

# 1:3 LVPECL CLOCK BUFFER WITH PROGRAMMABLE DIVIDER

## **FEATURES**

- Distributes One Differential Clock Input to Three LVPECL Differential Clock Outputs
- Programmable Output Divider for Two LVPECL Outputs
- Low-Output Skew 15 ps (Typical)
- V<sub>cc</sub> Range 3 V–3.6 V
- Signaling Rate Up to 800-MHz LVPECL
- Differential Input Stage for Wide Common-Mode Range
- Provides VBB Bias Voltage Output for Single-Ended Input Signals
- Receiver Input Threshold ±75 mV
- 24-Terminal QFN Package (4 mm × 4 mm)
- Accepts Any Differential Signaling: LVDS, HSTL, CML, VML, SSTL-2, and Single-Ended: LVTTL/LVCMOS

## DESCRIPTION

The CDCP1803 clock driver distributes one pair of differential clock inputs to three pairs of LVPECL differential clock outputs Y[2:0] and  $\overline{Y[2:0]}$  with minimum skew for clock distribution. The CDCP1803 is specifically designed for driving 50- $\Omega$  transmission lines.

The CDCP1803 has three control terminals, S0, S1, and S2, to select different output mode settings; see Table 1 for details. The CDCP1803 is characterized for operation from  $-40^{\circ}$ C to  $85^{\circ}$ C. For use in single-ended driver applications, the CDCP1803 also provides a VBB output terminal that can be directly connected to the unused input as a common-mode voltage reference.



 $^{(1)}$  Thermal pad must be connected to V<sub>SS</sub>.





P0025-02



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



#### FUNCTIONAL BLOCK DIAGRAM

#### **TERMINAL FUNCTIONS**

TER	MINAL	1/0	DECODIDITION		
NAME	NO.	I/O	DESCRIPTION		
EN	1	I	ENABLE: Enables or disables all outputs simultaneously.		
	$(\text{with } 60\text{-}k\Omega \text{ pullup}) = \text{EN} = 1: \text{ outputs on according to } S[2:0] \text{ settings} \\ \text{EN} = 0: \text{ outputs } Y[2:0] \text{ off (high impedance)} \\ \text{See Table 1 for details.}$		EN = 0: outputs Y[2:0] off (high impedance)		
IN, <b>IN</b>	3, 4	I (differential)	Differential input clock. Input stage is sensitive and has a wide common-mode range. Therefore, almost any type of differential signal can drive this input (LVPECL, LVDS, CML, HSTL). Because the input is high-impedance, it is recommended to terminate the PCB transmission line before the input (e.g., with 100 $\Omega$ across input). Input can also be driven by a single-ended signal if the complementary input is tied to VBB. A more-advanced scheme for single-ended signals is given in the <i>Application Information</i> section near the end of this document.		
			The inputs employ an ESD structure protecting the inputs in case of an input voltage exceeding the rails by more than ~0.7 V. Reverse biasing of the IC through these inputs is possible and must be prevented by limiting the input voltage $< V_{DD}$ .		
NC	12		No connect. Leave this terminal open or tie to ground.		
S[2:0]	24, 19, 18	l (with 60-kΩ pullup)	Select mode of operation. Defines the output configuration of Y[2:0], see Table 1 for configuration.		
VBB	6	0	Bias voltage output can be used to bias unused complementary input IN for single-ended input signals.		
			The output voltage of VBB is $V_{DD}$ – 1.3 V. When driving a load, the output current drive is limited to about 1.5 mA.		
V <sub>DD</sub> PECL	2, 5	Supply	Supply voltage PECL input + internal logic		
V <sub>DD</sub> [2:0]	8, 11, 14, 17, 20, 23	Supply	PECL output supply voltage for output Y[2:0]. Each output can be disabled by pulling the corresponding $V_{\text{DD}}x$ to GND.		
			<b>CAUTION:</b> In this mode, no voltage from outside may be forced, because internal diodes could be forced in forward direction. Thus, it is recommended to disconnect the output if it is not being used.		
V <sub>SS</sub>	7, 13	Supply	Device ground		
Y[2:0] Y[2:0]	9, 15, 21 10, 16, 22	O (LVPECL)	LVPECL clock outputs. These outputs provide low-skew copies of IN or down-divided copies of clock IN based on selected mode of operation S[2:0]. If an output is unused, the output can simply be left open to save power and minimize noise impact to the remaining outputs.		

