2.048 MHz. For 1.544 MHz operation, the device automatically compensates for the 193rd clock pulse each frame.

With a fixed level on the BCLK_R/CLKSEL pin, BLCK_X will be selected as the bit clock for both the transmit and receive directions. Table I indicates the frequencies of operation which can be selected, depending on the state of BCLK_R/CLKSEL. In this synchronous mode, the bit clock, BCLK_X, may be from 64 kHz to 2.048 MHz, but must be synchronous with MCLK_X.

Each FS_X pulse begins the encoding cycle and the PCM data from the previous encode cycle is shifted out of the enabled D_X output on the positive edge of BCLK_X. After 8 bit clock periods, the TRI-STATE D_X output is returned to a high impedance state. With an FS_R pulse, PCM data is latched via the D_R input on the negative edge of BCLK_X (or BCLK_R if running). FS_X and FS_R must be synchronous with MCLK_{X/R}.

TABLE I. Selection of Master Clock Frequencies

BCLK _R /CLKSEL		r Clock y Selected
BOENR/ DENOLE	TP3067	TP3064
Clocked	2.048 MHz	1.536 MHz or
		1.544 MHz
0	1.536 MHz or	2.048 MHz
	1.544 MHz	
1	2.048 MHz	1.536 MHz or
		1.544 MHz

ASYNCHRONOUS OPERATION

For asynchronous operation, separate transmit and receive clocks may be applied. $\rm MCLK_X$ and $\rm MCLK_R$ must be 2.048 MHz for the TP3067, or 1.536 MHZ, 1.544 MHz for the TP3064, and need not be synchronous. For best transmis-

sion performance, however, MCLK_R should be synchronous with MCLK_X, which is easily achieved by applying only static logic levels to the MCLK_R/PDN pin. This will automatically connect MCLK_X to all internal MCLK_R functions (see Pin Description). For 1.544 MHz operation, the device automatically compensates for the 193rd clock pulse each frame. FS_X starts each encoding cycle and must be synchronous with MCLK_X and BCLK_X. FS_R starts each decoding cycle and must be synchronous with BCLK_R. BCLK_R must be a clock, the logic levels shown in Table I are not valid in asynchronous mode. BCLK_X and BCLK_R may operate from 64 kHz to 2.048 MHz.

SHORT FRAME SYNC OPERATION

The COMBO can utilize either a short frame sync pulse (the same as the TP3020/21 CODECs) or a long frame sync pulse. Upon power initialization, the device assumes a short frame mode. In this mode, both frame sync pulses, FS_X and FS_R, must be one bit clock period long, with timing relationships specified in Figure 2. With FS_X high during a falling edge of $BCLK_X$, the next rising edge of $BCLK_X$ enables the Dy TRI-STATE output buffer, which will output the sign bit. The following seven rising edges clock out the remaining seven bits, and the next falling edge disables the DX output. With FS_R high during a falling edge of BCLK_R (BCLK_X in synchronous mode), the next falling edge of BCLK_R latches in the sign bit. The following seven falling edges latch in the seven remaining bits. All devices may utilize the short frame sync pulse in synchronous or asynchronous operating mode.

LONG FRAME SYNC OPERATION

To use the long (TP5116A/56 CODECs) frame mode, both the frame sync pulses, FS_X and FS_R, must be three or more bit clock periods long, with timing relationships specified in Figure 3. Based on the transmit frame sync, FS_X, the COM-BO will sense whether short or long frame sync pulses are being used. For 64 kHz operation, the frame sync pulse must be kept low for a minimum of 160 ns. The D_X TRI-STATE output buffer is enabled with the rising edge of FSX or the rising edge of BCLK_X, whichever comes later, and the first bit clocked out is the sign bit. The following seven BCLK_X rising edges clock out the remaining seven bits. The D_X output is disabled by the falling BCLK_X edge following the eighth rising edge, or by FS_X going low, whichever comes later. A rising edge on the receive frame sync pulse, FS_R, will cause the PCM data at D_R to be latched in on the next eight falling edges of BCLK_B(BCLK_X in synchronous mode). All devices may utilize the long frame sync pulse in synchronous or asynchronous mode.

TRANSMIT SECTION

The transmit section input is an operational amplifier with provision for gain adjustment using two external resistors, see *Figure 4*. The low noise and wide bandwidth allow gains in excess of 20 dB across the audio passband to be realized. The op amp drives a unity-gain filter consisting of RC active pre-filter, followed by an eighth order switched-capacitor bandpass filter clocked at 256 kHz. The output of this filter directly drives the encoder sample-and-hold circuit. The A/D is of companding type according to μ -law (TP3064) or A-law (TP3067) coding conventions. A precision voltage reference is trimmed in manufacturing to provide an input overload (t_{MAX}) of nominally 2.5V peak (see

Functional Description (Continued)

table of Transmission Characteristics). The FS_X frame sync pulse controls the sampling of the filter output, and then the successive-approximation encoding cycle begins. The 8-bit code is then loaded into a buffer and shifted out through D_X at the next FS_X pulse. The total encoding delay will be approximately 165 μs (due to the transmit filter) plus 125 μs (due to encoding delay), which totals 290 μs . Any offset voltage due to the filters or comparator is cancelled by sign bit integration.