## **CONTROL TERMINAL SETTINGS**

The CDCP1803 has three control terminals (S0, S1, and S2) and an enable terminal (EN) to select different output mode settings.



Figure 1. Control Terminal Setting for Example

Table 1	. (	Selection	Mode	Table
---------	-----	-----------	------	-------

						LVPECL <sup>(1)</sup>	
MODE	EN	S2	S1	S0	Y0	Y1	Y2
0	0	x	x	x		Off (high-z)	
1	1	0	0	0	÷ 1	÷ 1	÷ 1
2	1	0	0	V <sub>DD</sub> /2	÷ 1	Off (high-z)	Off (high-z)
3	1	0	0	1	÷ 1	÷ 1	Off (high-z)
4	1	0	V <sub>DD</sub> /2	0	÷ 1	÷ 2	Off (high-z)
5	1	0	V <sub>DD</sub> /2	V <sub>DD</sub> /2	÷ 1	÷ 4	Off (high-z)
6	1	0	V <sub>DD</sub> /2	1	÷ 1	÷ 8	Off (high-z)
7	1	0	1	0	÷ 1	Off (high-z)	÷ 1
8	1	0	1	1	÷ 1	÷ 2	÷ 1
9	1	V <sub>DD</sub> /2	0	0	÷ 1	÷ 4	÷ 1
10	1	V <sub>DD</sub> /2	0	V <sub>DD</sub> /2	÷ 1	÷ 8	÷ 1
11	1	V <sub>DD</sub> /2	0	1	÷ 1	Off (high-z)	÷ 2
12	1	V <sub>DD</sub> /2	V <sub>DD</sub> /2	0	÷ 1	÷ 1	÷ 2
13	1	V <sub>DD</sub> /2	V <sub>DD</sub> /2	V <sub>DD</sub> /2	÷ 1	÷ 2	÷ 2
14	1	V <sub>DD</sub> /2	V <sub>DD</sub> /2	1	÷ 1	÷ 4	÷2
15	1	V <sub>DD</sub> /2	1	0	÷ 1	÷8	÷ 2
16	1	V <sub>DD</sub> /2	1	V <sub>DD</sub> /2	÷ 1	Off (high-z)	÷ 4
17	1	V <sub>DD</sub> /2	1	1	÷ 1	÷ 1	÷ 4
18	1	1	0	0	÷ 1	÷2	÷ 4
19	1	1	0	V <sub>DD</sub> /2	÷ 1	÷ 4	÷ 4
20	1	1	0	1	÷ 1	÷8	÷ 4
21	1	1	V <sub>DD</sub> /2	0	÷ 1	Off (high-z)	÷ 8
22	1	1	V <sub>DD</sub> /2	V <sub>DD</sub> /2	÷ 1	÷ 1	÷ 8
23	1	1	V <sub>DD</sub> /2	1	÷ 1	÷ 2	÷ 8
24	1	1	1	0	÷ 1	÷ 4	÷ 8
25	1	1	1	V <sub>DD</sub> /2	÷ 1	÷8	÷ 8
26	1	1	1	1	÷ 1	Off (high-z)	÷ 16
27	V <sub>DD</sub> /2	0	0	0	÷ 1	÷ 1	÷ 16
28	V <sub>DD</sub> /2	0	0	V <sub>DD</sub> /2	÷ 1	÷ 2	÷ 16
29	V <sub>DD</sub> /2	0	0	1	÷ 1	÷ 4	÷ 16
30	V <sub>DD</sub> /2	0	V <sub>DD</sub> /2	0	÷ 1	÷8	÷ 16
Rsv	V <sub>DD</sub> /2	1	V <sub>DD</sub> /2	1	Reserved	Reserved	Reserved
Rsv	V <sub>DD</sub> /2	1	1	0	N/A	Low	Low

(1) The LVPECL outputs are open-emitter stages. Thus, if the unused LVPECL outputs Y0, Y1, or Y2 are left unconnected, then the current consumption is minimized and noise impact to remaining outputs is neglectable. Also, each output can be individually disabled by connecting the corresponding V<sub>DD</sub> input to GND.

SCAS727E-NOVEMBER 2003-REVISED JANUARY 2007



#### **ABSOLUTE MAXIMUM RATINGS**

over operating free-air temperature (unless otherwise noted)<sup>(1)</sup>

$V_{DD}$	Supply voltage	–0.3 V to 3.8 V
VI	Input voltage	-0.2 V to (V <sub>DD</sub> + 0.2 V)
Vo	Output voltage	-0.2 V to (V <sub>DD</sub> + 0.2 V)
	Differential short-circuit current, Yn, Yn, I <sub>OSD</sub>	Continuous
	Electrostatic discharge (HBM 1.5 k $\Omega$ , 100 pF), ESD	>2000 V
	Moisture level 24-terminal QFN package (solder reflow temperature of 235°C) MSL	2
T <sub>stg</sub>	Storage temperature	–65°C to 150°C
TJ	Maximum junction temperature	125°C

(1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## **RECOMMENDED OPERATING CONDITIONS**

		MIN	TYP	MAX	UNIT
$V_{DD}$	Supply voltage	3	3.3	3.6	V
T <sub>A</sub>	Operating free-air temperature	-40		85	°C

### **ELECTRICAL CHARACTERISTICS**

over operating free-air temperature range (unless otherwise noted)

## LVPECL INPUT IN, IN

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
f <sub>clk</sub>	Input frequency		0		800	MHz
V <sub>CM</sub>	High-level input common mode		1		V <sub>DD</sub> – 0.3	V
	Input voltage swing between IN and $\overline{IN}^{(1)}$		500		1300	
V <sub>IN</sub>	Input voltage swing between IN and $\overline{\rm IN}{}^{(2)}$		125		1300	mV
I <sub>IN</sub>	Input current	$V_{I} = V_{DD}$ or 0 V			±10	μA
R <sub>IN</sub>	Input impedance		300			kΩ
CI	Input capacitance at IN, IN			1		pF

(1) Is required to maintain ac specifications

(2) Is required to maintain device functionality

## **ELECTRICAL CHARACTERISTICS (continued)**

over operating free-air temperature range (unless otherwise noted)

## LVPECL OUTPUT DRIVER Y[2:0], Y[2:0]

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
f <sub>clk</sub>	Output frequency, see Figure 3.		0		800	MHz
V <sub>OH</sub>	High-level output voltage	Termination with 50 $\Omega$ to $V_{DD}$ – 2 V	V <sub>DD</sub> – 1.18		V <sub>DD</sub> - 0.81	V
V <sub>OL</sub>	Low-level output voltage	Termination with 50 $\Omega$ to $V_{DD}$ – 2 V	V <sub>DD</sub> – 1.98		V <sub>DD</sub> – 1.55	V
Vo	Output voltage swing between Y and $\overline{Y}$ , see Figure 3.	Termination with 50 $\Omega$ to $V_{DD}$ – 2 V	500			mV
I <sub>OZL</sub>	Output 2 state surrent	$V_{DD} = 3.6 \text{ V}, V_{O} = 0 \text{ V}$			5	۸
I <sub>OZH</sub>	Output 3-state current	$V_{DD} = 3.6 \text{ V}, V_O = V_{DD} - 0.8 \text{ V}$		10		μA
t <sub>r</sub> /t <sub>f</sub>	Rise and fall times	20% to 80% of V <sub>OUTPP</sub> , see Figure 7.	200		350	ps
t <sub>skpecl(o)</sub>	Output skew between any LVPECL output Y[2:0] and $\overline{Y[2:0]}$	See Note A in Figure 6.		15	30	ps
t <sub>Duty</sub>	Output duty-cycle distortion <sup>(1)</sup>	Crossing point-to-crossing point distortion	-50		50	ps
t <sub>sk(pp)</sub>	Part-to-part skew	Any Y, see Note B in Figure 6.		50		ps
Co	Output capacitance	V <sub>O</sub> = V <sub>DD</sub> or GND		1		pF
LOAD	Expected output load			50		Ω

(1) For an 800-MHz signal, the 50-ps error would result in a duty cycle distortion of ±4% when driven by an ideal clock input signal.