RECEIVE SECTION

The receive section consists of an expanding DAC which drives a fifth order switched-capacitor low pass filter clocked at 256 kHz. The decoder is A-law (TP3067) or μ -law (TP3064) and the 5th order low pass filter corrects for the sin x/x attenuation due to the 8 kHz sample/hold. The filter is then followed by a 2nd order RC active post-filter with its output at VF_RO. The receive section is unity-gain, but gain can be added by using the power amplifiers. Upon the occurrence of FS_R, the data at the D_R input is clocked in on the falling edge of the next eight BCLK_R (BCLK_X) peri-

ods. At the end of the decoder time slot, the decoding cycle begins, and 10 μ s later the decoder DAC output is updated. The total decoder delay is ~10 μ s (decoder update) plus 110 μ s (filter delay) plus 62.5 μ s (½ frame), which gives approximately 180 μ s.

RECEIVE POWER AMPLIFIERS

Two inverting mode power amplifiers are provided for directly driving a matched line interface transformer. The gain of the first power amplifier can be adjusted to boost the $\pm 2.5V$ peak output signal from the receive filter up to $\pm 3.3V$ peak into an unbalanced 300 Ω load, or $\pm 4.0V$ into an unbalanced anced 15 k Ω load. The second power amplifier is internally connected in unity-gain inverting mode to give 6 dB of signal gain for balanced loads.

Maximum power transfer to a 600 Ω subscriber line termination is obtained by differentially driving a balanced transformer with a $\sqrt{2}$:1 turns ratio, as shown in *Figure 4*. A total peak power of 15.6 dBm can be delivered to the load plus termination.

ENCODING FORMAT AT D_X OUTPUT

				ΤΡ3 μ-L						(1	nclude	A-L	3067 ∟aw n Bit In	versio	n)	
V _{IN} = +Full-Scale	1	0	0	0	0	0	0	0	1	0	1	0	1	0	1	0
$V_{IN} = 0V$	∫1	1	1	1	1	1	1	1	1	1	0	1	0	1	0	1
	lo	1	1	1	1	1	1	1	0	1	0	1	0	1	0	1
$V_{IN} = -Full-Scale$	0	0	0	0	0	0	0	0	0	0	1	0	1	0	1	0

Absolute Maximum Ratings

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

V _{CC} to GNDA	7V
V _{BB} to GNDA	-7V
Voltage at any Analog Input	
or Output	$V_{CC}\!+\!0.3V$ to $V_{BB}\!-\!0.3V$

Voltage at any Digital Input or Output	V _{CC} +0.3V to GNDA-0.3V
Operating Temperature Range	-25°C to +125°C
Storage Temperature Range	-65°C to +150°C
Lead Temp. (Soldering, 10 sec.)	300°C
ESD (Human Body Model) J	1000V
ESD (Human Body Model) N	1500V
Latch-Up Immunity	100 mA on Any Pin

Electrical Characteristics Unless otherwise noted, limits printed in **BOLD** characters are guaranteed for $V_{CC} = +5.0V \pm 5\%$, $V_{BB} = -5.0V \pm 5\%$; $T_A = 0^{\circ}$ C to 70°C by correlation with 100% electrical testing at $T_A = 25^{\circ}$ C. All other limits are assured by correlation with other production tests and/or product design and characterization. All signals referenced to GNDA. Typicals specified at $V_{CC} = +5.0V$, $V_{BB} = -5.0V$, $T_A = 25^{\circ}$ C.

Symbol	Parameter	Conditions	Min	Тур	Max	Units		
POWER	POWER DISSIPATION (ALL DEVICES)							
I _{CC} 0	Power-Down Current	(Note)		0.5	1.5	mA		
I _{BB} 0	Power-Down Current	(Note)		0.05	0.3	mA		
I _{CC} 1	Active Current	VPI=0V; VF _R O, VPO ⁺ and VPO ⁻ unloaded		7.0	10.0	mA		
I _{BB} 1	Active Current	VPI=0V; VF _R O, VPO ⁺ and VPO ⁻ unloaded		7.0	10.0	mA		
DIGITAL	DIGITAL INTERFACE							
VIL	Input Low Voltage				0.6	V		
V _{IH}	Input High Voltage		2.2			V		
V _{OL}	Output Low Voltage	D_X , $I_L = 3.2 \text{ mA}$ TS _X , $I_L = 3.2 \text{ mA}$, Open Drain			0.4 0.4	V V		
V _{OH}	Output High Voltage	$D_X, I_H = -3.2 \text{ mA}$	2.4			V		
IIL	Input Low Current	$GNDA \le V_{IN} \le V_{IL}$, All Digital Inputs	- 10		10	μΑ		
I _{IH}	Input High Current	$V_{IH} \leq V_{IN} \leq V_{CC}$	- 10		10	μΑ		
I _{OZ}	Output Current in High Impedance State (TRI-STATE)	$D_X,GNDA{\leq}V_O{\leq}V_{CC}$	- 10		10	μΑ		

Note: I_{CC0} and I_{BB0} are measured after first achieving a power-up state.