#### LVPECL INPUT-TO-LVPECL OUTPUT PARAMETERS

	PARAMETER	TEST CONDITIONS	MIN TYP	MAX	UNIT
t <sub>pd(lh)</sub>	Propagation delay, rising edge	VOX to VOX	320	600	ps
t <sub>pd(hl)</sub>	Propagation delay, falling edge	VOX to VOX	320	600	ps
t <sub>sk(p)</sub>	LVPECL pulse skew	VOX to VOX, see Note C in Figure 6.		100	ps

## JITTER CHARACTERISTICS

	PARAMETER	TEST CONDITIONS	MIN TYP	MAX	UNIT
JITTER CH	IARACTERISTICS				
	Additive phase jitter from input to	12 kHz to 20 MHz, f <sub>out</sub> = 250 MHz to 800 MHz, divide-by-1 mode		0.15	
<sup>I</sup> jitterLVPECL	LVPECL output Y[2:0], see Figure 2.	50 kHz to 40 MHz, f <sub>out</sub> = 250 MHz to 800 MHz, divide-by-1 mode		0.25	ps rms





## SUPPLY CURRENT ELECTRICAL CHARACTERISTICS

over recommended operating free-air temperature range (unless otherwise noted)

	PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Supply current	Full load	All outputs enabled and terminated with 50 $\Omega$ to $V_{DD}-2$ V on LVPECL outputs, f = 800 MHz for LVPECL outputs, $V_{DD}$ = 3.3 V		140		
I <sub>DD</sub>		No load	Outputs enabled, no output load, f = 800 MHz for LVPECL outputs, $V_{DD}$ = 3.6 V			90	mA
	Supply current savi output stage disable		f = 800 MHz for LVPECL output, $V_{DD}$ = 3.3 V		10		
I <sub>DDZ</sub>	Supply current, 3-s	tate	All outputs in high-impedance state by control logic, $f$ = 0 Hz, $V_{DD}$ = 3.6 V			0.5	mA



## PACKAGE THERMAL RESISTANCE

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$R_{\theta JA-1}$	QFN-24 package thermal resistance <sup>(1)</sup>	4-layer JEDEC test board (JESD51-7), airflow = 0 ft/min		106.6		°C/W
$R_{ extsf{ heta}JA-2}$	QFN-24 package thermal resistance with thermal vias in $PCB^{(1)}$	4-layer JEDEC test board (JESD51-7) with four thermal vias of 22-mil diameter each, airflow = 0 ft/min		55.4		°C/W

(1) It is recommended to provide four thermal vias to connect the thermal pad of the package effectively with the PCB and ensure a good heat sink.

#### Example:

Calculation of the junction-lead temperature with a 4-layer JEDEC test board using four thermal vias:  $T_{Chassis} = 85^{\circ}C$  (temperature of the chassis)

 $\begin{array}{l} \mathsf{P}_{effective} = \mathsf{I}_{max} \times \mathsf{V}_{max} = 90 \text{ mA} \times 3.6 \text{ V} = 324 \text{ mW} \text{ (max power consumption inside the package)} \\ \theta \mathsf{T}_{Junction} = \theta_{JA-2} \times \mathsf{P}_{effective} = 55.45^{\circ} \text{C/W} \times 324 \text{ mW} = 17.97^{\circ} \text{C} \end{array}$ 

$$\label{eq:time_time_time_time_time} \begin{split} T_{Junction} &= \theta T_{Junction} + T_{Chassis} = 17.97^{\circ}C + 85^{\circ}C = 103^{\circ}C \text{ (the maximum junction temperature of } \\ T_{die-max} &= 125^{\circ}C \text{ is not violated}) \end{split}$$