Electrical Characteristics (Continued)

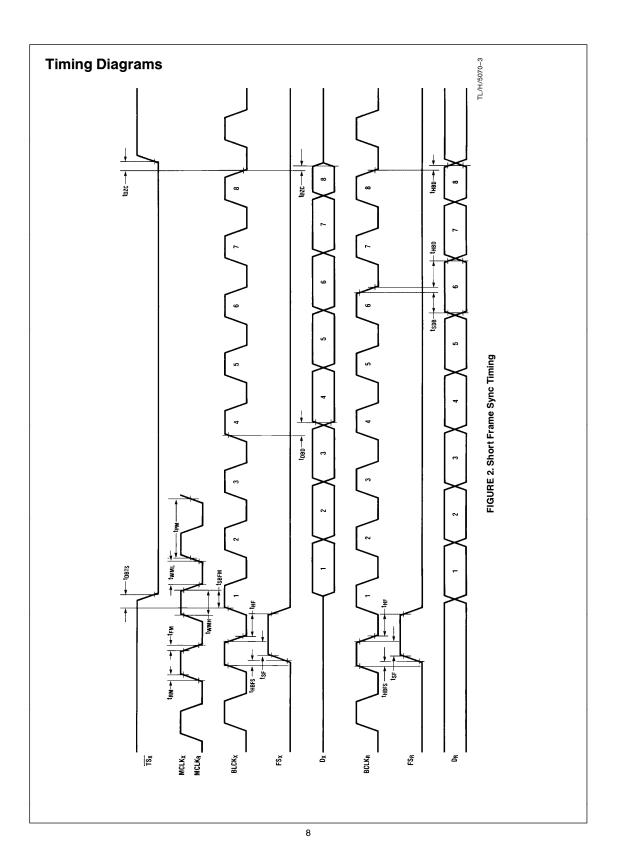
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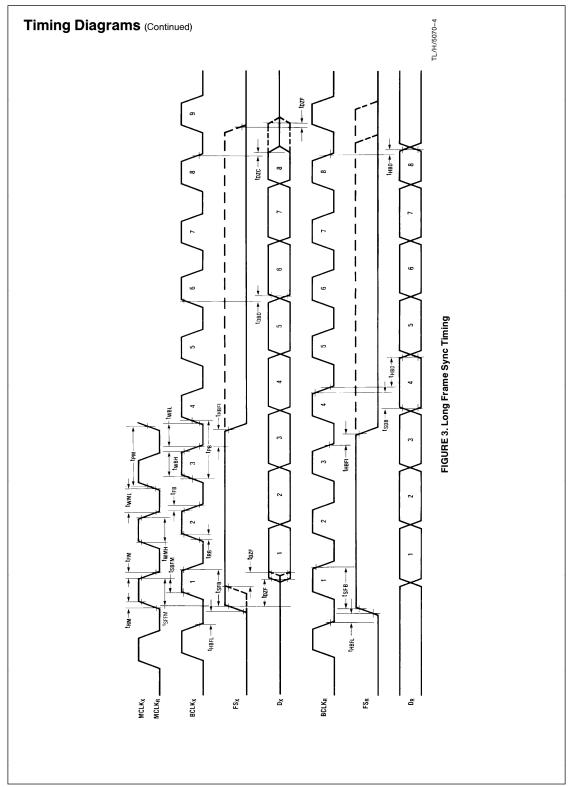
	Parameter	Conditions	Min	Тур	Max	Units
ANALOG IN	ITERFACE WITH TRANSMIT INPU	T AMPLIFIER (ALL DEVICES)				
I _I XA	Input Leakage Current	$-2.5V{\leq}V{\leq}{+}2.5V,$ VF_XI $^+$ or VF_XI $^-$	-200		200	nA
R _I XA	Input Resistance	$-2.5V{\leq}V{\leq}{+}2.5V,$ VF_XI $^+$ or VF_XI $^-$	10			MΩ
R _O XA	Output Resistance	Closed Loop, Unity Gain		1	3	Ω
R _L XA	Load Resistance	GS _X	10			kΩ
C _L XA	Load Capacitance	GS _X			50	pF
V _O XA	Output Dynamic Range	GS _X , R _L \geq 10 k Ω	- 2.8		+ 2.8	V
A _V XA	Voltage Gain	VF_XI^+ to GS_X	5000			٧/١
F _U XA	Unity-Gain Bandwidth		1	2		MH:
V _{OS} XA	Offset Voltage		-20		20	m۷
V _{CM} XA	Common-Mode Voltage	CMRRXA > 60 dB	- 2.5		2.5	V
CMRRXA	Common-Mode Rejection Ratio	DC Test	60			dB
PSRRXA	Power Supply Rejection Ratio	DC Test	60			dB
ANALOG IN	ITERFACE WITH RECEIVE FILTER	R (ALL DEVICES)				
R _O RF	Output Resistance	Pin VF _R O		1	3	Ω
R _L RF	Load Resistance	$VF_{R}O = \pm 2.5V$	10			kΩ
C _L RF	Load Capacitance	Connect from VF _R O to GNDA			25	pF
VOS _R O	Output DC Offset Voltage	Measure from VF _R O to GNDA	-200		200	m۷
100K0						
	ITERFACE WITH POWER AMPLIF	IERS (ALL DEVICES)				
	ITERFACE WITH POWER AMPLIF	ERS (ALL DEVICES) -1.0V ≤ VPI ≤ 1.0V	- 100		100	nA
ANALOG IN			- 100 10		100	
ANALOG IN	Input Leakage Current	-1.0V≤VPI≤1.0V			100 25	nA MΩ mV
ANALOG IN IPI RIPI	Input Leakage Current Input Resistance	-1.0V≤VPI≤1.0V	10	1		MΩ
ANALOG IN IPI RIPI VIOS	Input Leakage Current Input Resistance Input Offset Voltage	- 1.0V ≤ VPI ≤ 1.0V - 1.0V ≤ VPI ≤ 1.0V Inverting Unity-Gain at	10	1 400		MΩ mV
ANALOG IN IPI RIPI VIOS ROP	Input Leakage Current Input Resistance Input Offset Voltage Output Resistance	$-1.0V \le VPI \le 1.0V$ $-1.0V \le VPI \le 1.0V$ Inverting Unity-Gain at $VPO^{+} \text{ or } VPO^{-}$	10			MΩ mV Ω
ANALOG IN IPI RIPI VIOS ROP F _C	Input Leakage Current Input Resistance Input Offset Voltage Output Resistance Unity-Gain Bandwidth	$-1.0V \le VPI \le 1.0V$ $-1.0V \le VPI \le 1.0V$ Inverting Unity-Gain at $VPO^{+} \text{ or } VPO^{-}$	10		25	MΩ m\ Ω kH:
ANALOG IN IPI RIPI VIOS ROP F _C C _L P	Input Leakage Current Input Resistance Input Offset Voltage Output Resistance Unity-Gain Bandwidth Load Capacitance	$-1.0V \le VPI \le 1.0V$ $-1.0V \le VPI \le 1.0V$ Inverting Unity-Gain at VPO + or VPO - Open Loop (VPO -) $R_L = 600\Omega VPO^+ \text{ to } VPO^-$	10	400	25	MΩ mV Ω kH;

Timing Specifications

Unless otherwise noted, limits printed in **BOLD** characters are guaranteed for $V_{CC} = \pm 5.0V \pm 5\%$, $V_{BB} = -5.0V \pm 5\%$, $T_A = 0^{\circ}$ C to 70°C by correlation with 100% electrical testing at $T_A = 25^{\circ}$ C. All other limits are assured by correlation with other production tests and/or product design and characterization. All signals are referenced to GNDA. Typicals specified at $V_{CC} = \pm 5.0V$, $V_{BB} = -5.0V$, $T_A = 25^{\circ}$ C. All timing parameters are measured at $V_{OH} = 2.0V$ and $V_{OL} = 0.7V$. See Definitions and Timing Conventions section for test methods information.

Symbol	Parameter	Conditions	Min	Тур	Мах	Units
1/t _{PM}	Frequency of Master Clock			1.536		MHz
		MCLK _X and MCLK _B		1.544 2.048		MHz MHz
t _{RM}	Rise Time of Master Clock	MCLK _X and MCLK _R			50	ns
t _{FM}	Fall Time of Master Clock	MCLK _X and MCLK _R			50	ns
t _{PB}	Period Bit of Clock		485	488	15725	ns
t _{RB}	Rise Time of Bit Clock	BCLK _X and BCLK _R			50	ns
t _{FB}	Fall Time of Bit Clock	BCLK _X and BCLK _R			50	ns
t _{WMH}	Width of Master Clock High	MCLK _X and MCLK _R	160			ns
t _{WML}	Width of Master Clock Low	MCLK _X and MCLK _R	160			ns
^t SBFM	Set-Up Time from $BCLK_X$ High to $MCLK_X$ Falling Edge		100			ns
^t SFFM	Set-Up Time from FS_X High to MCLK_X Falling Edge	Long Frame Only	100			ns
t _{WBH}	Width of Bit Clock High		160			ns
t _{WBL}	Width of Bit Clock Low		160			ns
t _{HBFL}	Holding Time from Bit Clock Low to Frame Sync	Long Frame Only	0			ns
t _{HBFS}	Holding Time from Bit Clock High to Frame Sync	Short Frame Only	0			ns
t _{SFB}	Set-Up Time for Frame Sync to Bit Clock Low	Long Frame Only	80			ns
t _{DBD}	Delay Time from BCLK _X High to Data Valid	Load = 150 pF plus 2 LSTTL Loads	0		180	ns
t _{DBTS}	Delay Time to $\overline{TS_X}$ Low	Load = 150 pF plus 2 LSTTL Loads			140	ns
t _{DZC}	Delay Time from BCLK _X Low to Data Output Disabled		50		165	ns
t _{DZF}	Delay Time to Valid Data from FS_X or $BCLK_X$, Whichever Comes Later	C _L =0 pF to 150 pF	20		165	ns
t _{SDB}	Set-Up Time from D_R Valid to BCLK $_{R/X}$ Low		50			ns
t _{HBD}	Hold Time from $BCLK_{R/X}$ Low to D_R Invalid		50			ns
t _{SF}	Set-Up Time from FS _{X/R} to BCLK _{X/R} Low	Short Frame Sync Pulse (1 Bit Clock Period Long)	50			ns
t _{HF}	Hold Time from $BCLK_{X/R}$ Low to $FS_{X/R}$ Low	Short Frame Sync Pulse (1 Bit Clock Period Long)	100			ns
t _{HBFI}	Hold Time from 3rd Period of Bit Clock Low to Frame Sync (FS _X or FS _R)	Long Frame Sync Pulse (from 3 to 8 Bit Clock Periods Long)	100			ns
t _{WFL}	Minimum Width of the Frame Sync Pulse (Low Level)	64k Bit/s Operating Mode	160			ns