#### **CONTROL INPUT CHARACTERISTICS**

over recommended operating free-air temperature range

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>su</sub>	Setup time, S0, S1, S2, and EN terminals before clock IN		25			ns
t <sub>h</sub>	Hold time, S0, S1, S2, and EN terminals after clock IN		0			ns
t <sub>(disable)</sub>	Time between latching the EN low transition and when all outputs are disabled (how much time is required until the outputs turn off)			10		ns
t <sub>(enable)</sub>	Time between latching the EN low-to-high transition and when outputs are enabled based on control settings (how much time passes before the outputs carry valid signals)			1		μs
Rpullup	Internal pullup resistor on S[2:0] and EN input		42	60	78	kΩ
V <sub>IH(H)</sub>	Three-level input high, S0, S1, S2, and EN terminals <sup>(1)</sup>		0.9 V <sub>DD</sub>			V
V <sub>IL(L)</sub>	Three-level low, S0, S1, S2, and EN terminals				0.1 V <sub>DD</sub>	V
I <sub>IH</sub>	Input surrent S0, S1, S2, and EN terminals	$V_{I} = V_{DD}$			-5	μA
I <sub>IL</sub>	Input current, S0, S1, S2, and EN terminals	V <sub>I</sub> = GND	38		85	μA

(1) Leaving this terminal floating automatically pulls the logic level high to  $V_{DD}$  through an internal pullup resistor of 60 k $\Omega$ .

## **BIAS VOLTAGE VBB**

over operating free-air temperature range

	PARAMETER	TEST CONDITIONS	MIN	TYP MAX	UNIT
VBB	Output reference voltage	$V_{DD} = 3 V - 3.6 V$ , $I_{BB} = -0.2 mA$	V <sub>DD</sub> – 1.4	V <sub>DD</sub> - 1.2	V



OUTPUT REFERENCE VOLTAGE (V<sub>BB</sub>)

#### PARAMETER MEASUREMENT INFORMATION





- The difference between the fastest and the slowest  $t_{pd(LH)n}$  (n = 0...2)
- The difference between the fastest and the slowest  $t_{pd(HL)n}$  (n = 0...2)
- B. Part-to-part skew,  $t_{sk(pp)}$ , is calculated as the greater of:
- The difference between the fastest and the slowest t<sub>pd(LH)n</sub> (n = 0...2 for LVPECL, n = 3 for LVCMOS) across multiple devices
  The difference between the fastest and the slowest t<sub>pd(HL)n</sub> (n = 0...2 for LVPECL, n = 3 for LVCMOS) across multiple devices
  Pulse skew, t<sub>sk(p)</sub>, is calculated as the magnitude of the absolute time difference between the high-to-low (t<sub>pd(HL</sub>) and the low-to-high
- C. Pulse skew,  $t_{sk(p)}$ , is calculated as the magnitude of the absolute time difference between the high-to-low ( $t_{pd(HL)}$  and the low-to-high ( $t_{pd(LH)}$ ) propagation delays when a single switching input causes one or more outputs to switch,  $t_{sk(p)} = |t_{pd(HL)} t_{pd(LH)}|$ . Pulse skew is sometimes referred to as *pulse width distortion or duty cycle skew*.

T0067-02



Figure 6. Waveforms for Calculation of tsk(o) and tsk(pp)

Figure 7. LVPECL Differential Output Voltage and Rise/Fall Time

#### PCB DESIGN FOR THERMAL FUNCTIONALITY

It is recommended to take special care of the PCB design for good thermal flow from the QFN 24-terminal package to the PCB.

Due to the three LVPECL outputs, the current consumption of the CDCP1803 is fixed.

JEDEC JESD51-7 specifies thermal conductivity for standard PCB boards.



### PARAMETER MEASUREMENT INFORMATION (continued)

Modeling the CDCP1803 with a standard 4-layer JEDEC board results in a 59.5°C maximum temperature with  $R_{\theta JA}$  of 106.62°C/W for 25°C ambient temperature.

When deploying four thermal vias (one per quadrant), the thermal flow improves significantly, yielding 42.9°C maximum temperature with  $R_{\theta JA}$  of 55.4°C/W for 25°C ambient temperature.

To ensure sufficient thermal flow, it is recommended to design with four thermal vias in applications enabling all four outputs at once.



Figure 8. Recommended Thermal Via Placement

See the Quad Flatpack No-Lead Logic Packages (SCBA017) and QFN/SON PCB Attachment (SLUA271) application reports for further package-related information.

### **APPLICATION INFORMATION**

#### LVPECL RECEIVER INPUT TERMINATION

The input of the CDCP1803 has a high impedance and comes with a large common-mode voltage range.

For optimized noise performance, it is recommended to properly terminate the PCB trace (transmission line). If a differential signal drives the CDCP1803, then a 100- $\Omega$  termination resistor is recommended to be placed as close as possible across the input terminals. An even better approach is to install 2 × 50- $\Omega$  resistors, with the center tap connected to a capacitor (C) to terminate odd-mode noise and make up for transmission line mismatches. The VBB output can also be connected to the center tap to bias the input signal to (V<sub>DD</sub> – 1.3 V) (see Figure 9).



Figure 9. Recommended AC-Coupling LVPECL Receiver Input Termination



Figure 10. Recommended DC-Coupling LVPECL Receiver Input Termination

The CDCP1803 can also be driven by single-ended signals. Typically, the input signal becomes connected to one input, while the complementary input must be properly biased to the center voltage of the incoming input signal. For LVCMOS signals, this would be  $V_{CC}/2$ , realized by a simple voltage divider (e.g., two 10-k $\Omega$  resistors). The best option (especially if the dc offset of the input signal might vary) is to ac-couple the input signal and then rebias the signal using the VBB reference output. See Figure 11.

## **APPLICATION INFORMATION (continued)**



NOTE:  $C_{AC}$  – AC-coupling capacitor (e.g., 10 nF)  $C_{CT}$  – Capacitor keeps voltage at  $\overline{IN}$  constant (e.g., 10 nF)  $R_{dc}$  – Load and correct duty cycle (e.g., 50  $\Omega$ ) VBB – Bias voltage output

S0087-02

#### Figure 11. Typical Application Setting for Single-Ended Input Signals Driving the CDCP1803

### DEVICE BEHAVIOR DURING RESET AND CONTROL-TERMINAL SWITCHING

#### Output Behavior From Enabling the Device (EN = $0 \rightarrow 1$ )

In disable mode (EN = 0), all output drivers are switched in high-Z mode. The S[2:0] control inputs are also switched off. In the same mode, all flip-flops are reset. The typical current consumption is below 500  $\mu$ A.

When the device is enabled again, it takes typically 1  $\mu$ s for the settling of the reference voltage and currents. During this time, the outputs Y[2:0] and Y[2:0] drive a high signal. After the settle time, the outputs go into the low state. Due to the synchronization of each output driver signal with the input clock, the state of the waveforms after enabling the device is as shown in Figure 12. The inverting input and output signal is not included. The Y:/1 waveform is the undivided output driver state.









Signal State After the Device is Enabled (IN = High)

T0068-01

Figure 12. Waveforms

## **APPLICATION INFORMATION (continued)**

### Enabling a Single Output Stage

If a single output stage becomes enabled:

- Y[2:0] is either low or high (undefined).
- $\overline{Y[2:0]}$  is the inverted signal of Y[2:0].

With the first positive clock transition, the undivided output becomes the input clock state. The divided output states are equal to the actual internal divider. The internal divider is not reset while enabling single output drivers.







Figure 14. Signal State After an Output Driver Becomes Enabled While IN = 1

### PACKAGING INFORMATION

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	Eco Plan <sup>(2)</sup>	Lead/Ball Finish	MSL Peak Temp <sup>(3)</sup>
CDCP1803RGER	ACTIVE	QFN	RGE	24	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
CDCP1803RGERG4	ACTIVE	QFN	RGE	24	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
CDCP1803RGET	ACTIVE	QFN	RGE	24	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
CDCP1803RGETG4	ACTIVE	QFN	RGE	24	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
CDCP1803RTHR	ACTIVE	QFN	RTH	24	3000	TBD	CU SNPB	Level-2-235C-1 YEAR
CDCP1803RTHT	ACTIVE	QFN	RTH	24	250	TBD	CU SNPB	Level-2-235C-1 YEAR

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details. **TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