Transmission Characteristics

Unless otherwise noted, limits printed in **BOLD** characters are guaranteed for $V_{CC} = \pm 5.0V \pm 5\%$, $V_{BB} = -5.0V \pm 5\%$; $T_A = 0^{\circ}C$ to 70°C by correlation with 100% electrical testing at $T_A = 25^{\circ}C$. All other limits are assured by correlation with other production tests and/or product design and characterization. GNDA = 0V, f = 1.02 kHz, $V_{IN} = 0$ dbm0, transmit input amplifier connected for unity gain non-inverting. Typicals specified at $V_{CC} = \pm 5.0V$, $V_{BB} = -5.0V$, $T_A = 25^{\circ}C$.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
AMPLITU	JDE RESPONSE					
	Absolute Levels (Definition of nominal gain)	Nominal 0 dBm0 Level is 4 dBm (600Ω) 0 dBm0		1.2276		Vrms
t _{MAX}	Virtual Decision Value Defined per CCITT Rec. G711	Max Transmit Overload Level TP3064 (3.17 dBm0) TP3067 (3.14 dBm0)		2.501 2.492		V _{PK} V _{PK}
G _{XA}	Transmit Gain, Absolute	$T_{A} = 25^{\circ}C, V_{CC} = 5V, V_{BB} = -5V$	-0.15		0.15	dB
G _{XR}	Transmit Gain, Relative to G _{XA}		- 1.8 - 0.15 - 0.35 - 0.7		-40 -30 -26 -0.1 0.15 0.05 0 -14 -32	dB dB dB dB dB dB dB dB dB
G _{XAT}	Absolute Transmit Gain Variation with Temperature	Relative to G _{XA}	-0.1		0.1	dB
G _{XAV}	Absolute Transmit Gain Variation with Supply Voltage	Relative to G _{XA}	-0.05		0.05	dB
G _{XRL}	Transmit Gain Variations with Level	Sinusoidal Test Method Reference Level = -10 dBm0 VF _X I ⁺ = -40 dBm0 to $+3 \text{ dBm0}$ VF _X I ⁺ = -50 dBm0 to -40 dBm0 VF _X I ⁺ = -55 dBm0 to -50 dBm0	- 0.2 - 0.4 - 1.2		0.2 0.4 1.2	dB dB dB
G _{RA}	Receive Gain, Absolute	$T_A = 25^{\circ}C$, $V_{CC} = 5V$, $V_{BB} = -5V$ Input = Digital Code Sequence for 0 dBm0 Signal	-0.15		0.15	dB
G _{RR}	Receive Gain, Relative to G _{RA}	f=0 Hz to 3000 Hz f=3300 Hz f=3400 Hz f=4000 Hz	-0.15 -0.35 -0.7		0.15 0.05 0 - 14	dB dB dB dB
G _{RAT}	Absolute Receive Gain Variation with Temperature	Relative to G _{RA}	-0.1		0.1	dB
G _{RAV}	Absolute Receive Gain Variation with Supply Voltage	Relative to G _{RA}	-0.05		0.05	dB
G _{RRL}	Receive Gain Variations with Level	Sinusoidal Test Method; Reference Input PCM Code Corresponds to an Ideally Encoded - 10 dBm0 Signal PCM Level = -40 dBm0 to +3 dBm0 PCM Level = -50 dBm0 to -40 dBm0 PCM Level = -55 dBm0 to -50 dBm0	- 0.2 - 0.4 - 1.2		0.2 0.4 1.2	dB dB dB
V _{RO}	Receive Filter Output at VF _B O	$RL = 10 k\Omega$	-2.5		2.5	v

Transmission Characteristics (Continued)

Unless otherwise noted, limits printed in **BOLD** characters are guaranteed for $V_{CC} = \pm 5.0V \pm 5\%$, $V_{BB} = -5.0V \pm 5\%$; $T_A = 0^{\circ}$ C to 70°C by correlation with 100% electrical testing at $T_A = 25^{\circ}$ C. All other limits are assured by correlation with other production tests and/or product design and characterization. GNDA = 0V, f = 1.02 kHz, $V_{IN} = 0$ dbm0, transmit input amplifier connected for unity gain non-inverting. Typicals specified at $V_{CC} = \pm 5.0V$, $V_{BB} = -5.0V$, $T_A = 25^{\circ}$ C.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
ENVELOP	E DELAY DISTORTION WITH FREQU	JENCY				
D _{XA}	Transmit Delay, Absolute	f=1600 Hz		290	315	μs
D _{XR}	Transmit Delay, Relative to D_{XA}	f=500 Hz-600 Hz		195	220	μS
	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	f=600 Hz-800 Hz		120	145	μs
		f=800 Hz-1000 Hz		50	75	μs
		f = 1000 Hz - 1600 Hz		20	40	μs
		f = 1600 Hz - 2600 Hz		55	75	μ0 μS
		f = 2600 Hz - 2800 Hz		80	105	μ0 μS
		f = 2800 Hz - 3000 Hz		130	155	
D	Dessive Delay, Absolute					μs
D _{RA}	Receive Delay, Absolute	f=1600 Hz		180	200	μs
D _{RR}	Receive Delay, Relative to D _{RA}	f = 500 Hz - 1000 Hz	-40	-25		μs
		f=1000 Hz-1600 Hz	-30	-20		μs
		f=1600 Hz-2600 Hz		70	90	μs
		f=2600 Hz-2800 Hz		100	125	μs
		f=2800 Hz-3000 Hz		145	175	μs
NOISE	1	1				
N _{XC}	Transmit Noise, C Message Weighted	TP3064 (Note 1)		12	15	dBrnC
N _{XP}	Transmit Noise, Psophometric Weighted	TP3067 (Note 1)		-74	-67	dBm0p
N _{RC}	Receive Noise, C Message	PCM Code Equals Alternating				
	Weighted	Positive and Negative Zero				
		TP3064		8	11	dBrnC0
N _{RP}	Receive Noise, Psophometric	PCM Code Equals Positive				
··nr	Weighted	Zero				
	Weighted	TP3067		-82	-79	dBm0p
N _{RS}	Noise, Single Frequency	f=0 kHz to 100 kHz, Loop Around			-53	dBm0
110		Measurement, $VF_XI^+ = 0$ Vrms				
$PPSR_X$	Positive Power Supply Rejection,	V _{CC} =5.0 V _{DC} +100 mVrms				
	Transmit	f=0 kHz-50 kHz (Note 2)	40			dBC
NPSRX	Negative Power Supply Rejection,	$V_{BB} = -5.0 V_{DC} + 100 \text{ mVrms}$				
	Transmit	f=0 kHz-50 kHz (Note 2)	40			dBC
PPSR _R	Positive Power Supply Rejection,	PCM Code Equals Positive Zero				
	Receive	$V_{CC} = 5.0 V_{DC} + 100 \text{ mVrms}$				
		Measure VF _B O				
		f=0 Hz-4000 Hz	38			dBC
		f = 4 kHz - 50 kHz	25			dB
NPSRR	Negative Power Supply Rejection,	PCM Code Equals Positive Zero				
I'll ONR	Receive	$V_{BB} = -5.0 V_{DC} + 100 \text{ mVrms}$				
		Measure VF _B O				
		f = 0 Hz - 4000 Hz	40			dBC
		f = 4 kHz - 25 kHz	40			dB
		f = 25 kHz - 50 kHz	36			dB
SOS	Spurious Out-of-Band Signals	0 dBm0, 300 Hz – 3400 Hz Input				
000	at the Channel Output	PCM Code Applied at DR				
		Measure Individual Image Signals at				
		5 5				
		VF _R O 4600 Hz–7600 Hz			- 30	ab
					- 32	dB dB
		7600 Hz - 8400 Hz			-40	dB
	1	8400 Hz-100,000 Hz	1		-32	dB