**Important Information and Disclaimer:**The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

## TAPE AND REEL BOX INFORMATION





#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



Device	Package	Pins	Site	Reel Diameter (mm)	Reel Width (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
CDCP1803RGER	RGE	24	SITE 28	330	12	4.3	4.3	1.5	8	12	Q2
CDCP1803RGET	RGE	24	SITE 28	330	12	4.3	4.3	1.5	8	12	Q2
CDCP1803RTHR	RTH	24	SITE 28	330	12	4.3	4.3	1.5	8	12	Q2
CDCP1803RTHT	RTH	24	SITE 28	330	12	4.3	4.3	1.5	8	12	Q2



# PACKAGE MATERIALS INFORMATION

8-Nov-2007



Device	Package	Pins	Site	Length (mm)	Width (mm)	Height (mm)
CDCP1803RGER	RGE	24	SITE 28	342.9	336.6	20.64
CDCP1803RGET	RGE	24	SITE 28	342.9	336.6	20.64
CDCP1803RTHR	RTH	24	SITE 28	342.9	336.6	20.64
CDCP1803RTHT	RTH	24	SITE 28	342.9	336.6	20.64

# RTH (S-PQFP-N24)

# PLASTIC QUAD FLATPACK



NOTES:

- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
- B. This drawing is subject to change without notice.
- C. QFN (Quad Flatpack No-Lead) Package configuration.

The package thermal pad must be soldered to the board for thermal and mechanical performance. See the Product Data Sheet for details regarding the exposed thermal pad dimensions.





# THERMAL PAD MECHANICAL DATA

## RTH (S-PQFP-N24)

#### THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, Quad Flatpack No-Lead Logic Packages, Texas Instruments Literature No. SCBA017. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



#### Bottom View

NOTE: All linear dimensions are in millimeters

Exposed Thermal Pad Dimensions

## **MECHANICAL DATA**



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. Quad Flatpack, No-Leads (QFN) package configuration.
- The package thermal pad must be soldered to the board for thermal and mechanical performance. See the Product Data Sheet for details regarding the exposed thermal pad dimensions.
- E. Falls within JEDEC MO-220.



#### **IMPORTANT NOTICE**

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

TI products are not authorized for use in safety-critical applications (such as life support) where a failure of the TI product would reasonably be expected to cause severe personal injury or death, unless officers of the parties have executed an agreement specifically governing such use. Buyers represent that they have all necessary expertise in the safety and regulatory ramifications of their applications, and acknowledge and agree that they are solely responsible for all legal, regulatory and safety-related requirements concerning their products and any use of TI products in such safety-critical applications, notwithstanding any applications-related information or support that may be provided by TI. Further, Buyers must fully indemnify TI and its representatives against any damages arising out of the use of TI products in such safety-critical applications.

TI products are neither designed nor intended for use in military/aerospace applications or environments unless the TI products are specifically designated by TI as military-grade or "enhanced plastic." Only products designated by TI as military-grade meet military specifications. Buyers acknowledge and agree that any such use of TI products which TI has not designated as military-grade is solely at the Buyer's risk, and that they are solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI products are neither designed nor intended for use in automotive applications or environments unless the specific TI products are designated by TI as compliant with ISO/TS 16949 requirements. Buyers acknowledge and agree that, if they use any non-designated products in automotive applications, TI will not be responsible for any failure to meet such requirements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

Products		Applications	
Amplifiers	amplifier.ti.com	Audio	www.ti.com/audio
Data Converters	dataconverter.ti.com	Automotive	www.ti.com/automotive
DSP	dsp.ti.com	Broadband	www.ti.com/broadband
Interface	interface.ti.com	Digital Control	www.ti.com/digitalcontrol
Logic	logic.ti.com	Military	www.ti.com/military
Power Mgmt	power.ti.com	Optical Networking	www.ti.com/opticalnetwork
Microcontrollers	microcontroller.ti.com	Security	www.ti.com/security
RFID	www.ti-rfid.com	Telephony	www.ti.com/telephony
Low Power Wireless	www.ti.com/lpw	Video & Imaging	www.ti.com/video
		Wireless	www.ti.com/wireless

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2007, Texas Instruments Incorporated