Transmission Characteristics (Continued)

Unless otherwise noted, limits printed in **BOLD** characters are guaranteed for $V_{CC} = \pm 5.0V \pm 5\%$, $V_{BB} = -5.0V \pm 5\%$; $T_A = 0^{\circ}$ C to 70°C by correlation with 100% electrical testing at $T_A = 25^{\circ}$ C. All other limits are assured by correlation with other production tests and/or product design and characterization. GNDA = 0V, f = 1.02 kHz, $V_{IN} = 0$ dbm0, transmit input amplifier connected for unity gain non-inverting. Typicals specified at $V_{CC} = \pm 5.0V$, $V_{BB} = -5.0V$, $T_A = 25^{\circ}$ C.

Symbol	Parameter	Conditions	Min	Тур	Мах	Units
DISTORT	TION					
STD _{X,} STD _R	Signal to Total Distortion Transmit or Receive Half-Channel	Sinusoidal Test Method (Note 3) Level = 3.0 dBm0 = 0 dBm0 to - 30 dBm0 = -40 dBm0 XMT RCV = -55 dBm0 XMT RCV	33 36 29 30 14 15			dBC dBC dBC dBC dBC dBC
SFD_X	Single Frequency Distortion, Transmit				-46	dB
SFD _R	Single Frequency Distortion, Receive				-46	dB
IMD	Intermodulation Distortion	Loop Around Measurement, $VF_XI^+ = -4 \text{ dBm0 to } -21 \text{ dBm0, Two}$ Frequencies in the Range 300 Hz -3400 Hz			-41	dB
CROSST	ALK					
CT _{X-R}	Transmit to Receive Crosstalk	f=300 Hz-3000 Hz D _R =Quiet PCM Code		-90	-75	dB
CT _{R-X}	Receive to Transmit Crosstalk	f=300 Hz-3000 Hz, VF _X I=0V (Note 2)		-90	-70	dB
POWER	AMPLIFIERS					
V _O PA	$\begin{array}{l} \mbox{Maximum 0 dBm0 Level} \\ \mbox{(Better than } \pm 0.1 \mbox{ dB Linearity over} \\ \mbox{the Range} - 10 \mbox{ dBm0 to } + 3 \mbox{ dBm0}) \end{array}$	Balanced Load, R_L Connected Betwee VPO ⁺ and VPO ⁻ . $R_L = 600\Omega$ $R_L = 1200\Omega$	n 3.3 3.5			Vrms Vrms
						-

Note 2: PPSR_X, NPSR_X, and CT_{R-X} are measured with a -50 dBm0 activation signal applied to VF_XI⁺.

Note 3: TP3064 is measured using C message weighted filter. TP3067 is measured using psophometric weighted filter.

Applications Information

POWER SUPPLIES

While the pins of the TP3060 family are well protected against electrical misuse, it is recommended that the standard CMOS practice be followed, ensuring that ground is connected to the device before any other connections are made. In applications where the printed circuit board may be plugged into a "hot" socket with power and clocks already present, an extra long ground pin in the connector should be used.

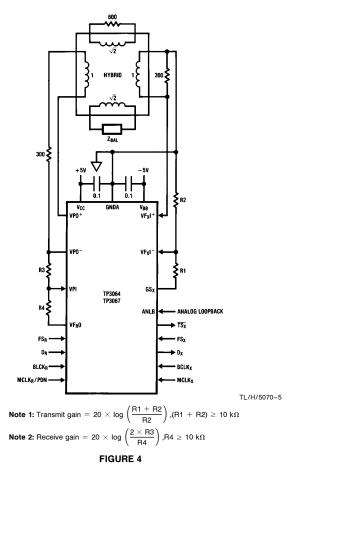
All ground connections to each device should meet at a common point as close as possible to the GNDA pin. This

Typical Asynchronous Application

minimizes the interaction of ground return currents flowing through a common bus impedance. 0.1 μF supply decoupling capacitors should be connected from this common ground point to V_{CC} and V_{BB}, as close to the device as possible.

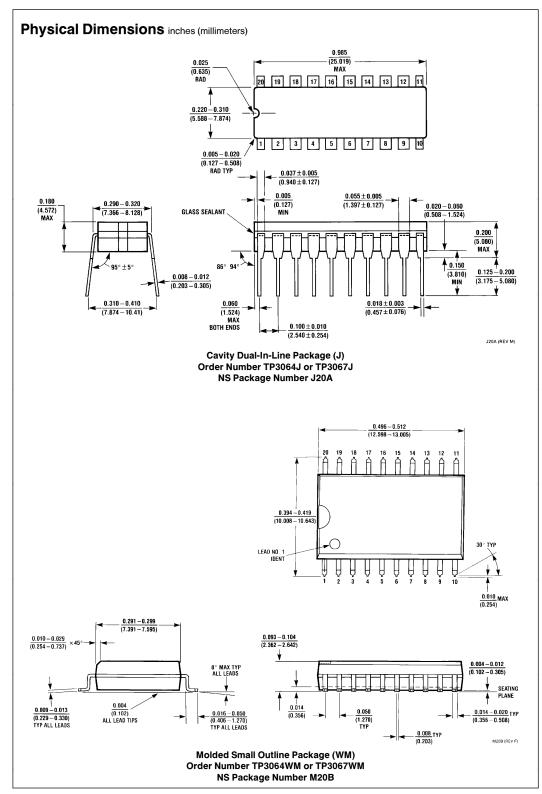
For best performance, the ground point of each CODEC/ FILTER on a card should be connected to a common card ground in "STAR" formation, rather than via a ground bus. This common ground point should be decoupled to V_{CC} and V_{BB} with 10 μF capacitors.

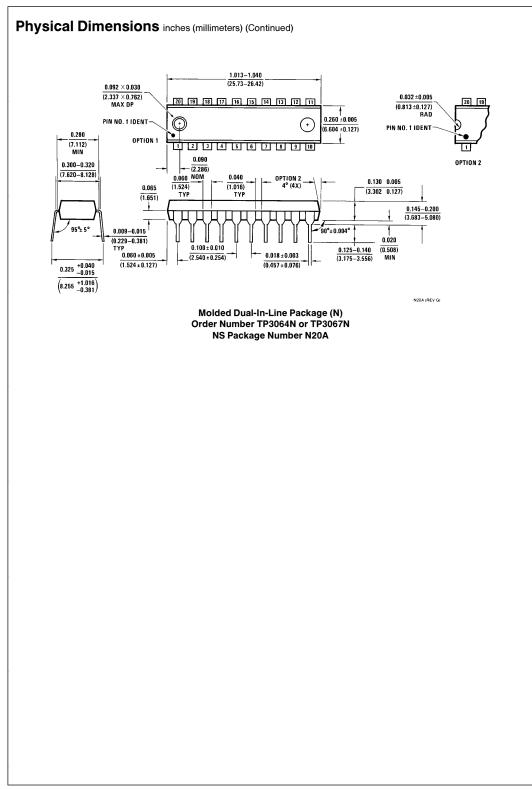
Note: See Application Note 370 for further details

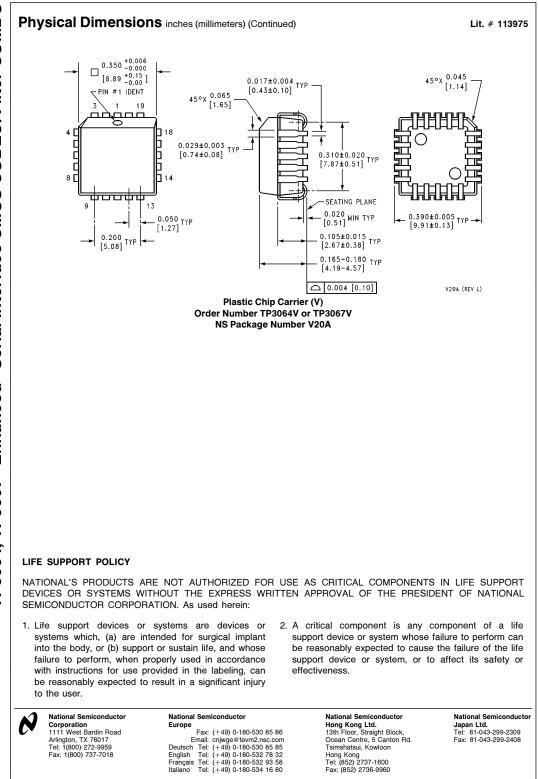


Definitions and Timing Conventions

DEFINITIONS		TIMING CONVENT	TIONS
V _{IH}	V _{IH} is the d.c. input level above which an input level is guaranteed to appear	For the purposes of conventions apply:	of this timing specification, the following
	as a logical one. This parameter is to be measured by performing a functional test at reduced clock	Input Signals	All input signals may be characterized as: $V_L=0.4V,V_H=$ 2.4V, $t_R<$ 10 ns, $t_F<$ 10 ns.
	speeds and nominal timing, (i.e. not minimum setup and hold times or output strobes), with the high level of all driving signals set to V _{IH} and	Period	The period of clock signal is designated as t _{Pxx} where xx represents the mnemonic of the clock signal being specified.
V _{IL}	maximum supply voltages applied to the device V_{IL} is the d.c. input level below which	Rise Time	Rise times are designated as t_{Ryy} , where yy represents a mnemonic of the signal whose rise time is being
	an input level is guaranteed to appear as a logical zero to the device. This parameter is measured in the same manner as V_{IH} but with all driving signal low levels set to V_{IL} and minimum supply voltages applied to the device.	Fall Time	specified. t_{Ryy} is measured from V_{IL} to V_{IH} . Fall times are designated as t_{Fyy} , where yy represents a mnemonic of the signal whose fall time is being specified. t_{Fyy} is measured from V_{IH} to V_{V} .
V _{OH}	V _{OH} is the minimum d.c. output level to which an output placed in a logical one state will converge when loaded at the maximum specified load current.	Pulse Width High	V_{IL} . The high pulse width is designated as t_{WZZH} , where zz represents the mnemonic of the input or output signal whose pulse width is being specified.
V _{OL}	V _{OL} is the maximum d.c. output level to which an output placed in a logical zero state will converge when loaded at the maximum specified load current.	Pulse Width Low	High pulse widths are measured from V_{IH} to V_{IH} . The low pulse width is designated as
Threshold Region	The threshold region is the range of input voltages between V_{IL} and V_{IH} .		t _{WzzL} , where zz represents the mnemonic of the input or output signal whose pulse width is being specified.
Valid Signal	A signal is Valid if it is in one of the valid logic states, (i.e. above V_{IH} or below V_{IL}). In timing specifiations, a	Catur Time	Low pulse widths are measured from V_{IL} to $V_{IL}. \label{eq:VIL}$
Invalid Signal	signal is deemed valid at the instant it enters a valid state. A signal is Invalid if it is not in a valid logic state, i.e. when it is in in the threshold region between V_{IL} and V_{IH} .	Setup Time	Setup times are designated as t _{SWWXX} , where ww represents the mnemonic of the input signal whose setup time is being specified relative to a clock or strobe input represented by mnemonic xx. Setup times are measured from the
	In timing specifications, a signal is deemed Invalid at the instant it enters the threshold region.	Hold Time	ww Valid to xx Invalid. Hold times are designated as t _{Hxxww} , where ww represents the mnemonic of the input signal whose hold time is being specified relative to a clock or strobe input represented by mnemonic xx. Hold times are measured from xx Valid to ww Invalid.
		Delay Time	Delay times are designated as t _{Dxxyy} Hi to Low, where xx represents the mnemonic of the input reference signal and yy represents the mnemonic of the output signal whose timing is being specified relative to xx. The mnemonic may optionally be terminated by an H or L to specify the high going or low going transition of the output signal. Maximum delay times are measured from xx Valid to yy Valid. Minimum delay times are measured from xx Valid to yy Invalid. This parameter is tested under the load conditions specified in the Conditions column of the Timing Specifications section of this data sheet.







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<u>Products</u> > <u>Telecommunications</u> > <u>Analog Line Card Components</u> > **TP3064**

TP3064 Product Folder

Enhanced Serial Interface CMOS CODEC/Filter COMBO

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Datasheet

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Package Availability, Models, Samples & Pricing

Part Number	Package		Status	Models		Samples & Electronic		udgetary Pricing	Std Pack	Package Marking		
	Туре	Pins	MSL		SPICE	IBIS	Orders	Qty	\$US each	Size		
TP3064WM-X	<u>SOIC</u> <u>WIDE</u>	20	MSL	Lifetime buy	N/A	N/A	Buy Now	1K+	\$1.7000	rail of 36	[logo]¢U¢Z¢2¢T TP3064WM-X	
TP3064WM	<u>SOIC</u> <u>WIDE</u>	20	MSL	Full production	N/A	N/A	Samples Buy Now	1K+	\$1.5000	rail of 36	[logo]¢U¢Z¢2¢T TP3064WM COMBO\$R	
TP3064N	MDIP	20	MSL	Full production	N/A	N/A	Samples Buy Now	1K+	\$1.5000	rail of 18	[logo]¢U¢Z¢3¢T TP3064N COMBO\$R	
TP3064 MDC	Die		Full production	N/A	N/A	Samples			tray of N/A	-		
TP3064 MWC	<u>Wafer</u>		Full production	N/A	N/A				wafer jar of N/A	-		

General Description

The TP3064 (μ -law) and TP3067 (A-law) are monolithic PCM CODEC/Filters utilizing the A/D and D/A conversion architecture shown in *Figure 1*, and a serial PCM interface. The devices are fabricated using National's advanced double-poly CMOS process (microCMOS).

Similar to the TP305X family, these devices feature an additional Receive Power Amplifier to provide push-pull balanced output drive capability. The receive gain can be adjusted by means of two external resistors for an output level of up to $\pm 6.6V$ across a balanced 600 Ohm load.

Also included is an Analog Loopback switch and a TS_X # output.

See also AN-370, "Techniques for Designing with CODEC/Filter COMBO Circuits."

Features

- Complete CODEC and filtering system including:
 - Transmit high-pass and low-pass filtering
 - Receive low-pass filter with sin x/x correction
 - Active RC noise filters
 - $\circ~\mu\text{-law}$ or A-law compatible COder and DECoder
 - o Internal precision voltage reference
 - o Serial I/O interface
 - o Internal auto-zero circuitry
 - Receive push-pull power amplifiers
- µ-law-TP3064
- A-law-TP3067
- Designed for D3/D4 and CCITT applications
- ±5V operation
- Low operating power-typically 70 mW
- Power-down standby mode-typically 3 mW
- Automatic power-down
- TTL or CMOS compatible digital interfaces
- Maximizes line interface card circuit density

[Information as of 9-Aug-2002]

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